

Hierarchical Bayesian Modelling for univariate geo-referenced spatial data

(BCG chap 5)

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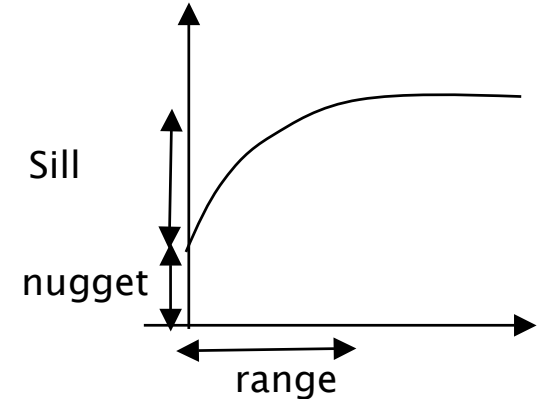


The Univariate stationary Gaussian isotropic case

Mean effect Spatial
Field

$$Y(s) = \mu(s) + v(s)$$

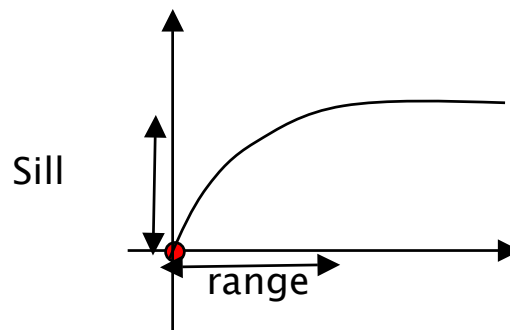
$$\mu(s) = X(s)\beta$$



Latent structured
phenomenon

$$Y(s) = \mu(s) + Z(s) + \varepsilon(s)$$

« Pure »
Error iid
noise

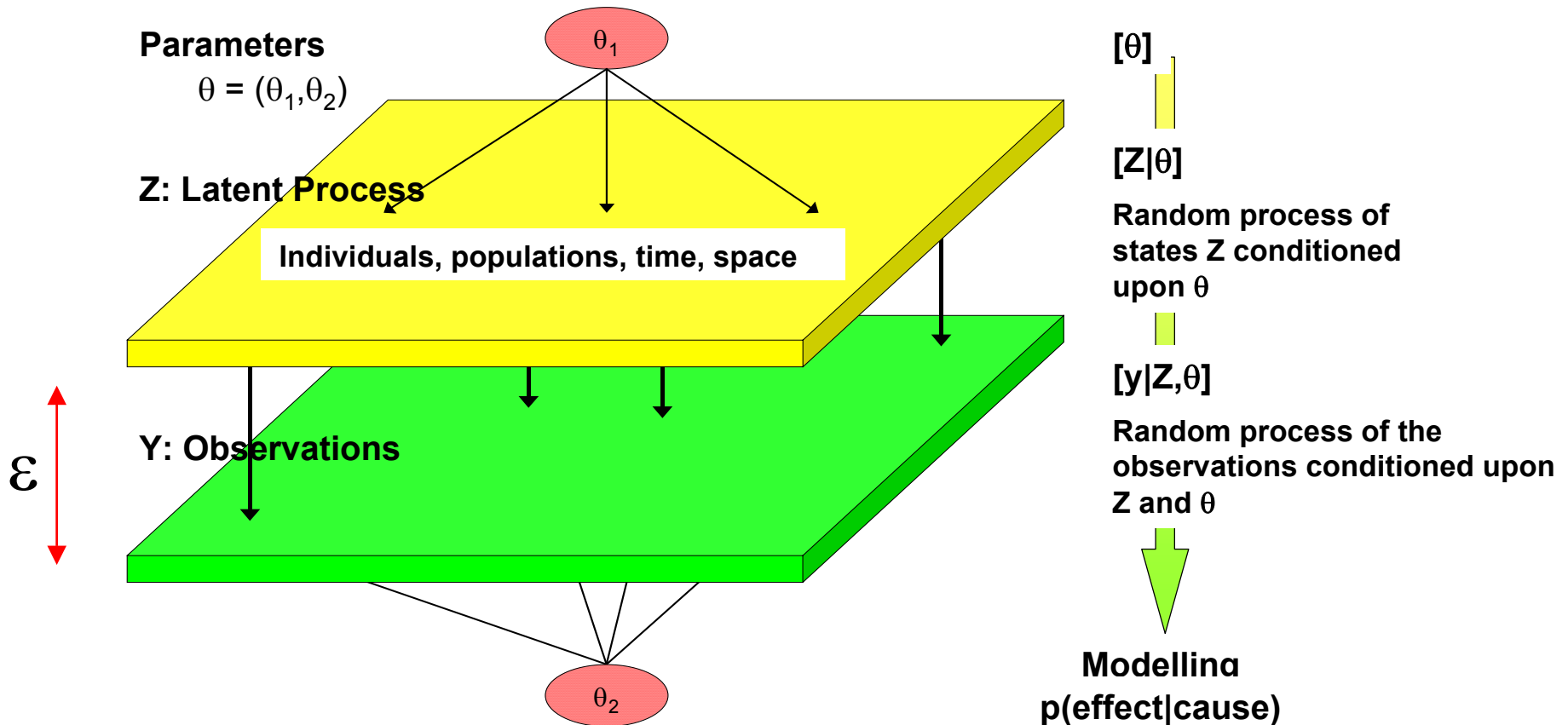


Given (μ, Z) the $Y(s)$'s are
cond't independent

Conditionnal (hierarchical) modelling strategy in HBM

- **Modelling : Capacity to accommodate complexity**

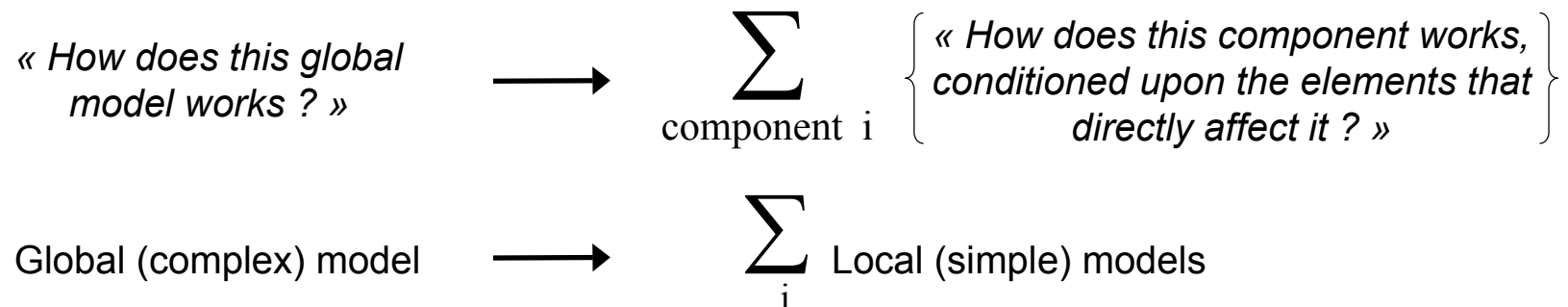
Parameters, latent states process and observation model can be modelled independently



Conditionnal (hierarchical) modelling strategy in HBM

- **Modelling : Capacity to accommodate complexity**

Each term $[Z|\theta]$ and $[y|Z,\theta]$ can be very complex if seen « globally », but is constructed from simple local interactions



- A natural framework to formalize knowledge
- Enhances dialog between modeler and practitioner

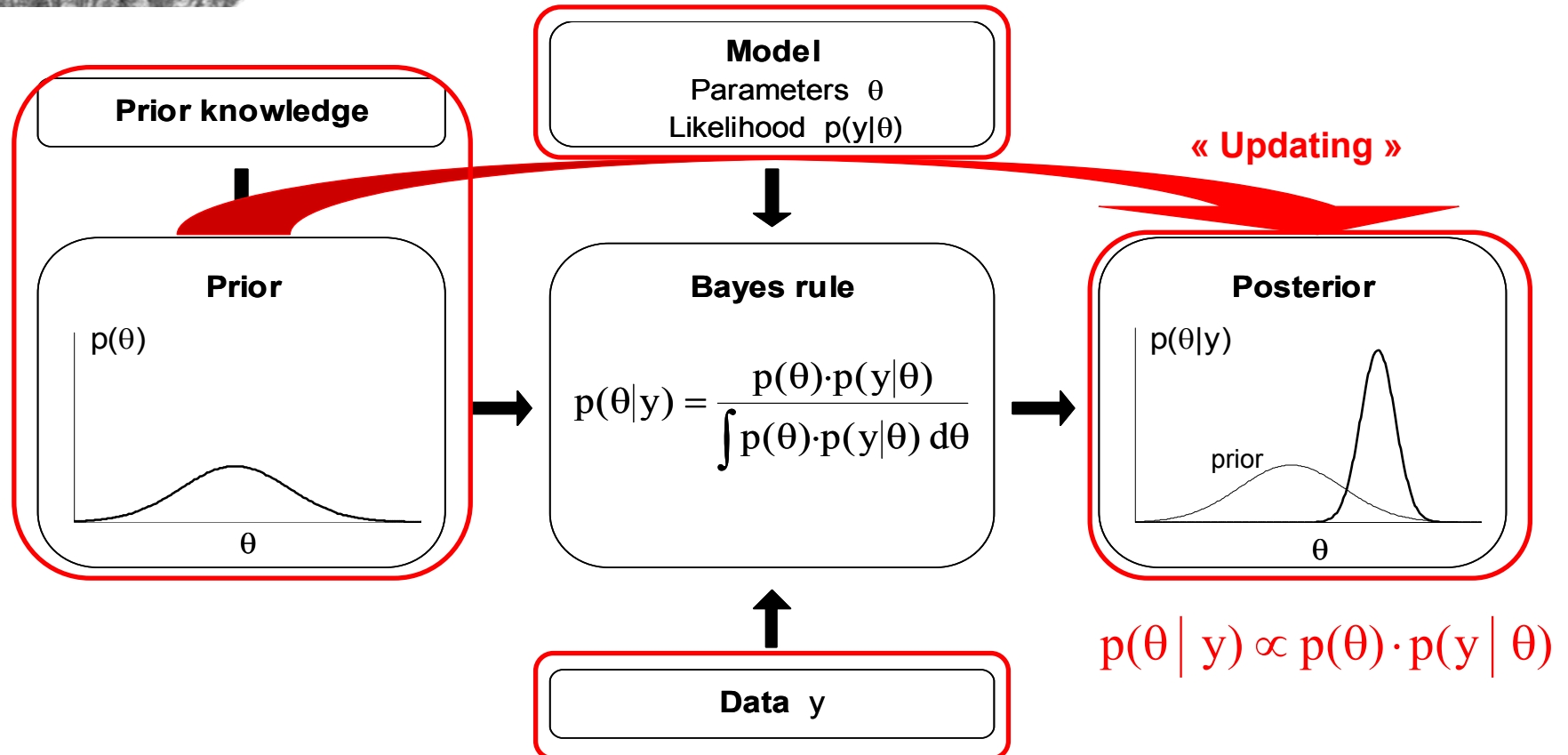
The Bayes rule (*Bayes theorem*)



Sir. Reverend Thomas Bayes (1702-1761)

Source : Brooks, S.P., 2003. *Bayesian computation : a statistical revolution*. *Phil. Trans. R. Soc. Lond. A* – 361: 2681-2697.

« Information processor »



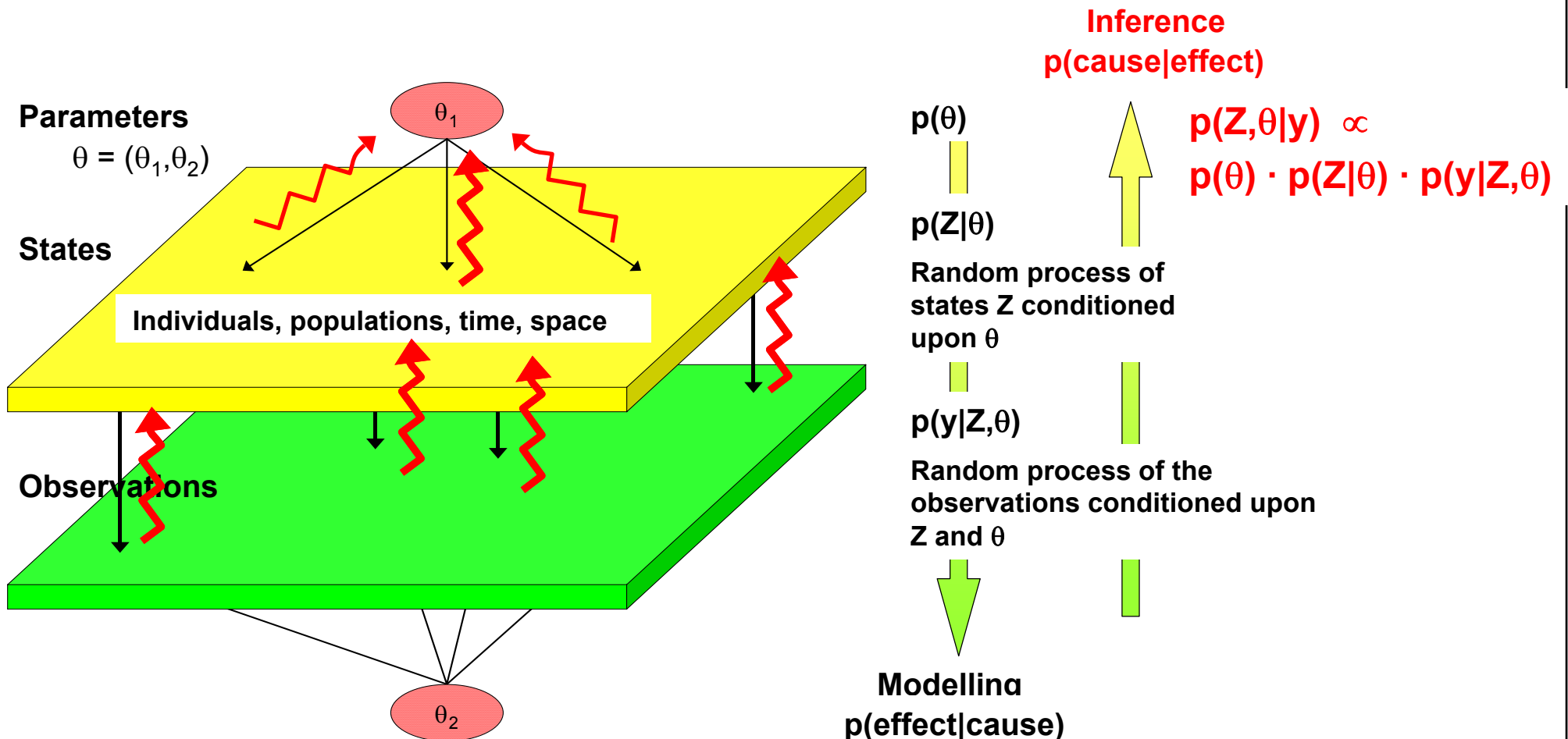
Conditionnal (hierarchical) modelling strategy in HBM

Take advantage of conditional independence

- **Inferences**

The joint posterior pdf splits into 3 components

⇒ Easy to switch from “Modelling” to “Inferences”



MCMC and bayesian inference go along well



- 1) Draw N replicates from $[\theta|y]$
- 2) use θ sample to get « empirical » estimates : mean, variance, percentiles from θ .

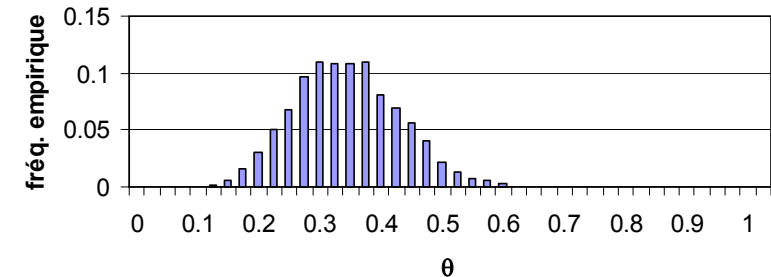
Unknown pdf
 $[\theta|y]$



sample from $[\theta|y]$:
 $(\theta^{(1)}, \theta^{(2)}, \dots, \theta^{(N)})$



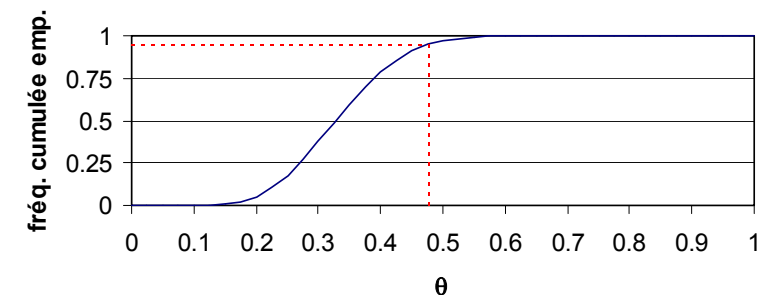
Histogramme de fréq. empirique de l'échantillon



$$\text{Moyenne: } \bar{\theta} = \frac{1}{N} \sum_{i=1}^N \theta^{(i)}$$

$$\text{Variance: } \frac{1}{N} \sum_{i=1}^N (\theta^{(i)} - \bar{\theta})^2$$

Calcul des percentiles de $[\theta|y]$



MCMC without tears : WinBUGS

Bayesian inference

Prior (known)
upon θ

Model likelihood
(known)

Posterior of θ

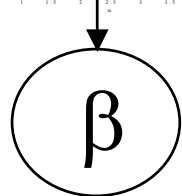
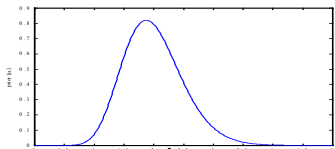
$$[\theta, Z | y] = \frac{[\theta][Z | \theta][y | \theta, Z]}{\iint_{\Theta, Z} [\theta, Z][y | \theta, Z] d\theta dZ}$$

Do not depend from θ and
often untractable
analytically. Can be
considered as a constant

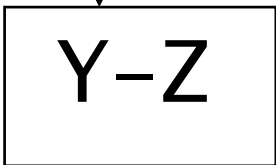
$$[\theta | y] = k \cdot [\theta][y | \theta] \longrightarrow$$

MCMC can help by
providing « samples »
from $[\theta | y]$

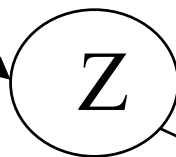
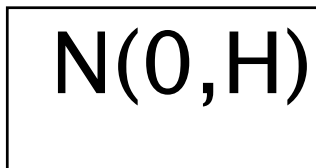
Take advantage of conjugacy for bayesian Inference



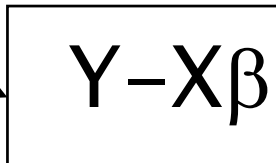
$$\beta | y, Z, \tau \sim N\left((X'X)^{-1} X'(Y-Z), \left(\frac{X'X}{(\tau)^2} \right)^{-1} \right)$$



$$Z | y, \beta, H, \tau \sim N\left(\left(H + \frac{I}{(\tau)^2} \right)^{-1} \left(\frac{Y - X\beta}{(\tau)^2} \right), \left(H + \frac{I}{(\tau)^2} \right)^{-1} \right)$$

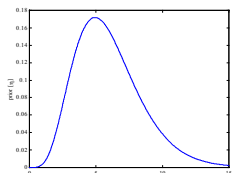


$H(\phi, \kappa, \sigma)$: cov matrix for Z
 τ : nugget variance

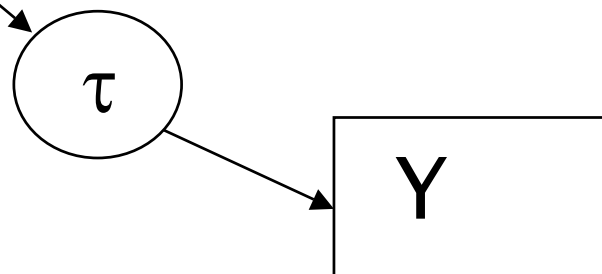


Take advantage of conjugacy for bayesian Inference (cont'd)

$H(\phi, \kappa, \sigma)$: cov matrix for Z
 τ : nugget variance



Prior Gamma



$$\frac{1}{(\tau)^2} | y, Z, \beta \sim \text{Gamma} (\bullet, \bullet)$$

$$\frac{1}{(\sigma)^2} | Z, \beta, C(\phi, \kappa) \sim \text{Gamma} (\bullet, \bullet)$$

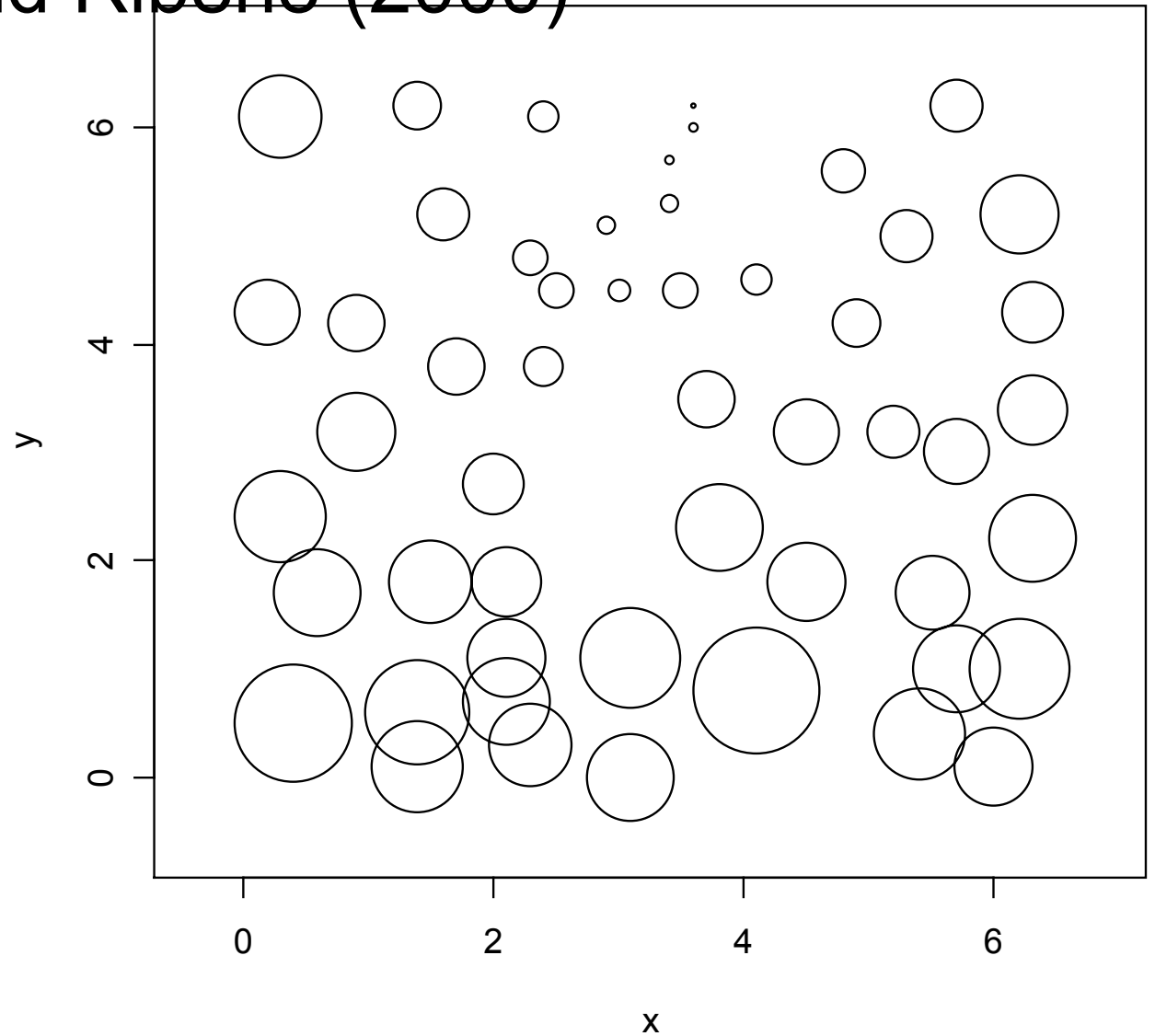
Can't take advantage of conjugacy for $\phi, \kappa!!!$

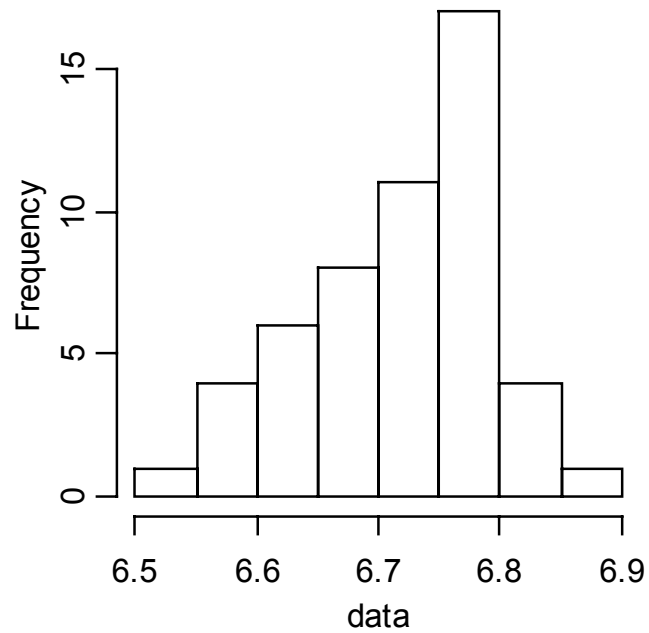
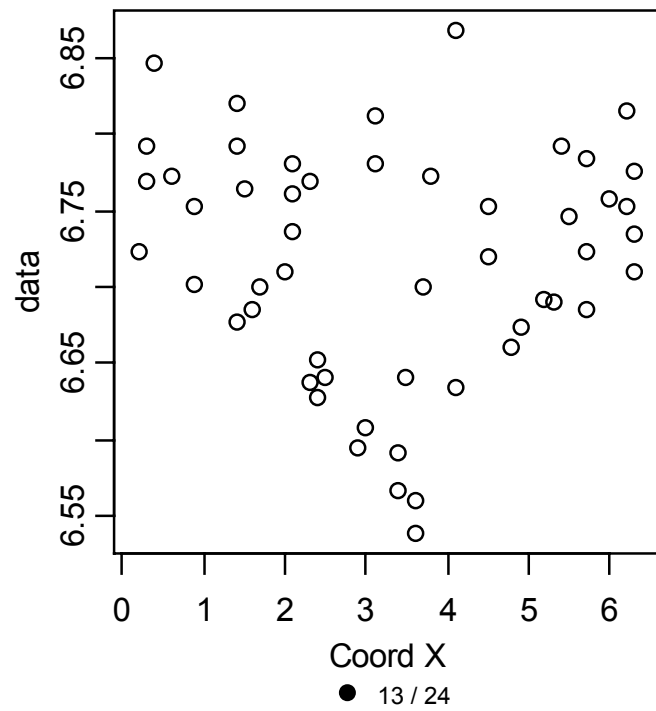
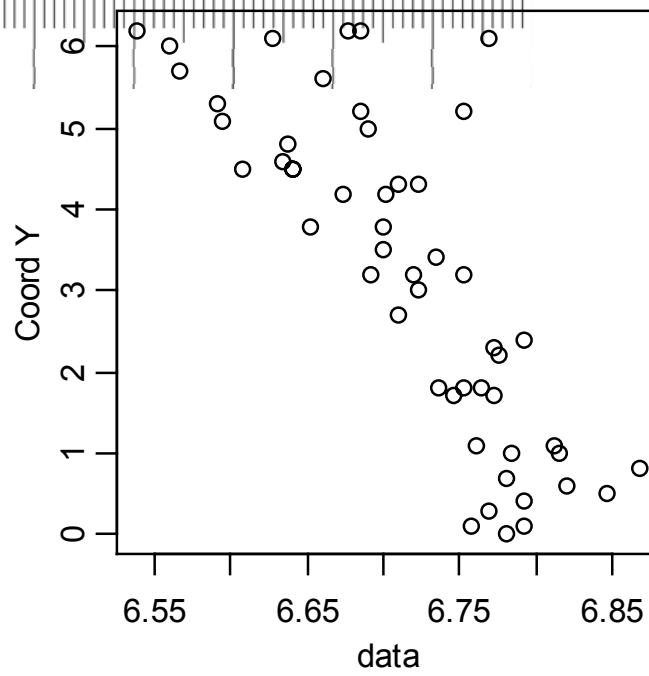
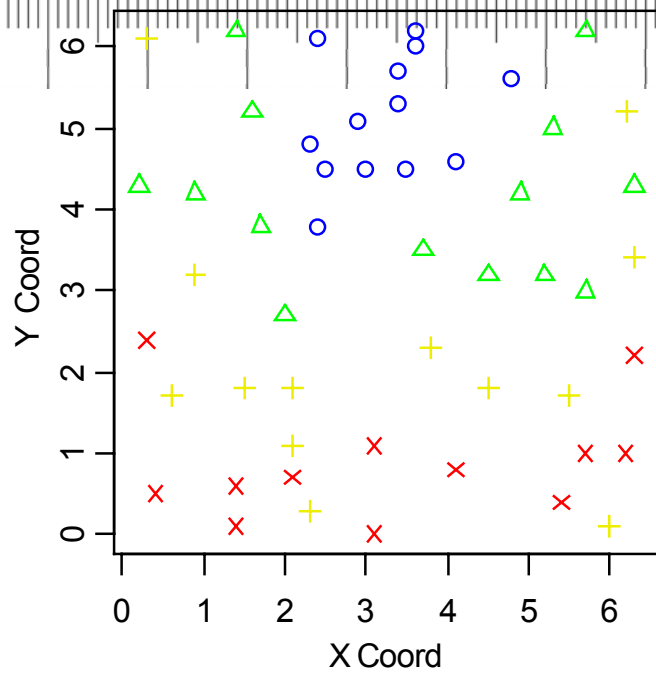
$H(\phi, \kappa, \sigma)$: cov matrix for Z

$$H(\phi, \kappa, \sigma) = \sigma^2 C(\phi, \kappa)$$

$$[\phi, \kappa | \sigma, Z] = k \times [\phi, \kappa] \times \frac{\exp(-Z' C^{-1}(\phi, \kappa) Z / 2(\sigma)^2)}{\sqrt{\det(C(\phi, \kappa))}}$$

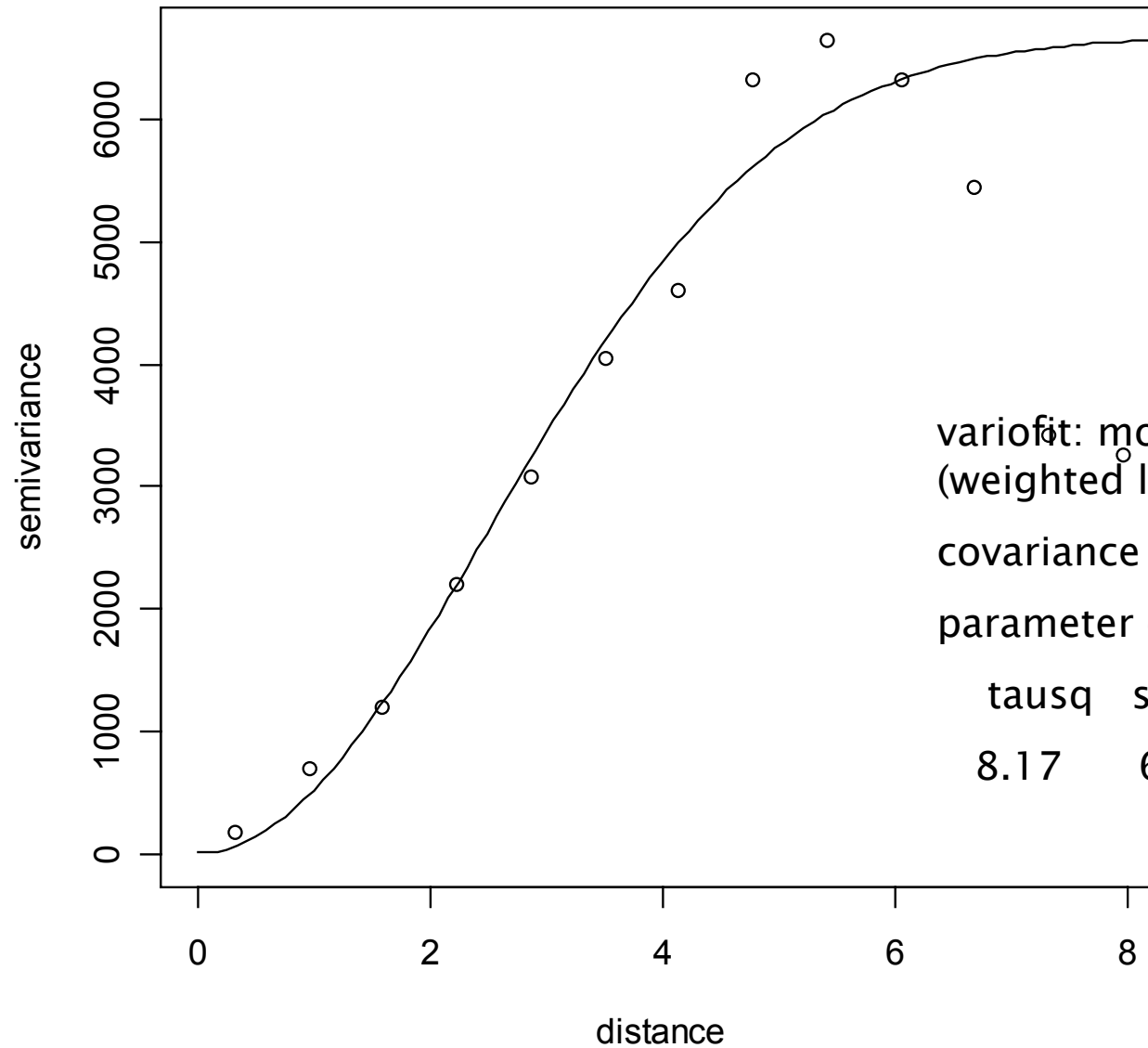
Elevation data From Diggle and Riberio (2000)





Data
description

Traditional Inference



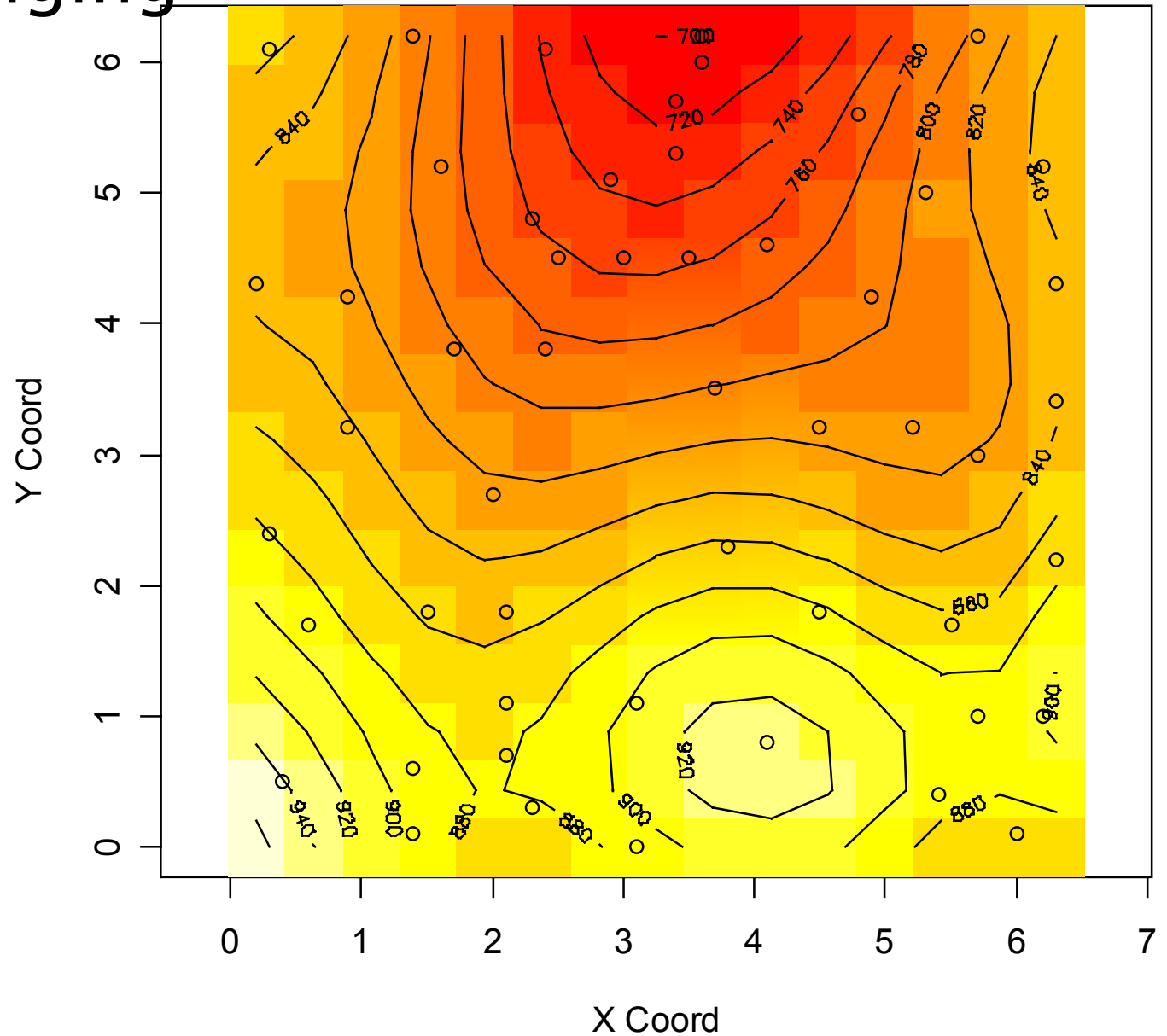
variofit: model parameters estimated by WLS
(weighted least squares):

covariance model is: powered.exponential

parameter estimates:

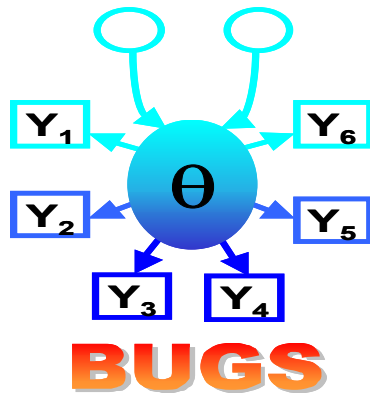
tausq	sigmasq	phi	kappa
8.17	6665	3.5	2

Frequentist kriging



Using GeoR



Friendly softwares, e.g. WinBUGS®



“Bayesian inference Using Gibbs Sampler”

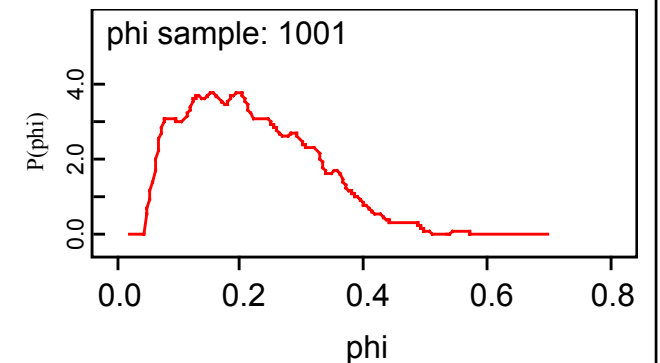
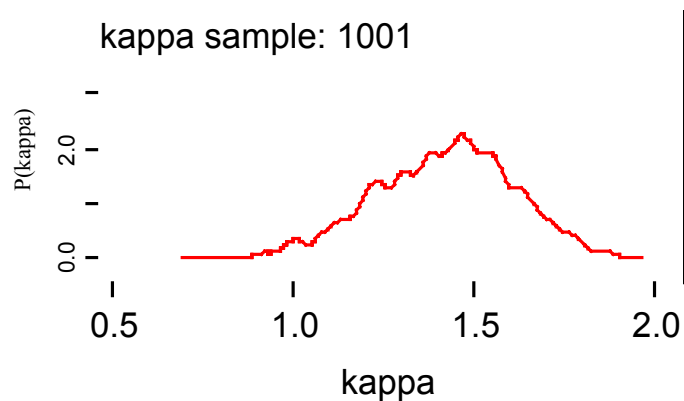
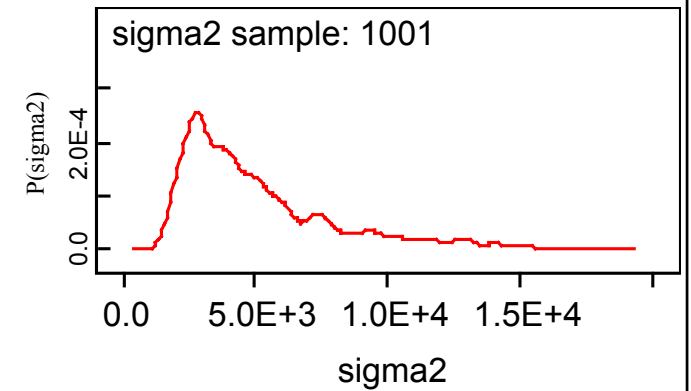
Medical Research Council, Biostatistics Unit, Cambridge, UK

Imperial College, London, UK

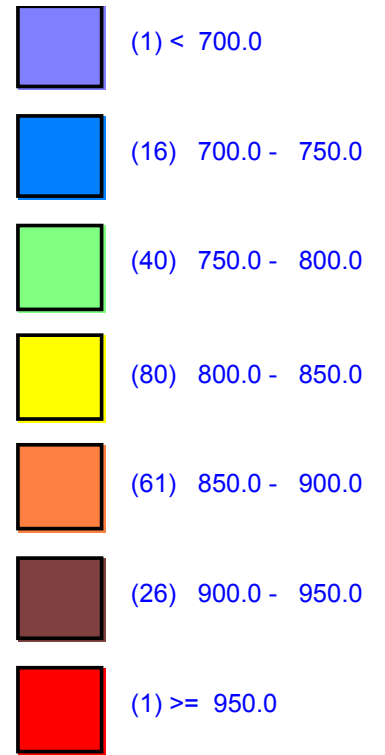
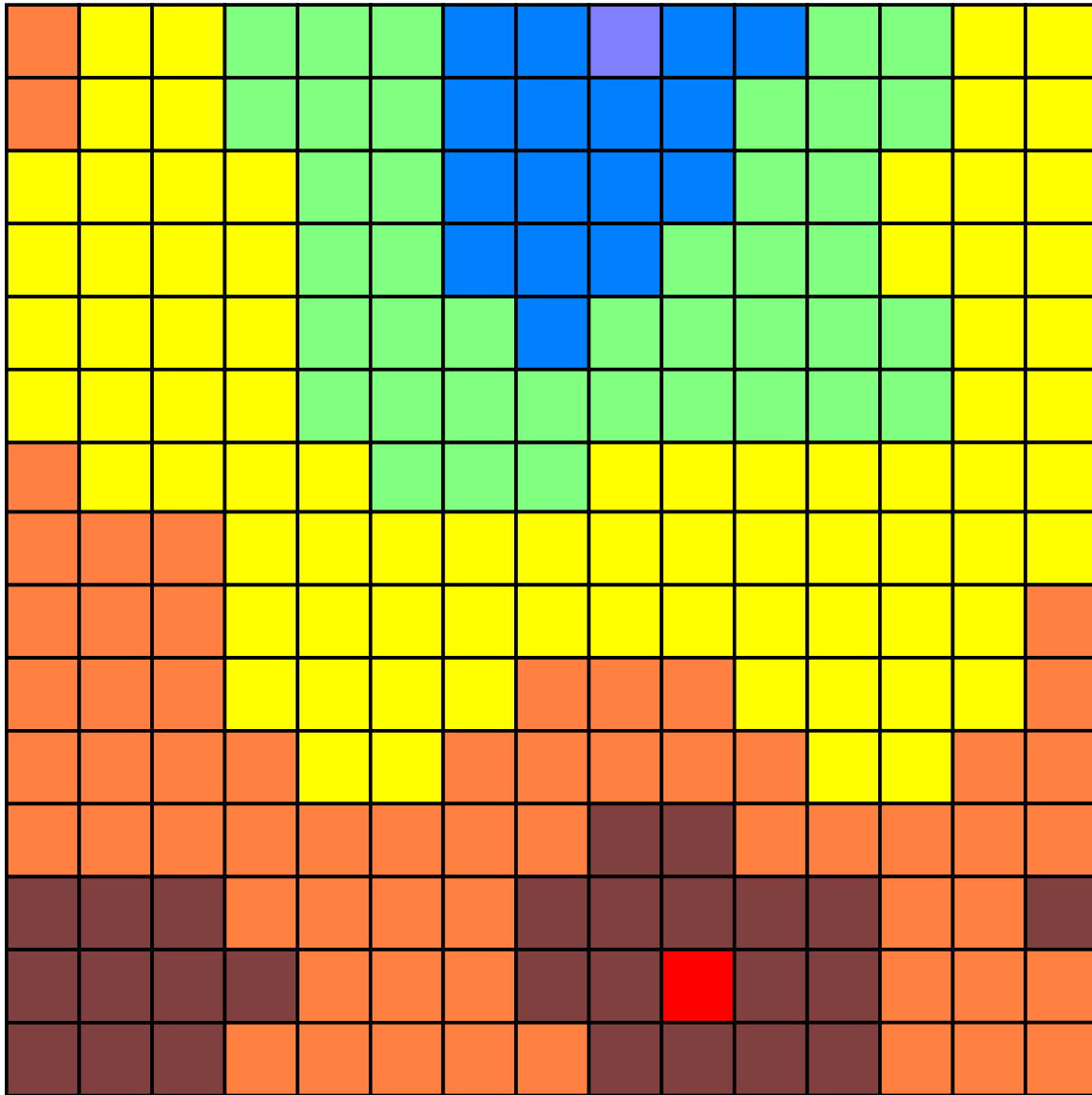
- Bayesian statistical modeling
- Very popular
- Sampling based methods using Gibbs sampling (eventually hybrid)
- Models can be described graphically
- Freeware, available at : www.mrc-bsu.cam.ac.uk/bugs/
- Extensions :
 - Spatial models : GeoBUGS®
 - Convergence : Coda®, Boa® ( packages)
- Coupling with 

Bayesian Kriging

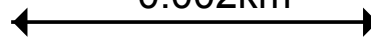
	Mean	Var
kappa	1.421	0.1934
phi	0.2178	0.102
sigma2	5145.0	3003.0



(samples)means for height.pred



0.002km

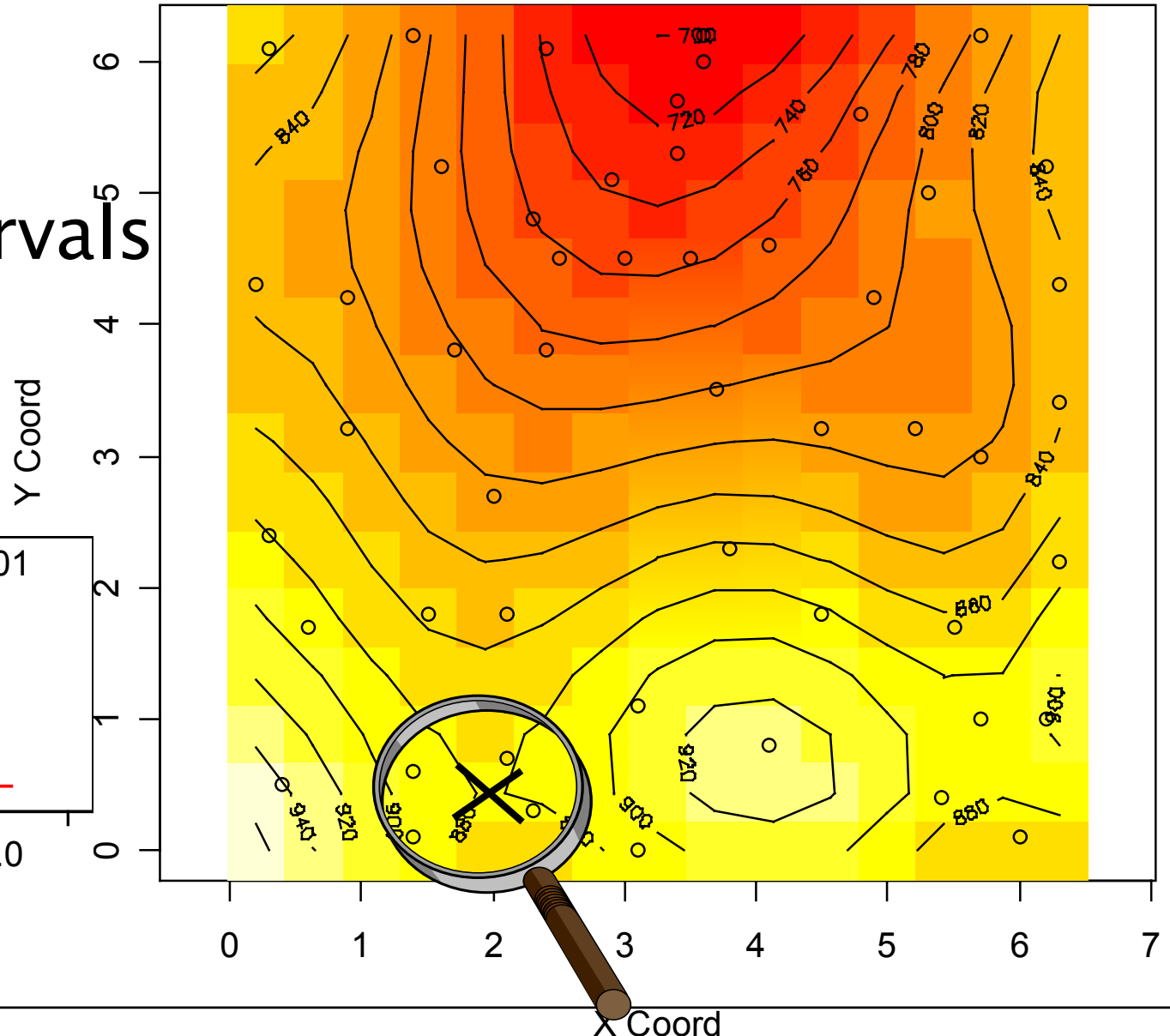
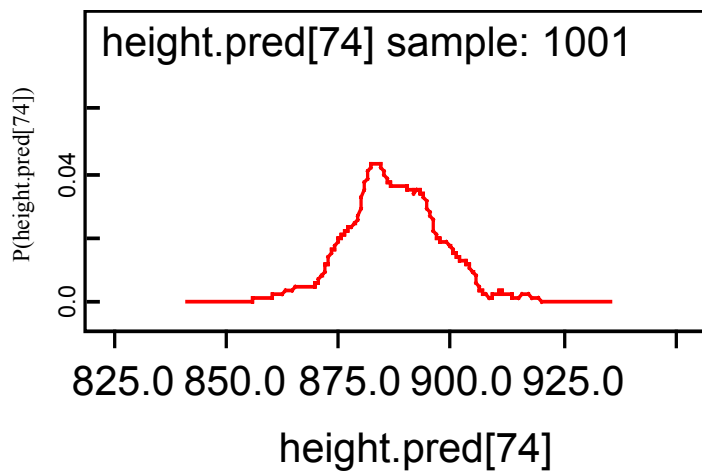


Bayes est = $887.2 \pm 2 * 10.8$
Freq. est = $878.7 \pm 2 * 3.2$

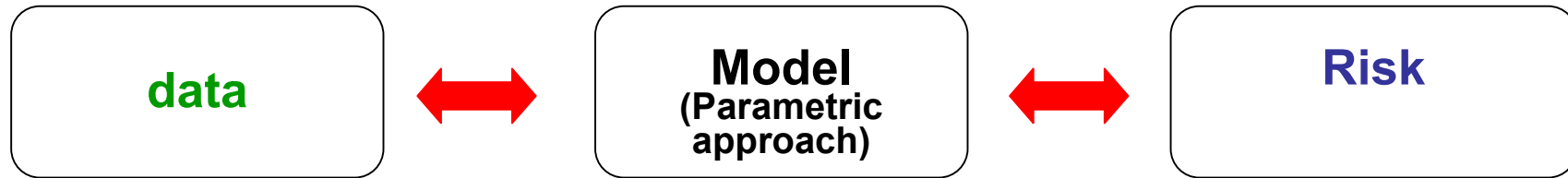
$$[y_{new}|y] = \int_{\Theta} [y_{new}|y, \theta] [\theta|y] d\theta$$

$$\theta = (\beta, \kappa, \phi, \sigma)$$

Confidence intervals
widen !



Probabilizing uncertainty : to bet or not to bet



Measurement error

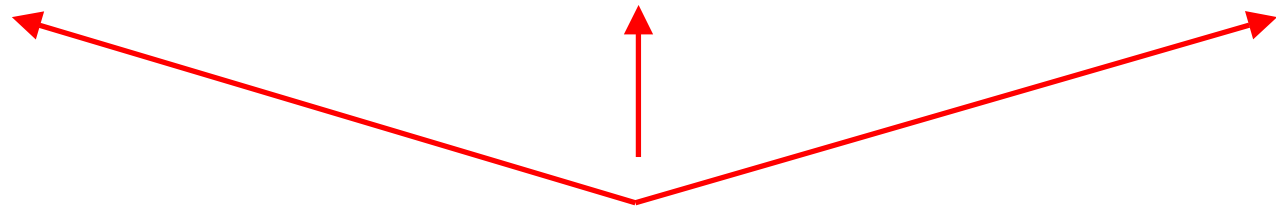
sampling

Incomplete observation

Randomness (**by essence**)
Stochastic models

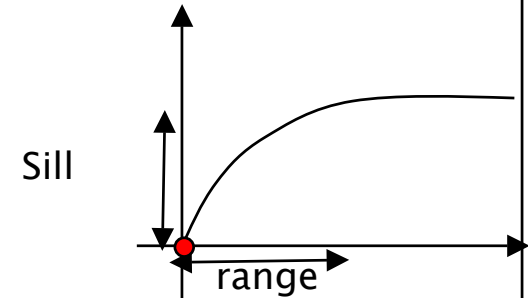
Parameter estimation (**by ignorance**)
Model robustness

Management under uncertainty



The Univariate stationary Non-Gaussian isotropic case

$$\mu(s) = X(s)\beta \quad \leftarrow \text{Mean effect}$$



$$Z(s) \sim N(0, H(\phi, \kappa, \sigma)) \quad \leftarrow$$

Latent structured phenomenon

Exemples for *Process model* : Gauss+Matern, powered exp...

$$Y(s) | Z, \theta, X \sim \ell(Z, \theta, X)$$

~~$$Y(s) = \mu(s) + Z(s) + \varepsilon(s)$$~~

Exemples for *data model* : Bernoulli, Poisson...

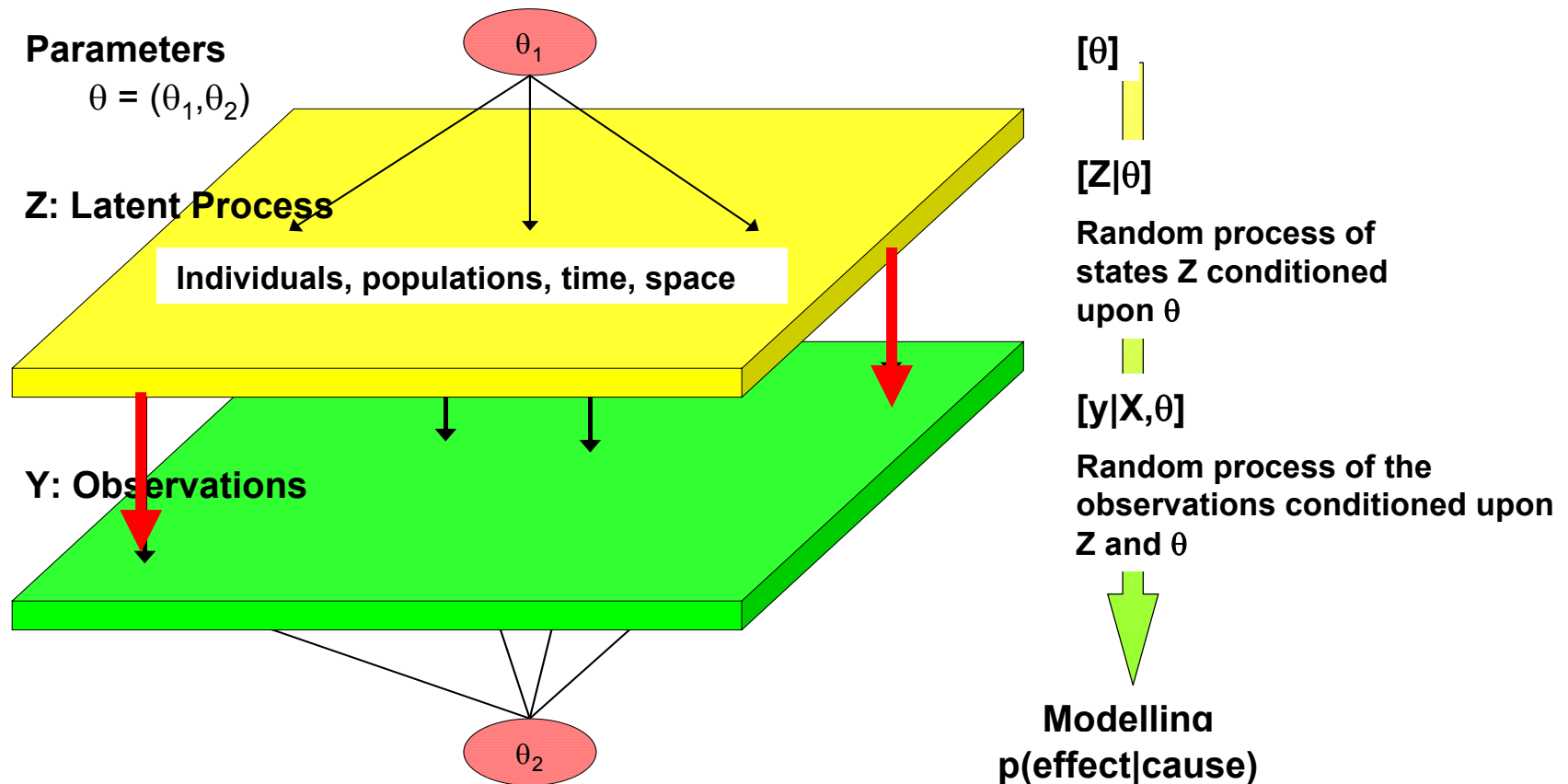
$$Y(s) | Z, \theta, X \sim dBern(p(s)); \log\left(\frac{p(s)}{1-p(s)}\right) = X\beta + Z$$

Given (μ, Z) the $Y(s)$'s are cond't independent

Conditionnal (hierarchical) modelling strategy in HBM

- **Modelling : Capacity to accommodate complexity**

Parameters, states process and observations process can be modelled independently





What 's next in chapter 5?

How to describe non-stationarity (5.3)

Play it again with areal data (lattice)...



THANKS!