# **COUNTING CLOSED GEODESICS UNDER INTERSECTION CONSTRAINTS**

### **NEGATIVELY CURVED SURFACES**

Let  $\Sigma$  be a closed (i.e. compact and without boundary) negatively curved Riemannian surface.



Topologically,  $\Sigma$  consists in a surface of genus g (meaning that it has g holes) where  $g \ge 2$ .



Typical examples are *hyperbolic surfaces*  $\Gamma \setminus \mathbb{H}$  where  $\mathbb{H}$  is the Poincaré halfplane and  $\Gamma$  is a discrete subgroup of  $PSL(2,\mathbb{R})$ ; in this case the curvature is constant and equal to -1.

### **CLOSED GEODESICS**

On a Riemannian surface, there are remarkable curves called geodesics which (locally) minimize lengths.

**Example.** On the sphere  $\mathbb{S}^2 \subset \mathbb{R}^3$ , the geodesics are exactly the great circles; in particular every geodesic is periodic.



The negativeness of the curvature implies that the geodesic flow is *chaotic* (i.e. very sensitive to initial conditions).



However, in every nontrivial class c of deformation of closed curves  $\mathbb{S}^1 \to \Sigma$ , there is exactly one closed geodesic (i.e. a periodic geodesic trajectory)  $\gamma_{c}$ , which minimizes the length in the class c.



## YANN CHAUBET

### **COUNTING PRIMITIVE GEODESICS**

We denote by  $\mathcal{P}$  the set of *primitive* closed geodesics (i.e. closed geodesics which are not a multiple of a shorter one). A famous result of Margulis [Mar69] reads

$$\sharp \{ \gamma \in \mathcal{P} : \ell(\gamma) \leqslant L \} \sim \frac{\mathrm{e}^{hL}}{hL}$$

as  $L \to \infty$ , where  $\ell(\gamma)$  denotes the *length* of the closed geodesic  $\gamma$  and h > 0 is the *topological entropy* of the geodesic flow (*h* measures the chaos; if  $\Sigma$  is hyperbolic then h = 1).

Note the analogy with the prime number theorem which reads  $\pi(x) \sim x/\log x$  as  $x \to \infty$  where  $\pi(x)$ is the number of primes which are smaller than *x*.

### IMPOSING CONSTRAINTS

A natural question to investigate is whether we can understand the asymptotic growth of the number of geodesics that satisfy a certain (geometric or topological) constraint.

We will be interested in the following features:

- self–intersection numbers;
- homology classes;
- geometric intersection numbers.

### SELF-INTERSECTION NUMBERS

For  $\gamma \in \mathcal{P}$  we denote by  $\iota(\gamma, \gamma)$  its self-intersection number.



Mirzakhani [Mir08, Mir16] showed that, provided  $\Sigma$  is a hyperbolic, we have for any  $k \in \mathbb{Z}_{\geq 0}$ ,

 $\sharp \{ \gamma \in \mathcal{P} : \ell(\gamma) \leqslant L, \ \iota(\gamma, \gamma) = k \} \sim c_k L^{6g-6}$ 

as  $L \to \infty$ , for some  $c_k > 0$  independent of L.

Each closed geodesic  $\gamma$  gives rise to a *homology class*  $[\gamma] \in H_1(\Sigma, \mathbb{Z}) \simeq \mathbb{Z}^{2g}.$ 

This homology class is determined by the *al*gebraic intersection numbers of  $\gamma$  with a basis  $(a_1, b_1, \ldots, a_g, b_g)$  of the first homology group.

Lalley [Lal88] and Pollicott [Pol91] showed that for any  $\xi \in H_1(\Sigma, \mathbb{Z})$ , we have

Let  $\gamma_{\star}$  be a simple and non-separating closed geodesic.

We denote by  $\iota(\gamma, \gamma_{\star})$  the geometric intersection number between  $\gamma$  and  $\gamma_{\star}$ .



for every  $k \ge 0$ . In fact,  $h_{\star}$  is the entropy of the surface with boundary  $\Sigma_{\star}$  obtained by cutting  $\Sigma$  along  $\gamma_{\star}$ .



### HOMOLOGY CLASSES





$$\sharp\{\gamma \in \mathcal{P} : \ell(\gamma) \leqslant L, \ [\gamma] = \xi\} \sim c \frac{\mathrm{e}^{hL}}{L^{\mathrm{g}}}$$

as  $L \to \infty$ , where c > 0 is independent of  $\xi$ .

### **GEOMETRIC INTERSECTION NUMBERS**



Then one can show [Cha21] that there are  $c_{\star} > 0$ and  $h_{\star} \in [0, h]$  such that, as  $L \to \infty$ , we have

$$\in \mathcal{P}: \ell(\gamma) \leqslant L, \ \iota(\gamma, \gamma_{\star}) = k \} \sim \frac{(c_{\star}L)^k}{k!} \frac{\mathrm{e}^{h_{\star}L}}{h_{\star}L}$$

The proof uses tools from microlocal analysis to study the transfer operator  $f \mapsto f \circ S$  associated to the dynamical scattering map S.



Then [Cha21] for every  $\mathbf{n} = (n_1, \dots n_r)$ , there is  $c_{\mathbf{n}} > 0$ ,  $d_{\mathbf{n}} \in \mathbb{Z}_{\geqslant 0}$  and  $h_{\mathbf{n}} \in \left]0,h\right[$  such that, as  $L \to \infty$ ,



where  $\mathbf{i}(\gamma, \vec{\gamma}_{\star}) = (\iota(\gamma, \gamma_{\star,1}), \ldots, \iota(\gamma, \gamma_{\star,r}))$  — here we need **n** to be *admissible*, that is  $\mathbf{n} = \mathbf{i}(\gamma, \vec{\gamma}_{\star})$  for some  $\gamma$ .

The number  $h_n$  is the maximum of the entropies of the surfaces  $\Sigma_i$  that are encountered by any  $\gamma$ satisfying  $\mathbf{i}(\gamma, \vec{\gamma}_{\star}) = \mathbf{n}$ , while  $d_{\mathbf{n}}$  is the number of times such a  $\gamma$  travels through a surface of maximal entropy.

[Cha21]	Yann Cha
	arXiv:2103
[Lal88]	Steven P. 1988.
[Mar69]	Gregorii A negative o
[Mir08]	Maryam Surfaces.
[Mir16]	Maryam I preprint an
[Pol91]	Mark Pol



### MULTIPLE CURVES

We fix a family of pairwise disjoint simple closed geodesics  $\gamma_{\star,1}, \ldots, \gamma_{\star,r}$ . Those curves separate  $\Sigma$ into sub-surfaces  $\Sigma_1, \ldots, \Sigma_q$ .

 $\sharp \{ \gamma \in \mathcal{P} : \ell(\gamma) \leqslant L, \ \mathbf{i}(\gamma, \vec{\gamma}_{\star}) = \mathbf{n} \} \sim c_{\mathbf{n}} L^{d_{\mathbf{n}}} \mathrm{e}^{h_{\mathbf{n}} L}$ 

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