

Erratum: Deconvolution with unknown noise distribution is possible for multivariate signals

Luc Lehéricy, Sylvain Le Corff, Élisabeth Gassiat

▶ To cite this version:

Luc Lehéricy, Sylvain Le Corff, Élisabeth Gassiat. Erratum: Deconvolution with unknown noise distribution is possible for multivariate signals. 2025. hal-04928354

HAL Id: hal-04928354 https://hal.science/hal-04928354v1

Preprint submitted on 4 Feb 2025

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Erratum: Deconvolution with unknown noise distribution is possible for multivariate signals

Élisabeth Gassiat*, Sylvain Le Corff[†], and Luc Lehéricy[‡]

*Université Paris-Saclay, CNRS, Laboratoire de mathématiques d'Orsay, 91405, Orsay, France.

[†]LPSM, Sorbonne Université, UMR CNRS 8001, Paris, France.

The erratum offers another way to obtain an inequality similar to that given in Proposition A.2 in [Gassiat et al., 2022], since an error has been found in its proof.

In this note we use the setting and the notations introduced in [Gassiat et al., 2022].

The proof of Proposition A.2 uses a study of the linear part of M_{\star} with a linear transformation A with properties described in Lemma I.1 of Appendix I in the supplementary material of [Gassiat et al., 2022]. In particular, this Lemma entails that A restricted to the polynomials of degree at most m is injective (lower triangular with diagonal coefficients equal to -1), with explicit inverse, thus allowing the control of its lowest singular value. The problem lies in point iv) of this Lemma: A is actually not injective. Its diagonal entries with coordinates $((i_1,0),(i_1,0))$ and $((0,i_2),(0,i_2))$ for $i_1,i_2\geqslant 1$ are zero, and its entry with coordinate ((0,0),(0,0)) is +1.

Consider now the following assumption. Let $\delta \in (0, 1)$.

 $\mathbf{H}(\delta)$: There exists $\nu_0 > 0$ such that for all $\nu \in (0, \nu_0]$, there exists $c(\nu, \delta) > 0$ such that for all R^\star such that $\Phi_{R^\star} \in \mathcal{H} \cap \Upsilon_{\kappa, S}$,

$$\forall \phi \in \mathcal{H} \cap \Upsilon_{\kappa,S} \quad \text{s.t.} \quad \phi \neq \Phi_{R^*}, \quad \frac{\left\| \frac{\phi}{\Phi_{R^*}} - \frac{\phi^{(1)}}{\Phi_{R^*}^{(1)}} - \frac{\phi^{(2)}}{\Phi_{R^*}^{(2)}} + 1 \right\|_{2,\nu}}{\max \left(\left\| \frac{\phi^{(1)}}{\Phi_{R^*}^{(1)}} - 1 \right\|_{2,\nu}, \left\| \frac{\phi^{(2)}}{\Phi_{R^*}^{(2)}} - 1 \right\|_{2,\nu} \right)^{1+\delta}} \geqslant c(\nu, \delta). \quad (1)$$

Proposition 1. Assume $\mathbf{H}(\delta)$ holds. There exists $\overline{\nu} > 0$ depending only on S and ρ such that for all $\nu \leqslant \overline{\nu}$, there exists a constant $\widetilde{c} > 0$ depending only on c_{ν} and $c(\nu, \delta)$ such that for all R^* such that $\Phi_{R^*} \in \mathcal{H} \cap \Upsilon_{\kappa, S}$, all $Q^* \in \mathbf{Q}(\nu, c_{\nu}, c_{Q})$ for some $c_{Q} \in (0, \infty]$, for all $\phi \in \mathcal{H} \cap \Upsilon_{\kappa, S}$, as soon as

$$\left\| \frac{\phi}{\Phi_{R^{\star}}} - \frac{\phi^{(1)}}{\Phi_{R^{\star}}^{(1)}} - \frac{\phi^{(2)}}{\Phi_{R^{\star}}^{(2)}} + 1 \right\|_{2,\nu} \leqslant \min \left\{ \left(c(\nu, \delta)^2 2^{-(1+\delta)} (2\nu)^{d(1+\delta)} \right)^{\frac{1}{1-\delta}}; 1 \right\},\tag{2}$$

[‡]Laboratoire J. A. Dieudonné, Université Côte d'Azur, CNRS, 06100, Nice, France.

it holds

$$M_{\star}(\phi;\nu) \geqslant \widetilde{c} \|\phi - \Phi_{R^{\star}}\|_{2,\nu}^{2(1+\delta)}. \tag{3}$$

In [Gassiat et al., 2022], \mathcal{H} is chosen as a closed subset of $\mathbf{L}^2(B^d_{\nu_{\rm est}})$ such that all elements of \mathcal{H} satisfy $\mathbf{H2}$. In the choice of \mathcal{H} we may require that $\mathbf{H}(\delta)$ holds, since this choice comes from the prior modeling that allows to fix $\mathbf{H2}$, see examples in Section 2 of [Gassiat et al., 2022]. If we add $\mathbf{H}(\delta)$ in the choice of \mathcal{H} , then Theorem 3.2 and Theorem 3.3 follow from the arguments developed in [Gassiat et al., 2022] with no modification.

Notice that the uniform consistency of the estimator (Section A.1 in [Gassiat et al., 2022]) holds without any change, that is without assuming $\mathbf{H}(\delta)$ which is only used to get rates.

Let us now prove Proposition 1. First, notice that for all $\nu > 0$, for all $\phi \in \Upsilon_{\rho,S}$, $|\phi(t)| \leqslant \sup_{u:\|u\| \leqslant \|t\|} \|\phi'(u)\| \|t\|$, where $\phi'(u)$ denotes the gradient of ϕ at u (recall that ϕ is multivariate analytic), so that it is possible to choose $\overline{\nu}$ depending only on S and ρ such that for all $\phi \in \Upsilon_{\rho,S}$, all $\nu \leqslant \overline{\nu}$, all $t \in B^d_{\nu}$, $|\phi(t)| \geqslant 1/2$. Let now R^* be such that $\Phi_{R^*} \in \mathcal{H} \cap \Upsilon_{\kappa,S}$, and let $Q^* \in \mathbf{Q}(\nu,c_{\nu},c_Q)$ for some $c_Q \in (0,\infty]$. Let ϕ be any function in $\mathcal{H} \cap \Upsilon_{\kappa,S}$ such that (2) holds. Denote

$$g_1 = \frac{\phi^{(1)}}{\Phi_{R^\star}^{(1)}} - 1, \qquad g_2 = \frac{\phi^{(2)}}{\Phi_{R^\star}^{(2)}} - 1 \quad \text{and} \quad G = \frac{\phi}{\Phi_{R^\star}} - 1 - g_1 - g_2 \,.$$

Then, M_{\star} rewrites

$$M_{\star}(\phi;\nu) = \|\Phi_{R^{\star}}\Phi_{R^{\star}}^{(1)}\Phi_{R^{\star}}^{(2)}(G - g_1g_2)\Phi_{Q^{\star}}^{(1)}\Phi_{Q^{\star}}^{(2)}\|_{2,\nu}^2, \tag{4}$$

and we get $M_{\star}(\phi; \nu) \geqslant \frac{c_{\nu}^4}{2^8} \|G - g_1 g_2\|_{2, \nu}^2$. Using $\mathbf{H}(\delta)$ and (2), we get

$$||g_1||_{2,\nu}||g_2||_{2,\nu} \leqslant \left(\frac{||G||_{2,\nu}}{c(\nu,\delta)}\right)^{2/(1+\delta)} \leqslant \frac{||G||_{2,\nu}}{2}(2\nu)^d$$

(recall $0 < \delta < 1$). We then get

$$M_{\star}(\phi;\nu) \geqslant \frac{c_{\nu}^{4}}{26} (\|G\|_{2,\nu} - \|g_{1}g_{2}\|_{2,\nu})^{2}$$

$$= \frac{c_{\nu}^{4}}{26} (\|G\|_{2,\nu} - (2\nu)^{-d} \|g_{1}\|_{2,\nu} \|g_{2}\|_{2,\nu})^{2}$$

$$\geqslant \frac{c_{\nu}^{4}}{28} \|G\|_{2,\nu}^{2}.$$

On the other hand,

$$\begin{split} \|\phi - \Phi_{R^*}\|_{2,\nu} &= \|G + g_1 + g_2\|_{2,\nu} \\ &\leq \|G\|_{2,\nu} + \|g_1\|_{2,\nu} + \|g_2\|_{2,\nu} \\ &\leq \|G\|_{2,\nu} + 2(c(\nu,\delta)^{-1}\|G\|_{2,\nu})^{1/(1+\delta)} \\ &\leq (1 + 2c(\nu,\delta)^{-1/(1+\delta)}) \|G\|_{2,\nu}^{1/(1+\delta)} \end{split}$$

since $||G||_{2,\nu} \le 1$. Hence, we may conclude

$$M_{\star}(\phi;\nu) \geqslant \frac{c_{\nu}^4}{2^8(1+2c(\nu,\delta)^{-1/(1+\delta)})^{2(1+\delta)}} \|\phi - \Phi_{R^{\star}}\|_{2,\nu}^{2(1+\delta)}.$$

Acknowledgement. The authors want to thank Thomas Lehéricy who pointed out the error.

REFERENCES REFERENCES

References

[Gassiat et al., 2022] Gassiat, E., Le Corff, S., and Lehéricy, L. (2022). Deconvolution with unknown noise distribution is possible for multivariate signals. *Ann. Statist.*, 50(1):303–323.