

Quadrilateral et Hexahedral Pseudo-conform Finite Elements

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What is the problem?

Loss of convergence for the RT, BDM, BDFM
when we use quadrilateral or hexahedral elements.

Standart model :

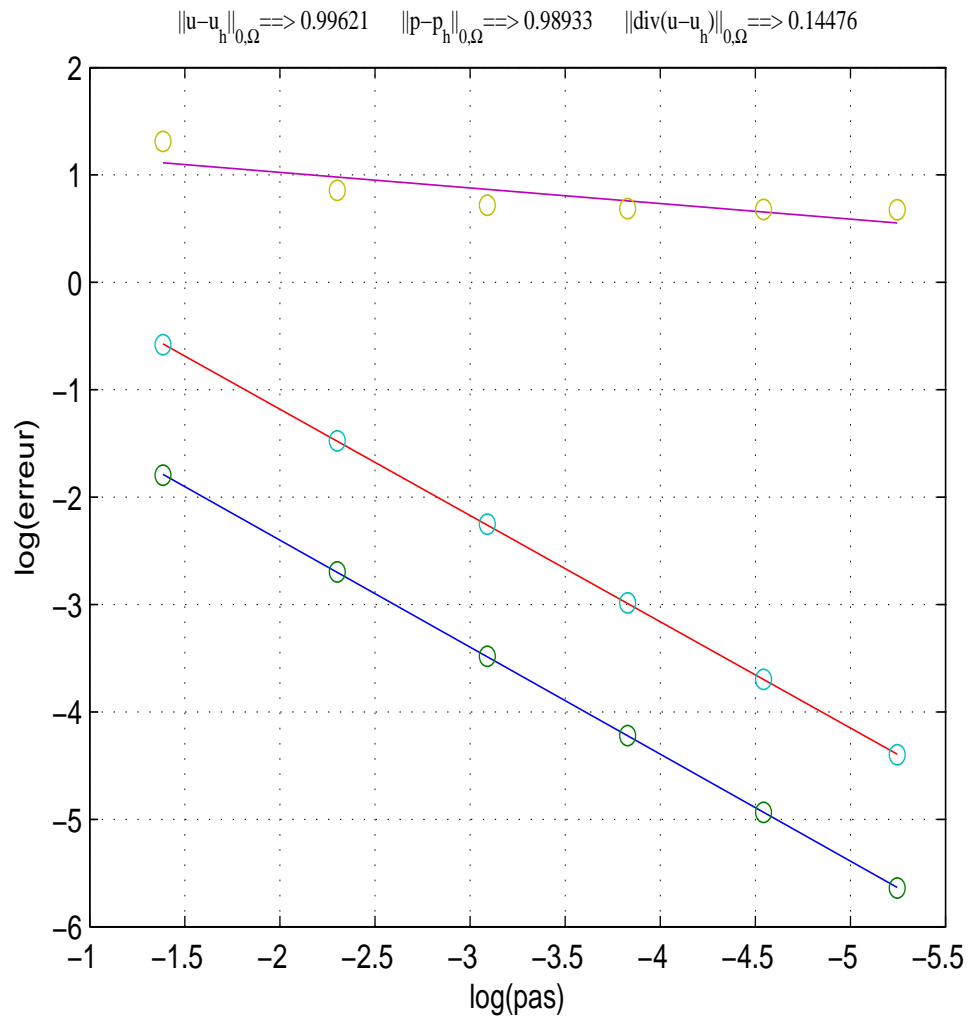
$$L_h = \left\{ \mathbf{v}_h \in H(\operatorname{div}, \Omega); \mathbf{v}_h|_K \in RT_0(K) \right\}, M_h = \left\{ q_h \in L^2(\Omega); q_h|_K \in P_0(K) \right\}$$

find $(\mathbf{u}_h, p_h) \in L_h \times M_h$ solution of

$$\begin{cases} \int_{\Omega} \operatorname{div} \mathbf{u}_h q_h dx + \int_{\Omega} f q_h dx = 0 & \forall q_h \in M_h \\ \int_{\Omega} A^{-1} \mathbf{u}_h \mathbf{v}_h dx - \int_{\Omega} \nabla p_h \mathbf{v}_h dx = 0 & \forall \mathbf{v}_h \in L_h \end{cases}$$

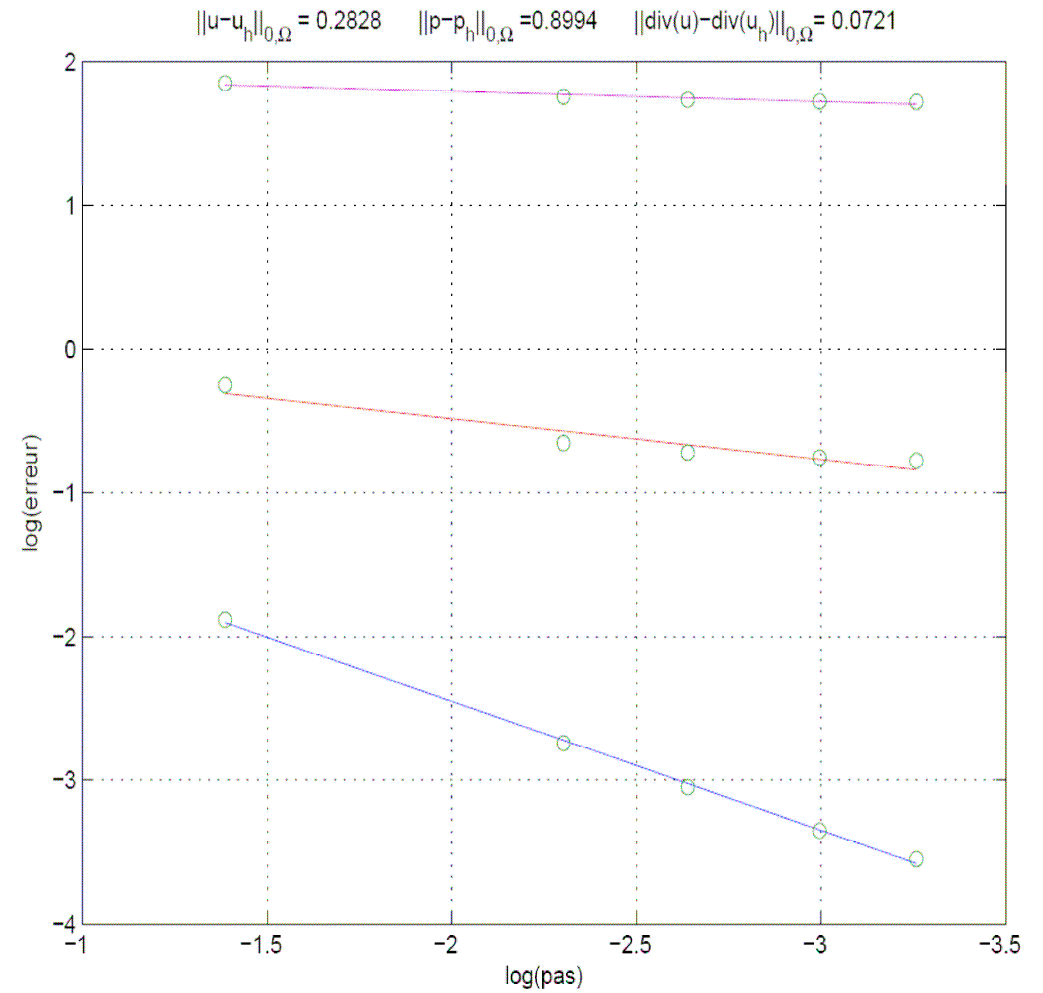
\mathbf{u}_h does not converge in $H(\operatorname{div})$ when the mesh is based on
quadrilateral or hexahedral elements.

2D



Loss of convergence on $\text{div}(\mathbf{u})$

3D

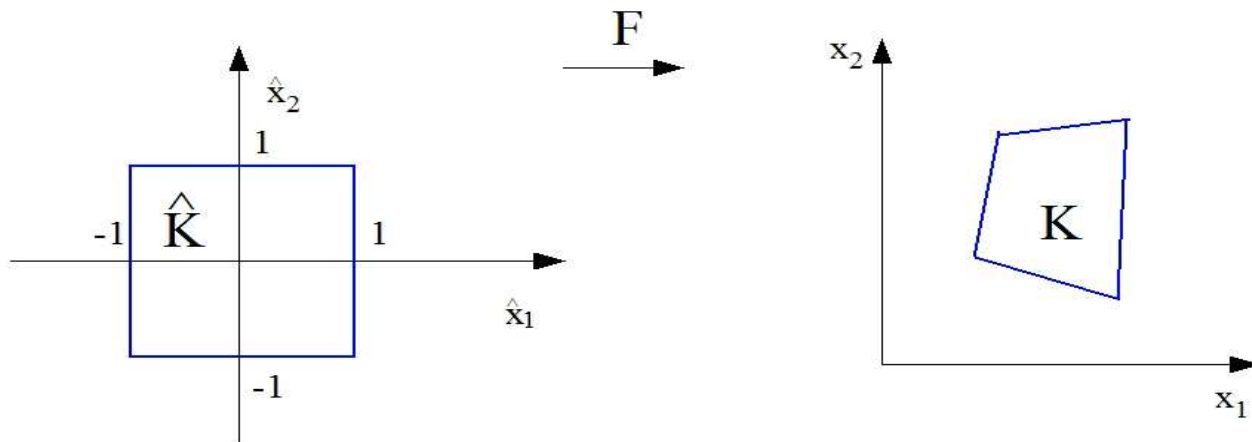


Loss of convergence on \mathbf{u} and $\text{div}(\mathbf{u})$

Where does the problem come from?

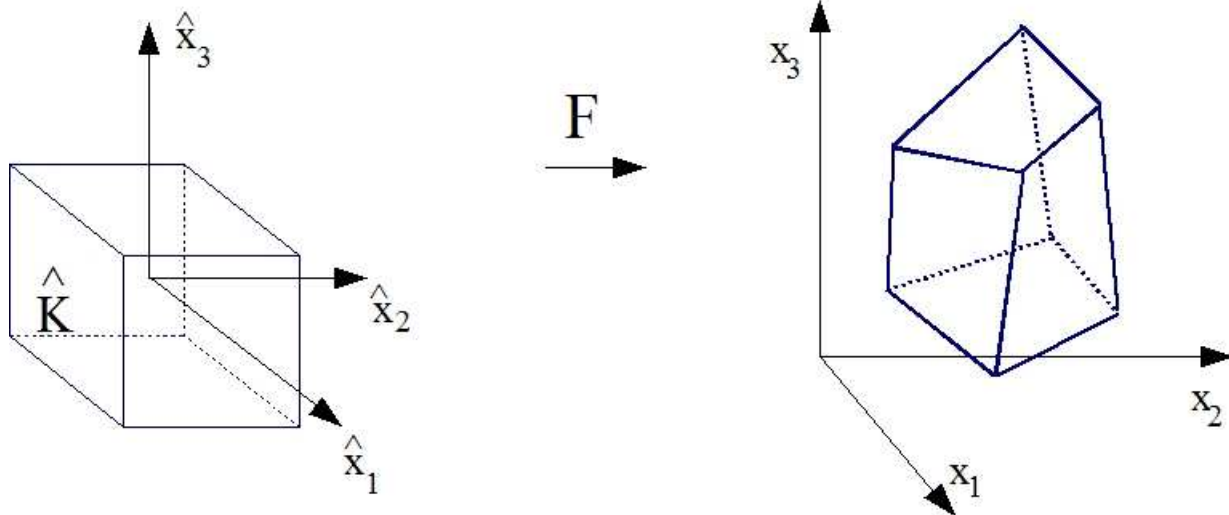
K : element of the triangulation

\hat{K} : reference element



F is bilinear

$$J_F = \det(DF) \in Q_1 \cap P_2$$



F is trilinear

$$J_F = \det(DF) \in Q_{2 \cap} P_4$$

Piola transform:

$$\mathbf{u}(\mathbf{x}) = \frac{1}{J_F(\hat{\mathbf{x}})} \mathbf{DF}(\hat{\mathbf{x}}) \hat{\mathbf{u}}(\hat{\mathbf{x}}), \quad p(\mathbf{x}) = \hat{p}(\hat{\mathbf{x}})$$

$$\int_{\partial K} \mathbf{u} \cdot \mathbf{n} p ds = \int_{\partial \hat{K}} \hat{\mathbf{u}} \cdot \hat{\mathbf{n}} \hat{p} d\hat{s}, \quad \int_K \operatorname{div} \mathbf{u} p dx = \int_{\hat{K}} \operatorname{div} \hat{\mathbf{u}} \hat{p} dx$$

$$\hat{\mathbf{u}}(\hat{\mathbf{x}}) = \mathbf{M}(\hat{\mathbf{x}}) \mathbf{u}(\mathbf{x})$$

Non linear relations

$$\operatorname{div} \hat{\mathbf{u}}(\hat{\mathbf{x}}) = J_F(\hat{\mathbf{x}}) \operatorname{div} \mathbf{u}(\mathbf{x})$$

2D

$$\|\mathbf{u} - \pi_h \mathbf{u}\|_{0,\Omega} \leq Ch \|u\|_{1,\Omega}$$

$$\|\operatorname{div}(\mathbf{u} - \pi_h \mathbf{u})\|_{0,\Omega} \leq C \|\operatorname{div} \mathbf{u}\|_{1,\Omega}$$

3D

$$\|\mathbf{u} - \pi_h \mathbf{u}\|_{0,\Omega} \leq C \|u\|_{1,\Omega}$$

$$\|\operatorname{div}(\mathbf{u} - \pi_h \mathbf{u})\|_{0,\Omega} \leq C \|\operatorname{div} \mathbf{u}\|_{1,\Omega}$$

Solutions



- Increase the space of discretisation to control the non-linear part of the transformation F . (Arnold-Boffi-Falk, 2004 (2D))

2D

Parallelogram (RT_0)

Degrees of freedom: 4

Quadrilateral (ABF_0)

Degrees of freedom: $4+2=6$

By using the same way, we obtain

3D

Parallelepiped (RT_0)

Degrees of freedom: 6

Hexahedron

Degrees of freedom: 36!!

Solutions



- « Remesh » the quadrilaterals or hexahedrals
Yu. Kuznetsov and S. Repin (J. Numer. Math 2005)

Obviously it is a possibility

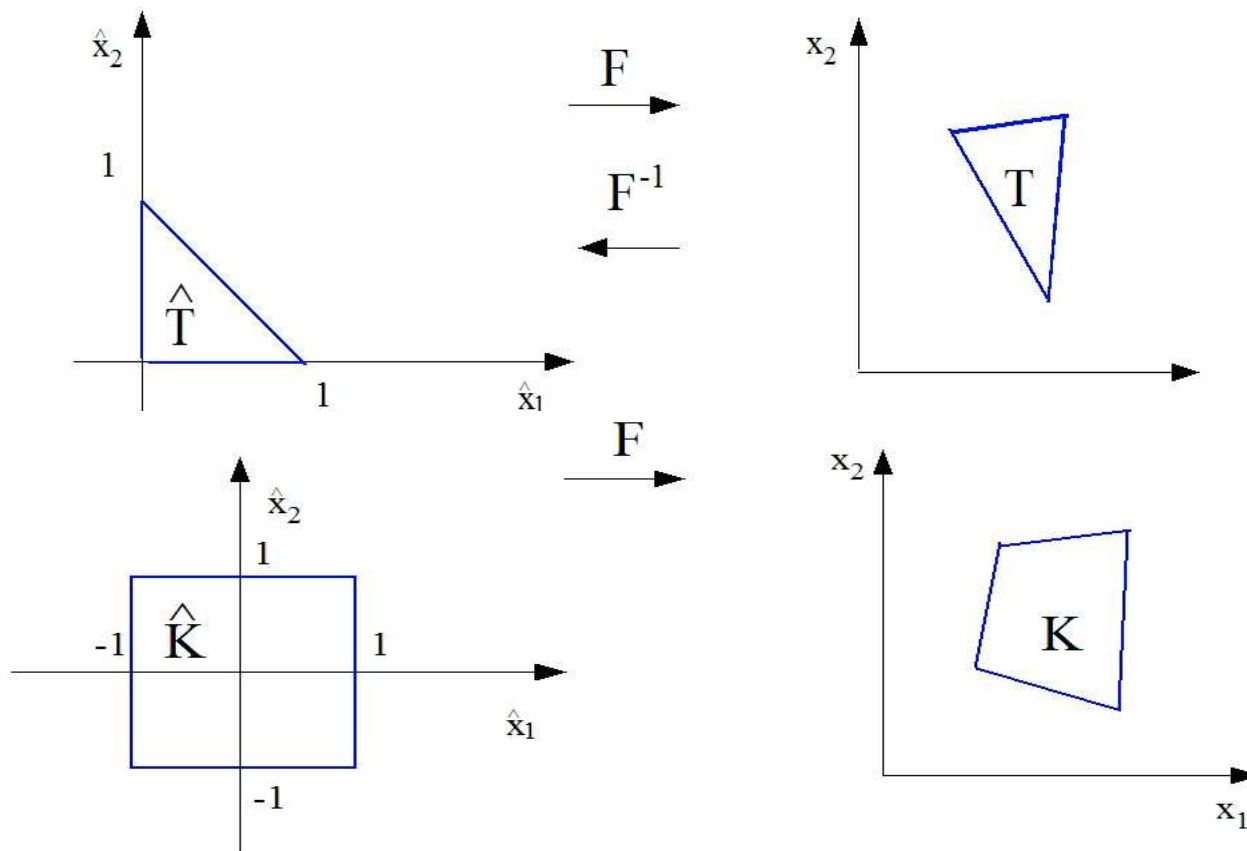
- Build pseudo-conform finite elements without adding degrees of freedom

We have chosen this last way

Cas 2D

Let us examine the Q_1 conform approximation on quadrilaterals. Why?

No loss of convergence with the Q_1 finite element but the background is different of the P_1 finite element on triangles



Work on \hat{T} is equivalent to work on T

$$\hat{p}|_{\hat{T}} \in P_1 \Leftrightarrow p|_T \in P_1$$

$$\hat{p}|_{\hat{K}} \in Q_1 \Rightarrow p|_K \notin Q_1$$

$p|_K$ is not polynomial

Consequence: All the integrals must be calculated on \hat{K}

$$\nabla p_h = DF^{-1} \nabla \hat{p}_h$$

$$\int_K \nabla p_h \cdot \nabla v_h dx = \int_{\hat{K}} DF^{-1} \nabla \hat{p}_h \cdot DF^{-1} \nabla \hat{v}_h J_F d\hat{x}$$

Goal:

Construct a new finite element satisfying:

- p_h is polynomial on K
- Degrees of freedom are the same
- On parallelogram, recover the classical “Q1 finite element”

Price to pay:

- The degree of the polynomials must be increased.
- The approximation is pseudo-conform

Geometry and notations

$K \subset \mathbf{R}^2$: a convex quadrilateral

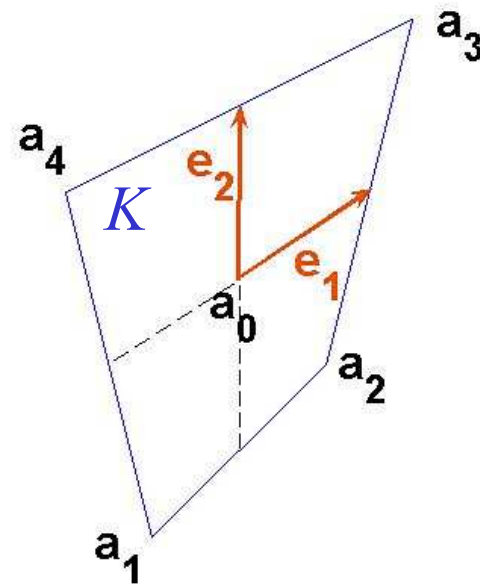
vertices : \mathbf{a}_i , edges : $\gamma_i = [\mathbf{a}_i, \mathbf{a}_{i+1}]$, $i = 1, \dots, 4$

center of K : $\mathbf{a}_0 = \frac{1}{4}(\mathbf{a}_1 + \mathbf{a}_2 + \mathbf{a}_3 + \mathbf{a}_4)$

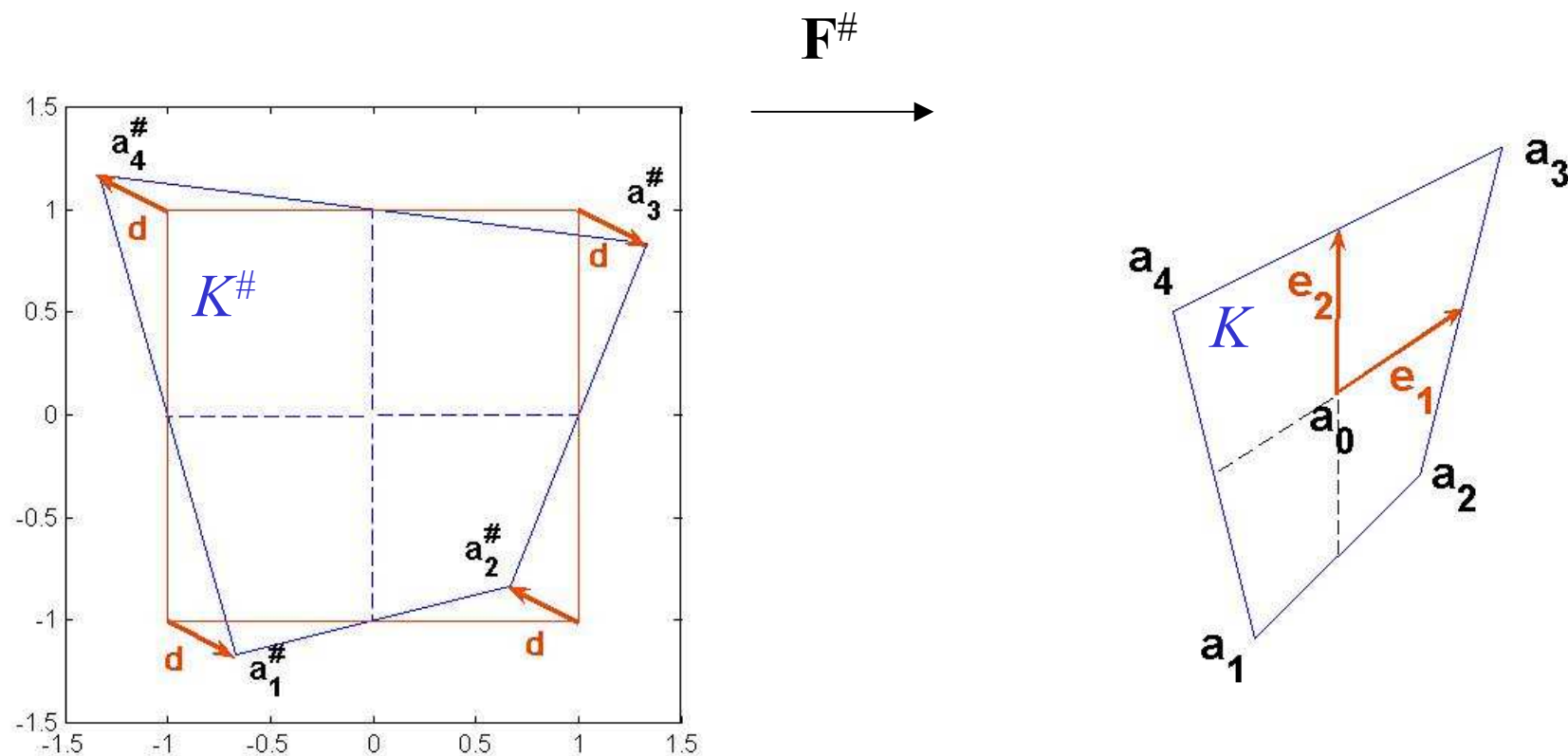
$(\mathbf{e}_1, \mathbf{e}_2)$ the basis of \mathbf{R}^2 given by

$$\mathbf{e}_1 = \frac{1}{4}(-a_1 + a_2 + a_3 - a_4)$$

$$\mathbf{e}_2 = \frac{1}{4}(-a_1 - a_2 + a_3 + a_4)$$



$\mathbf{F}^\#$: affine part of \mathbf{F} . By $\mathbf{F}^\#$, $K^\#$ is transformed into K
 $K^\#$ is a deformation of the unit square \hat{K}



$$K \text{ convex quadrilateral} \Leftrightarrow \|\mathbf{d}\|_K = |d_1| + |d_2| < 1$$

Construction of a new finite element $(K^\#, P_{K^\#}, \Sigma_{1,K^\#})$



We want $\Sigma_{1,K^\#} = \{w \rightarrow w(\mathbf{a}_i^\#), \quad 1 \leq i \leq 4\}$

Choice of $P_{K^\#}$?

$$\mapsto P_{K^\#} = Q_1$$

We obtain a non conforming approximation that does not satisfy the patch-test.
In the error estimation, we don't control the following term:

$$\sum_i \int_{\gamma_i} \frac{\partial \mathbf{u}}{\partial n} [\mathbf{u}_h - I_h \mathbf{u}] d\sigma$$

Solution : find $P_{K^\#}$ such that $\int_{\gamma_i} [\mathbf{u}_h] d\sigma = 0$

We must have $P_1 \subset P_{K^\#}$

Proposition:

For any convex quadrilateral K there exist a polynomial $\omega_{K^\#}$ such that for the choice:

$$P_{K^\#} = Vect(P_1, \omega_{K^\#})$$

We have

1°) $(K^\#, P_{K^\#}, \Sigma_{1,K^\#})$ is a finite element.

$$2^\circ) \quad \forall w \in P_{K^\#} \quad \int_{\gamma_i^\#} w d\sigma = \frac{|\gamma_i|}{2} \{w(\mathbf{a}_i^\#) + w(\mathbf{a}_{i+1}^\#)\} \quad (i = 1, \dots, 4)$$

Remark : $\omega_{K^\#}$ is not unique

Moreover, it is of interest to obtain:

- $\omega_{K^\#}$ depend continuously on the distortion parameter \mathbf{d}
- at the limite $\mathbf{d} = 0$, the finite element $(K^\#, P_{K^\#}, \Sigma_{1,K^\#}) = (\hat{K}, Q_1, \hat{\Sigma})$
the Lagrange reference finite element on the unit square

The simplest choice is to choose $\omega_{K^\#}$ in $P_3 \cap Q_2$ satisfying :

$$\left| \begin{array}{l} \omega_{K^\#}(\mathbf{a}_i) = (-1)^{i+1} \quad i = 1, \dots, 4 \\ \int_{\gamma_i^\#} \omega_{K^\#} d\sigma = 0 \quad i = 1, \dots, 4 \end{array} \right.$$

$\omega_{K^\#}$ can be calculated explicitley according to \mathbf{d} or numerically

Remark: We can computed the finite element basis in $P_3 \cap Q_2$ without calculating $\omega_{K^\#}$

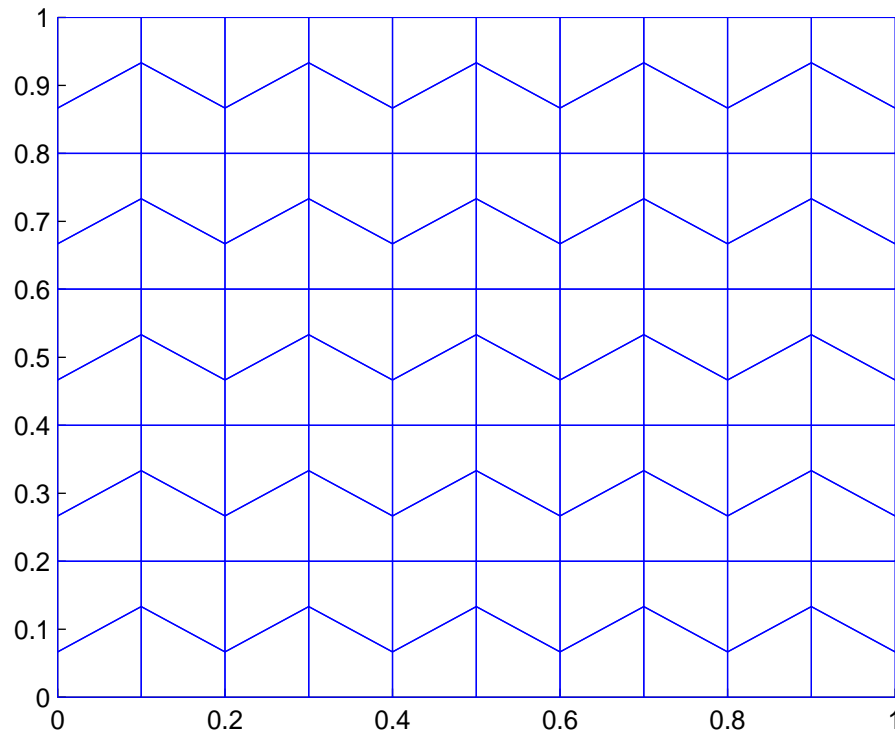
$$\omega_{K^\#}(x_1^\#, x_2^\#) = \frac{1}{den} (-3d_1d_2(1-d_1^2)(1-d_2^2)(1-x_1^{\#2} - x_2^{\#2})$$

$$+ (1-2d_1^2-2d_2^2+d_1^4+72d_1^2d_2^2+2d_2^4-32d_1^2d_2^4-32d_1^4d_2^2)x_1^\#x_2^\#$$

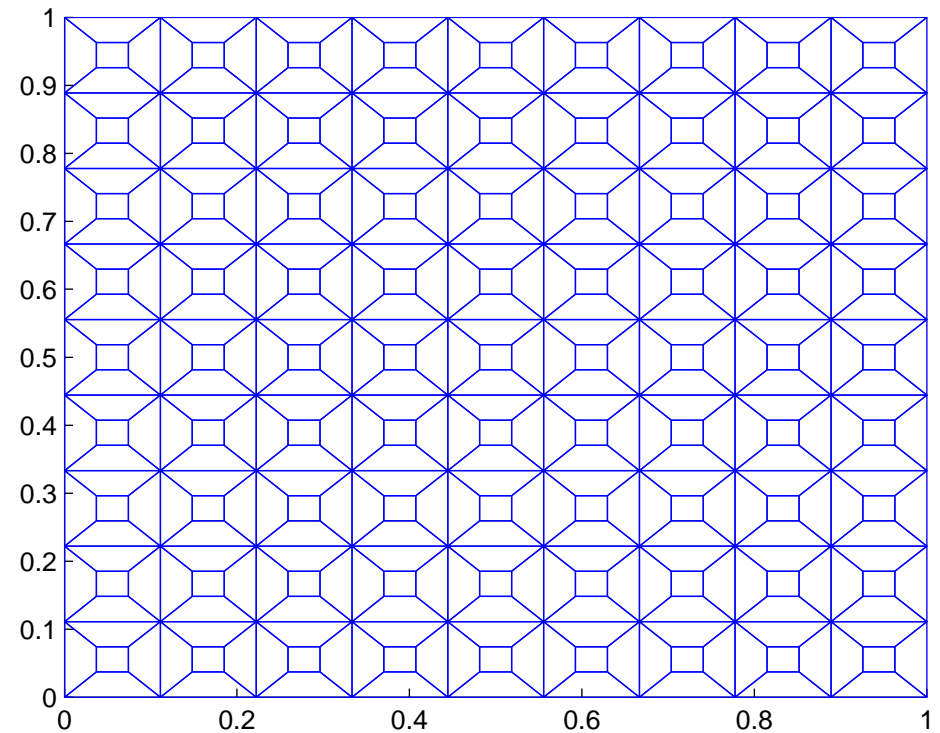
$$+ (-1-d_1^2+2d_2^2+2d_1^4-d_1^2d_2^2+d_2^4)d_2x_1^{\#2}x_2^\#$$

$$+ (-1+2d_1^2-d_2^2-d_1^4-d_1^2d_2^2+2d_2^4)d_1x_1^\#x_2^{\#2})$$

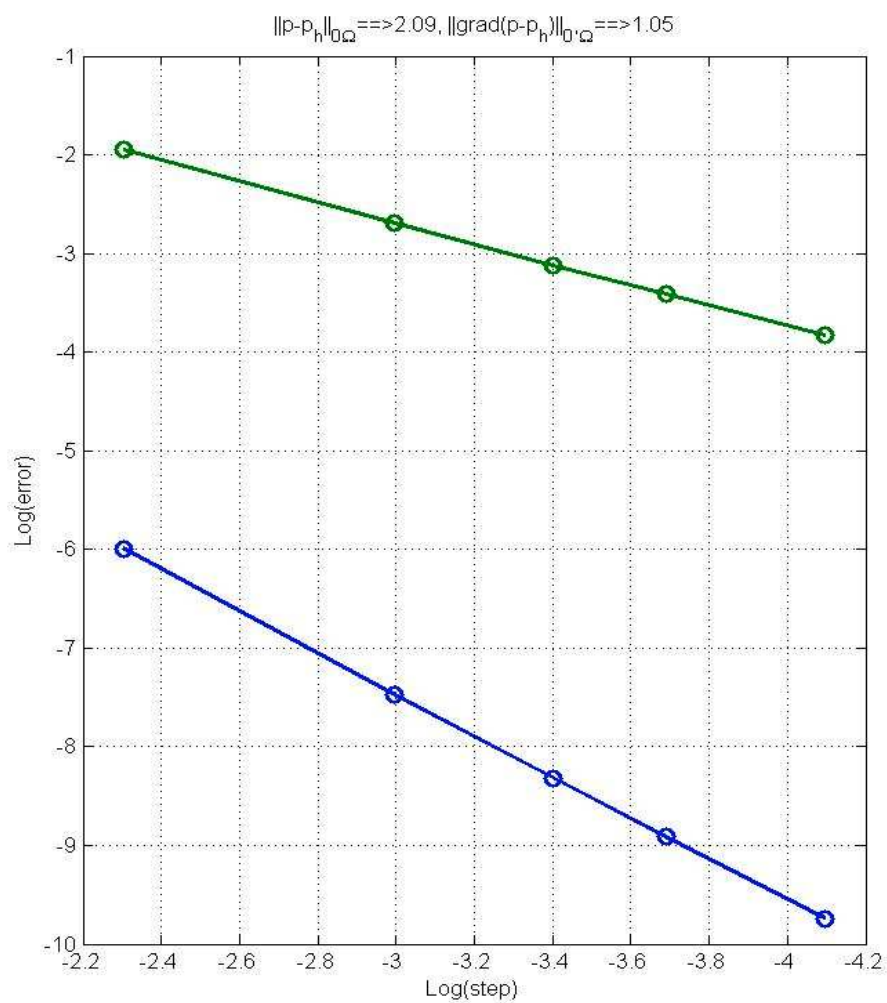
with $den = (1-d_1^2)(1-d_2^2)(1-(d_1+d_2)^2)(1-(d_1-d_2)^2)$



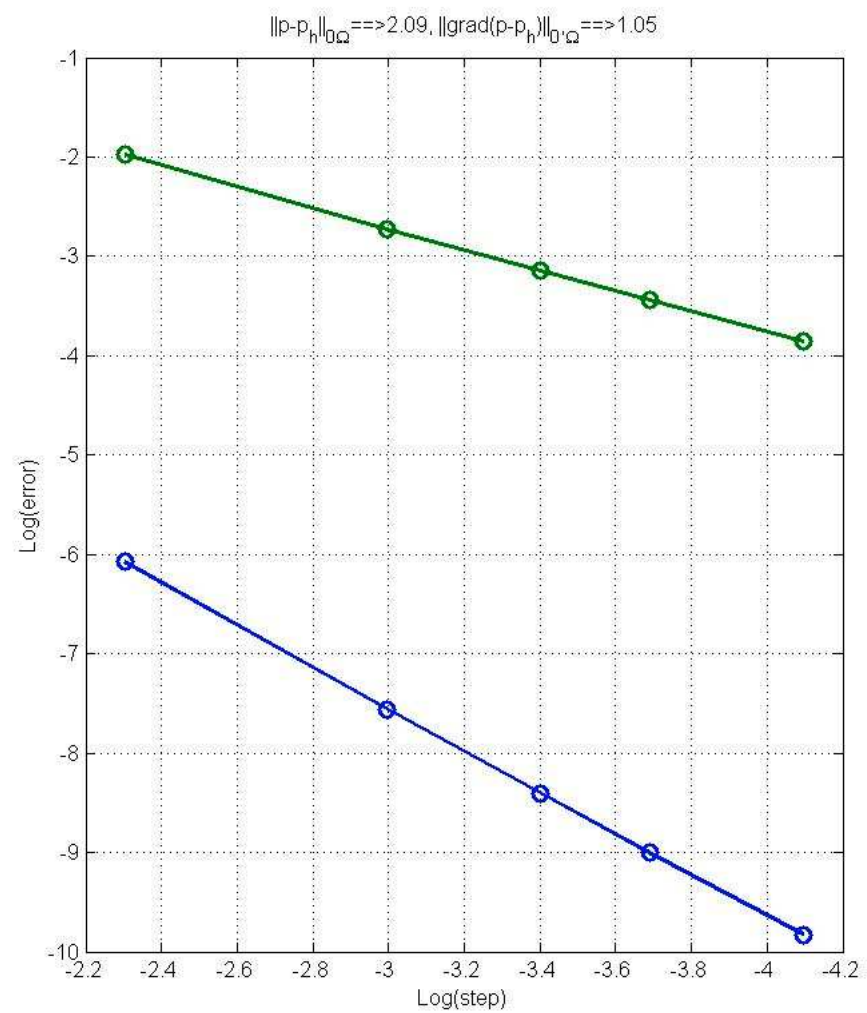
Mesh in “chevron”



Mesh in “alvéole”



Q_1 conform



Pseudo-conform method

Let us return to the initial problem



Construction of a new finite element $(K^\#, P_{K^\#}^*, \Sigma_{1,K^\#}^*)$

$$\text{We want } \Sigma_{1,K^\#}^* = \left\{ \mathbf{w} \rightarrow \int_{\gamma_i^\#} \mathbf{w} \cdot \mathbf{n} d\sigma, \quad 1 \leq i \leq 4 \right\}$$

Proposition:

For any convex quadrilateral K there exist a polynomial vector $\boldsymbol{\psi}_{K^\#}$ such that for the choice:

$$P_{K^\#}^* = \text{vect}(P_0 \times P_0, \mathbf{x}^\#, \boldsymbol{\psi}_{K^\#})$$

We have

1°) $(K^\#, P_{K^\#}^*, \Sigma_{1,K^\#}^*)$ is a finite element.

2°) $\forall \mathbf{w} \in P_{K^\#}^*, \forall s \in P_1$

$$\int_{\gamma_i^\#} s \mathbf{w} \cdot \mathbf{n} d\sigma = \left(\frac{1}{|\gamma_i|} \int_{\gamma_i} s d\sigma \right) \int_{\gamma_i} \mathbf{w} \cdot \mathbf{n} d\sigma \quad (i = 1, \dots, 4)$$

At the limite $\mathbf{d} = 0$, the finite element $(K^\#, P_{K^\#}^*, \Sigma_{1,K^\#}^*) = (\hat{K}, P_{1,0} \times P_{0,1}, \hat{\Sigma}_1^*)$
the RT reference finite element on the unit square

- The simplest choice is to choose $\boldsymbol{\psi}_{K^\#} = \mathbf{rot}(\omega_{K^\#})$

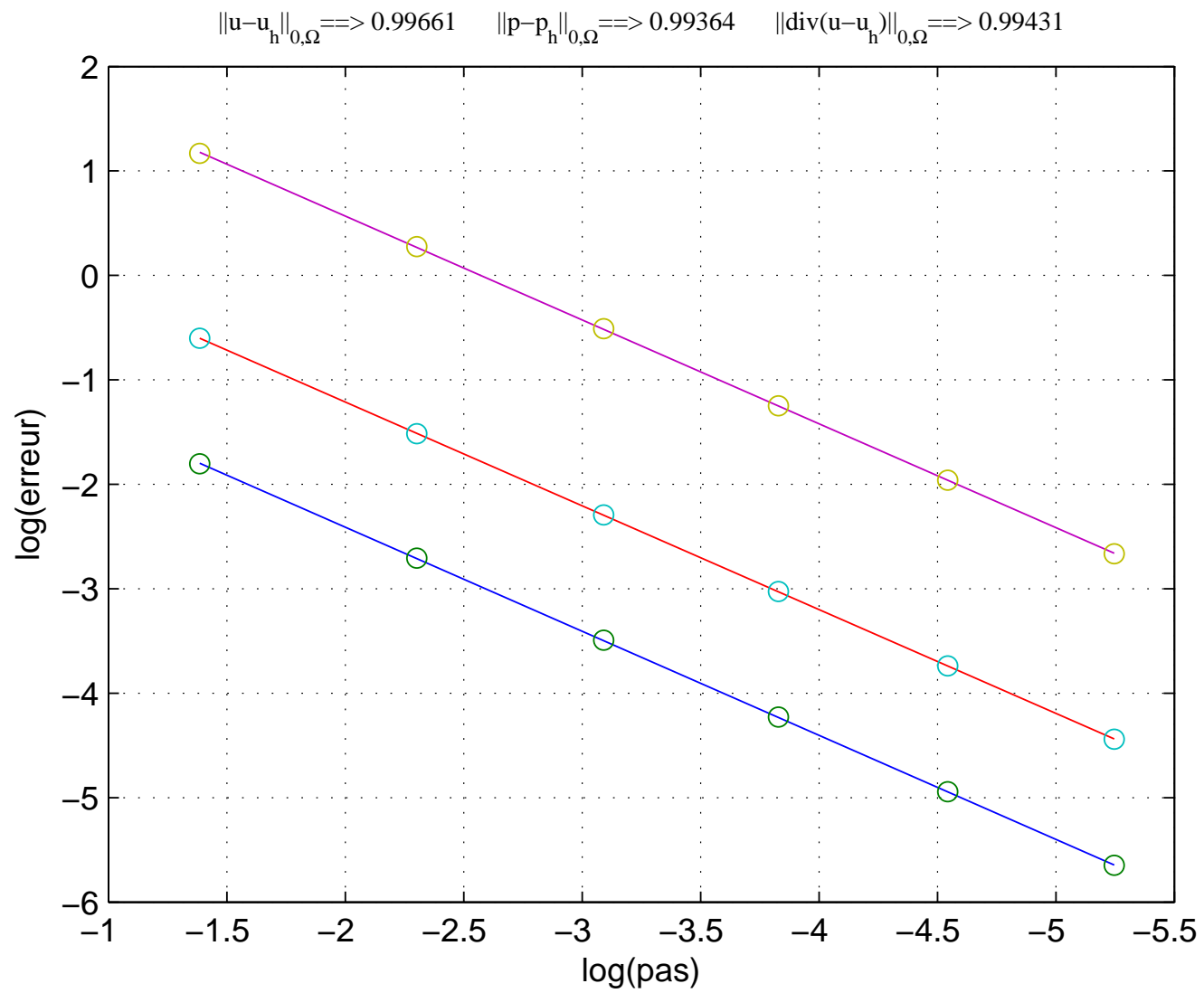
(De Rham diagram $H^1 \xrightarrow{rot} H(div)$)

- Another choice is to choose $\boldsymbol{\psi}_{K^\#}$ in BDM_1 satisfying :

$$div(\boldsymbol{\psi}_{K^\#}) = 0, \int_{\gamma_i^\#} \boldsymbol{\psi}_{K^\#} \cdot \mathbf{n} d\sigma = (-1)^i, \int_{\gamma_i^\#} s \boldsymbol{\psi}_{K^\#} \cdot \mathbf{n} d\sigma = 0 \quad i = 1, \dots, 4$$

$$BDM_1 = vect\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} y \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ x \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} -x \\ y \end{pmatrix}, \begin{pmatrix} -x^2 \\ 2xy \end{pmatrix}, \begin{pmatrix} -2xy \\ x^2 \end{pmatrix}\right)$$

Remark: We can computed the finite element basis in BDM_1
without calculated $\boldsymbol{\psi}_{K^\#}$



The convergence orders are good

Conclusion



- If the quadrilaterals K are parallelograms we have

$$(K^\#, P_{K^\#}, \Sigma_{1,K^\#}) = (\hat{K}, Q_1, \hat{\Sigma})$$

$$(K^\#, P_{K^\#}^*, \Sigma_{1,K^\#}^*) = (\hat{K}, P_{1,0} \times P_{0,1}, \hat{\Sigma}_1^*)$$

and the approximations are conform.

- If the quadrilaterals K are not parallelograms the approximations are not conform.

The use of $(K^\#, P_{K^\#}, \Sigma_{1,K^\#})$ allows us to have the continuity of p_h at the nodes and only the continuity of the mean values through each edge of the mesh.

The use of $(\hat{K}, P_{1,0} \times P_{0,1}, \hat{\Sigma}_1^*)$ allows us to have the continuity of the mean value of $\mathbf{u}_h \cdot \mathbf{n}$ and the continuity of the first momentum of $\mathbf{u}_h \cdot \mathbf{n}$ through each edge.

- The implementation is simple, but the basis functions depend on of the shape of K .

3D case

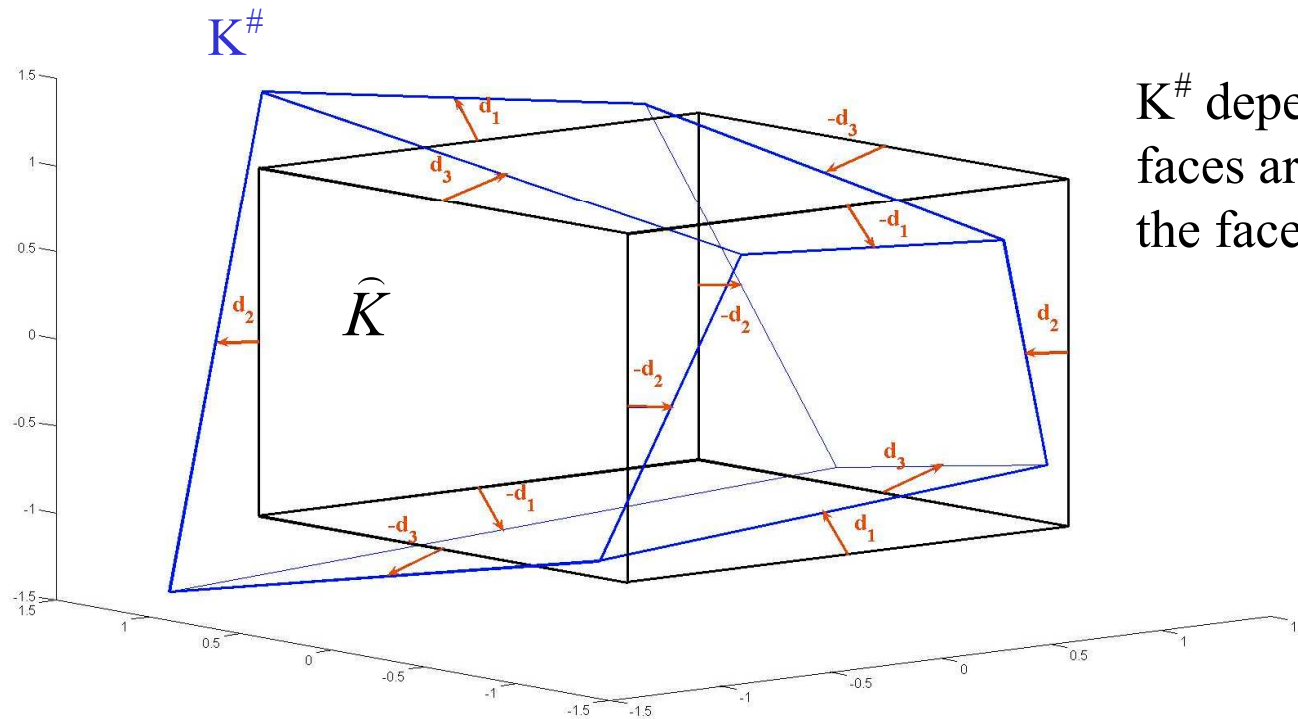


We apply the same approach with the 3D case.

Problems with the hexahedrons

- Description of a hexahedron (deformation of the unit cube)
- Plane faces and non-plane faces? Is it a real problem?
- Parametrisation of the faces

3D case



$K^\#$ depends on 6 parameters if the faces are plane and 9 parameters if the faces are not plane.

$$\int_{\gamma_i^\#} v(\mathbf{x}^\#) d\sigma^\# = \int_{\hat{\gamma}_i} v(\mathbf{x}^\#(\hat{\mathbf{x}})) \|\mathbf{M}(\hat{\mathbf{x}})\hat{\mathbf{n}}_i\| d\hat{\sigma}$$

plane face : $\|\mathbf{M}(\hat{\mathbf{x}})\hat{\mathbf{n}}_i\| \in P_1$

non plane face : $\|\mathbf{M}(\hat{\mathbf{x}})\hat{\mathbf{n}}_i\|$ is not polynomial

Construction of a new finite element $(K^\#, P_{K^\#}, \Sigma_{1,K^\#})$



We want $\Sigma_{1,K^\#} = \{w \rightarrow w(\mathbf{a}_i^\#), \quad 1 \leq i \leq 8\}$

How to build $P_{K^\#}$? (case of plane faces)

→ Let be $V_{K^\#}$ a polynomial space such that

- $\dim(V_{K^\#}) = 14$
- $P_1 \subset V_{K^\#}$
- $\Sigma_{2,K^\#} = \left\{ w \rightarrow w(\mathbf{a}_i), i = 1 \dots 8; w \rightarrow \int_{\gamma_i^\#} v d\sigma^\#, i = 1 \dots 6 \right\}$

is unisolvant on $V_{K^\#}$ when $K^\# = \hat{K}$

→ Building of integration formulas

$$\forall v \in P_1(K^\#) \quad \int_{\gamma_i^\#} v d\sigma^\# = \sum_{j=1}^4 \omega_{\gamma_i^\#, j} v(\mathbf{a}_{l_i(j)}^\#) \quad i = 1, \dots, 6$$

where $(l_i(j), j = 1, \dots, 4)$ are serial numbers of the node of the face $\gamma_i^\#$, $\omega_{\gamma_i^\#, j}$ depend only on the values of the cofacteur matrix of the jacobian at points $(\mathbf{a}_{l_i(j)}^\#, j = 1, \dots, 4)$

$$\rightarrow P_{K^\#}^* = \left\{ v \in V_{K^\#}^*; \int_{\gamma_i^\#} s_j v d\sigma^\# = \sum_{j=1}^4 \omega_{\gamma_i^\#, j} v(\mathbf{a}_{l_i(j)}^\#) \quad i = 1, \dots, 6 \right\}$$

→ Possible choices of polynomial space $V_{K^\#}$

- $V_{K^\#} = \{1, x, y, z, xy, xz, yz, xyz, x^2, y^2, z^2, x^2y, y^2z, xz^2\} \subset P_3 \cap Q_2$

- $V_{K^\#} = Q_1(K^\#) \oplus (1-x^2)(1-y^2)(1-z) \oplus (1-x^2)(1-y^2)(1+z)$
 $\oplus (1-y^2)(1-z^2)(1-x) \oplus (1-y^2)(1-z^2)(1+x)$
 $\oplus (1-z^2)(1-x^2)(1-y) \oplus (1-z^2)(1-x^2)(1+y)$

Proposition:

For any quadrilateral $K^\#$ not too much deformed compared to unit cube we have

1°) $(K^\#, P_{K^\#}, \Sigma_{1,K^\#})$ is a finite element.

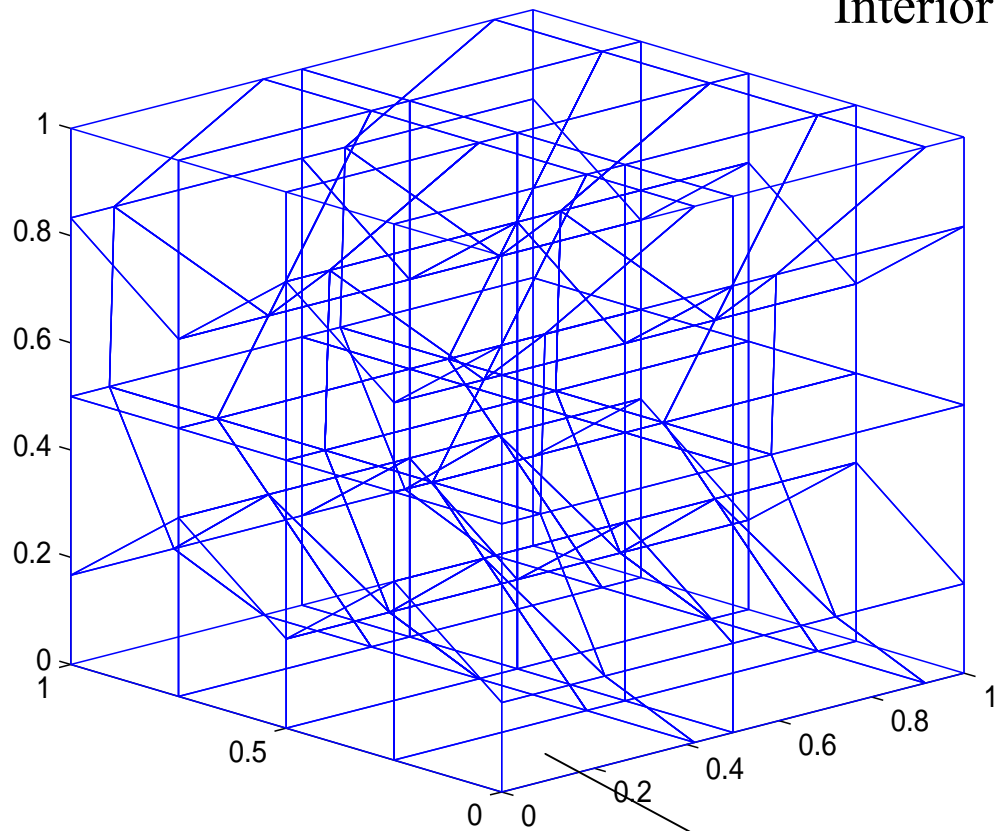
$$2^\circ) \quad \forall v \in P_{K^\#} \int_{\gamma_i^\#} v d\sigma^\# = \sum_{j=1}^4 \omega_{\gamma_i^\#,j} v(\mathbf{a}_{l_i(j)}^\#) \quad i = 1, \dots, 6$$

Remark: The main difference, when the faces are not plane, concerns the integration formulas:

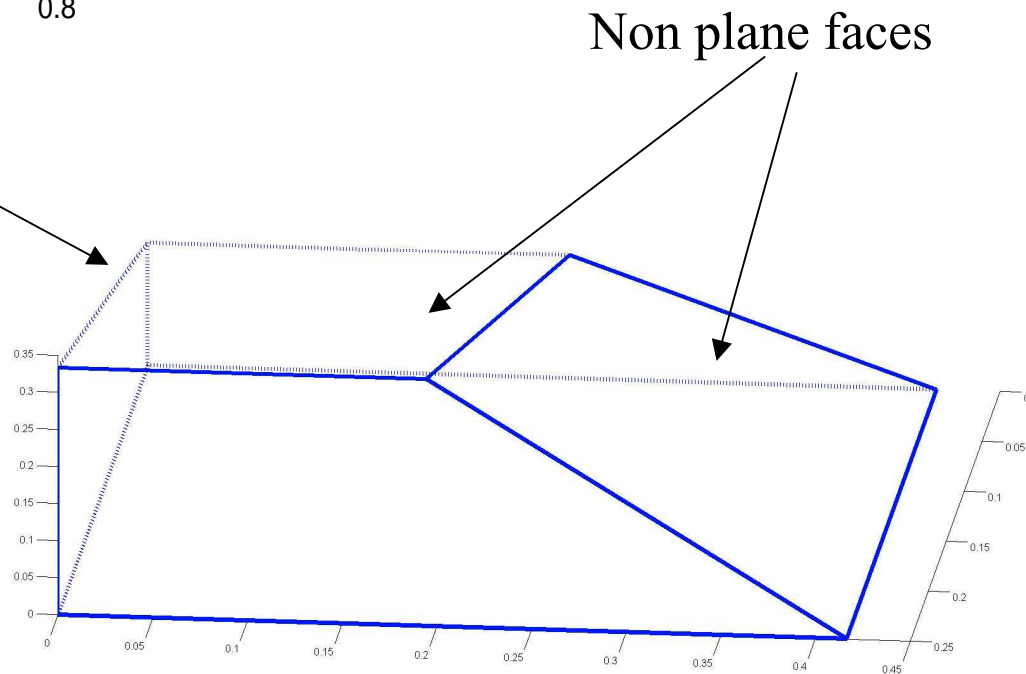
$\omega_{\gamma_i^\#,j}$ are explicitly known in the plane case

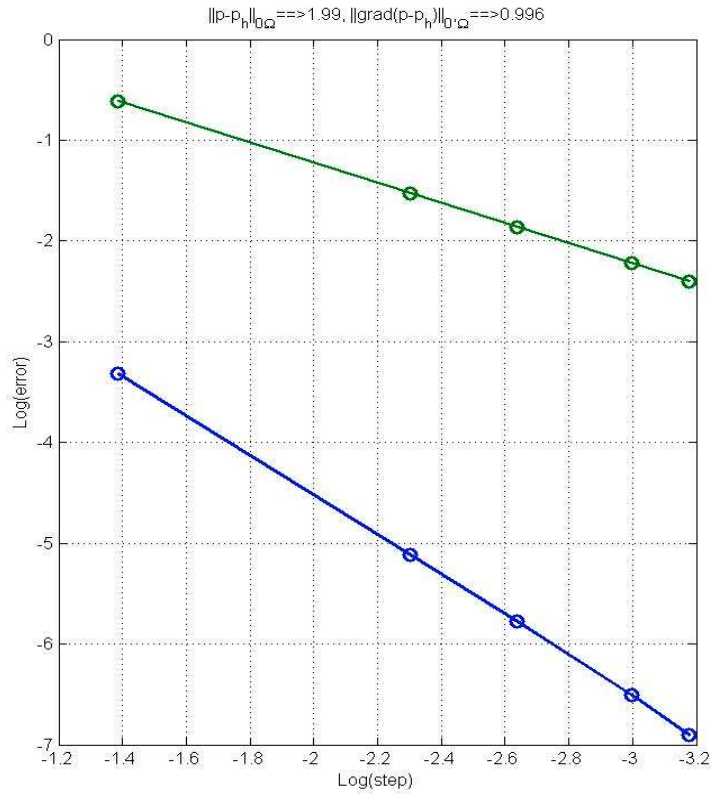
$\omega_{\gamma_i^\#,j}$ must be numerically calculated in the non - plane case

Interior faces are not plane



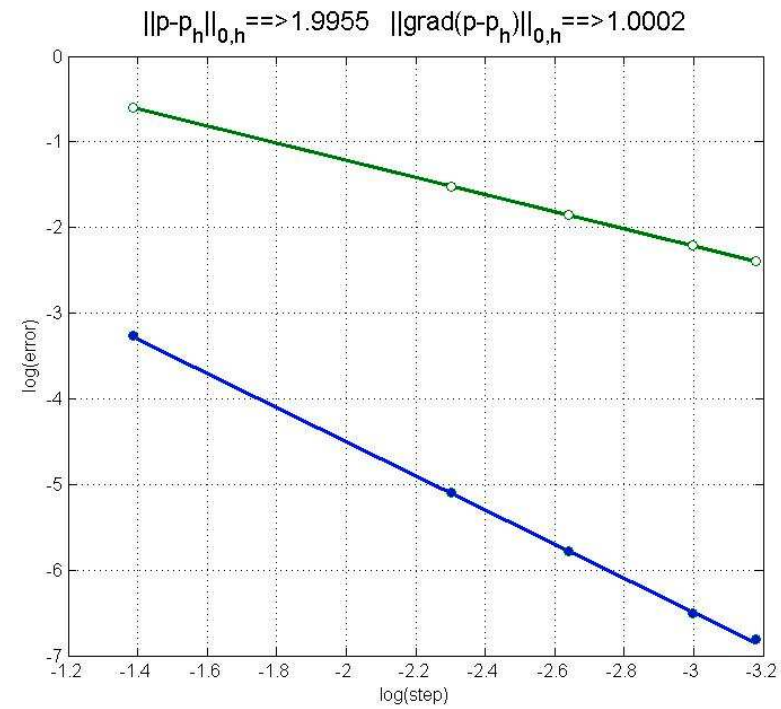
Destructured mesh



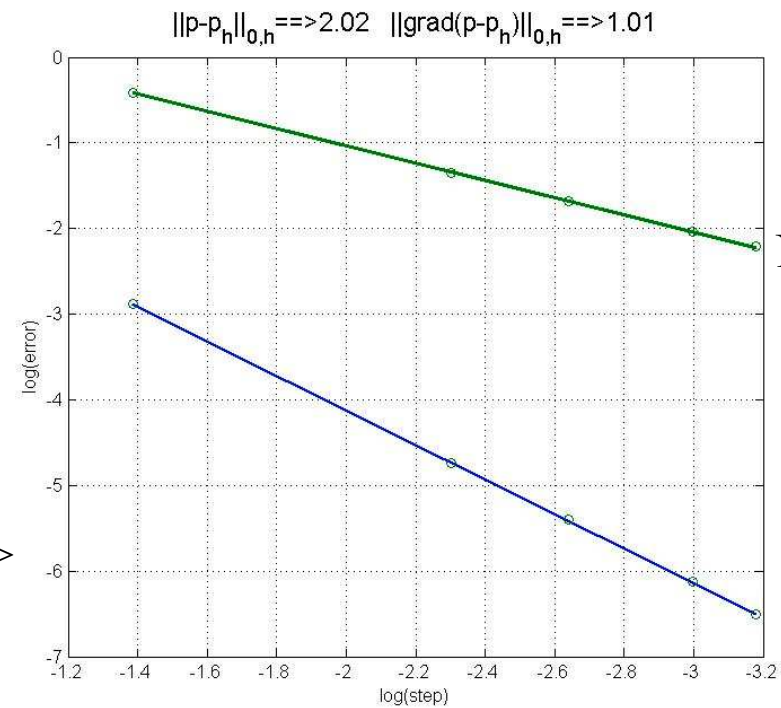


Q_1 conform

Pseudo-conform method \Rightarrow



Plane faces



Non-plane faces

What's about the approximation in Hdiv



Construction of a new finite element $(K^\#, P_{K^\#}^*, \Sigma_{1,K^\#}^*)$

$$\text{We want } \Sigma_{1,K^\#}^* = \left\{ \mathbf{w} \rightarrow \int_{\gamma_i^\#} \mathbf{w} \cdot \mathbf{n}_i d\sigma, \quad 1 \leq i \leq 6 \right\}$$

How to built $P_{K^\#}^*$?

→ Let be $V_{K^\#}^*$ a polynomial space such that

- $\dim(V_{K^\#}^*) = 18$
- $P_{0,0,0} \subset V_{K^\#}^*$
- $\Sigma_{2,K^\#}^* = \left\{ \mathbf{u} \rightarrow \int_{\gamma_i^\#} \mathbf{u} \cdot \mathbf{n} d\sigma^\#, i = 1 \dots 6; w \rightarrow \int_{\gamma_i^\#} s_j \mathbf{u} \cdot \mathbf{n} d\sigma^\#, i = 1 \dots 6, j = 1, 2 \right\}$

is unisolvant on $V_{K^\#}$ when $K^\# = \hat{K}$

→ Building of integration formulas

$$\forall \mathbf{v} \in P_{0,0,0}(K^\#) \quad \int_{\gamma_i^\#} s_j \mathbf{v} \cdot \mathbf{n}_i d\sigma^\# = \omega_{\gamma_i^\#, j} \int_{\gamma_i^\#} \mathbf{v} \cdot \mathbf{n}_i d\sigma^\# \quad j = 1, 2; i = 1, \dots, 6$$

$\omega_{\gamma_i^\#, j}$ depend only on values of the cofacteur matrix of the jacobian on $\gamma_i^\#$.

$$\rightarrow P_{K^\#}^* = \left\{ \mathbf{v} \in V_{K^\#}^*; \int_{\gamma_i^\#} s_j \mathbf{v} \cdot \mathbf{n}_i d\sigma^\# = \omega_{\gamma_i^\#, j} \int_{\gamma_i^\#} \mathbf{v} \cdot \mathbf{n}_i d\sigma^\# \quad j = 1, 2; i = 1, \dots, 6 \right\}$$

→ Possible choice of polynomial space $V_{K^\#}^* = BDM_1$

$$BDM_1 = vect \left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} y \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} z \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ x \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ z \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ x \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ y \end{pmatrix}, \begin{pmatrix} -x \\ 0 \\ z \end{pmatrix}, \begin{pmatrix} x \\ -y \\ 0 \end{pmatrix}, \begin{pmatrix} x \\ y \\ z \end{pmatrix}, \begin{pmatrix} x^2 \\ -2xy \\ 0 \end{pmatrix}, \begin{pmatrix} -2xz \\ 0 \\ z^2 \end{pmatrix}, \begin{pmatrix} -2xy \\ y^2 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -xy \\ xz \end{pmatrix}, \begin{pmatrix} xz \\ -yz \\ 0 \end{pmatrix}, \begin{pmatrix} xy \\ 0 \\ -yz \end{pmatrix} \right)$$

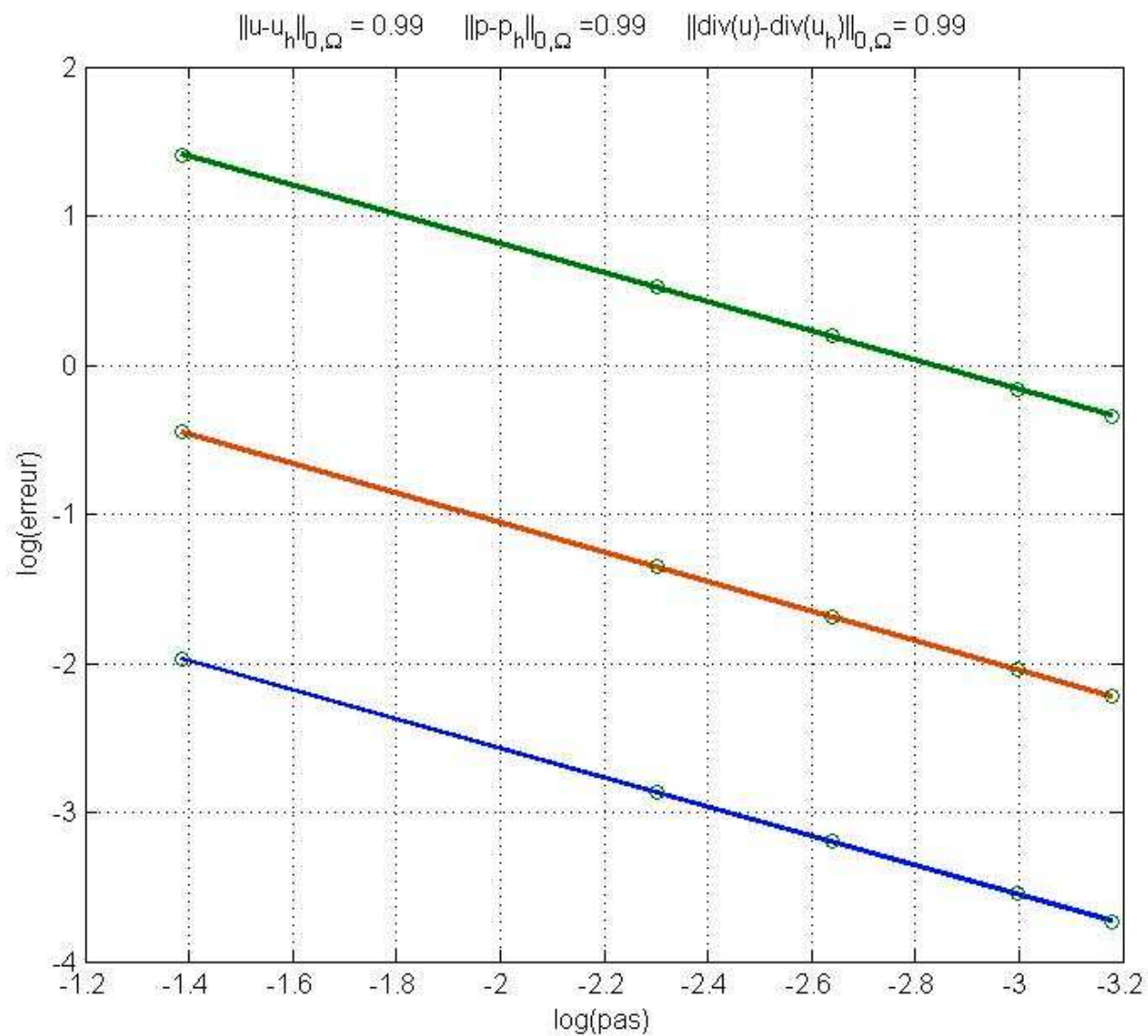
Proposition:

For any quadrilateral $K^\#$ not too much deformed compared to unit cube we have

1°) $(K^\#, P_{K^\#}^*, \Sigma_{1,K^\#}^*)$ is a finite element.

$$2^\circ) \quad \forall \mathbf{v} \in P_{K^\#}^* \quad \int_{\gamma_i^\#} s_j \mathbf{v} \cdot \mathbf{n}_i d\sigma^\# = \omega_{\gamma_i^\#, j} \int_{\gamma_i^\#} \mathbf{v} \cdot \mathbf{n}_i d\sigma^\# \quad j = 1, 2; i = 1, \dots, 6$$

Problem with the integration formula when the faces are not plane.



Pseudo-conform method (plane faces)

Conclusions

- 2D case:
 - The numerical results agree with the theoretical results.
 - Possibility to generalise the results to FEM of higher degrees.
- 3D case:
 - Necessity to work on the geometry of the hexahedrons.
 - Clarify the problem of plane faces and non-plane faces.
 - Use the De Rham diagram to connect the H_1 case to the $H(\text{div})$ case

$$\text{(De Rham diagram : } H^1 \xrightarrow{\nabla} H(\text{curl}) \xrightarrow{\text{rot}} H(\text{div}))$$