Definition 1.11: the map i has to be *strict*, not only continuous, that is: the (discrete) topology on $\overline{G}(\bar{k})$ must be induced by the topology on E. Same remark in the assumptions of the proposition in the appendix.

Remark 2.3.: "descent datum" should be "glueing datum". Also condition (*) is a priori stronger than simply requiring that all conjugate torsors are isomorphic.

Definition 4.2: the displayed formula does not follow immediately from the definition because Y is not necessarily proper (hence in general $Y(\mathbf{A}_k)$ is not the same as $\prod_v Y(k_v)$). Nevertheless the formula is easy to prove using the well known injectivity of the map $H^1(\mathcal{O}_v, \mathcal{G}_v) \to H^1(k_v, G)$ when v is a place of good reduction of G and $\mathcal{G}_v$ is a smooth model of G over $\mathrm{Spec}\,(\mathcal{O}_v)$.