

Singular and singularly perturbed systems and multiple resurgence.

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1. Types of resurgence.

Among the many types of *resurgence*, two stand out:

- (i) *Equational resurgence*, so-called because it arises in 'singular' equations (differential; partial diff.; functional etc). It is by now well understood. Prof. B. Yu. Sternin, for one, devoted a number of papers to the subject, esp. about PDE' s.
- (ii) *Co-equational resurgence*. It is quite prevalent in theoretical physics and occurs typically in (power series) expansions in a 'singular' small parameter. Many interesting parameters or constants in physics fall into this category¹. It is far more complex than equational resurgence, yet loosely dual to it.
- (iii) To highlight these differences-cum-similarities, we shall focus on a model problem (*non-linear singular and singularly perturbed differential systems*) where both types of resurgence coexist side-by-side.

But before getting into the thick of things, a few ultra-quick reminders are in order.

¹Cf the Michael Berry 'principle': *the divergence of expansions in a small parameter such as $\hbar$ reflects the non-trivial nature of the transition from a classical theory to its non-classical extension.* 

2. Resurgent functions.

Resurgent functions live in three models:

- (i) In the *formal model*, as formal power series $\tilde{\varphi}(z)$ of z^{-1} .
- (ii) In the *convolution model* or *Borel plane*, as analytic germs $\hat{\varphi}(\zeta)$ at 0, endlessly continuable (laterally along any finitely broken line).
- (iii) In the *geometric models*, as sectorial germs $\varphi_\theta(z)$ at ∞ in the z -variable.

$$(i) \quad \tilde{\varphi}(z) = \sum a_n z^{-n} \quad \text{multiplication}$$

$\downarrow$ *Borel*

$$(ii) \quad \hat{\varphi}(\zeta) = \sum a_n \frac{\zeta^{n-1}}{(n-1)!} \quad \text{convolution} \quad \left\{ \begin{array}{l} (\hat{\varphi}_1 * \hat{\varphi}_2)(\zeta) := \\ \int_0^\zeta \hat{\varphi}_1(\zeta_1) \hat{\varphi}_2(\zeta - \zeta_1) d\zeta_1 \end{array} \right.$$

$\downarrow$ *Laplace*

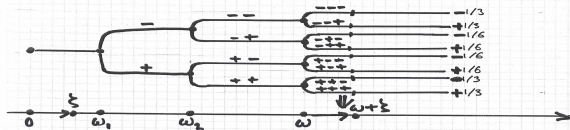
$$(iii) \quad \varphi_\theta(z) = \int_{\arg \zeta = \theta} e^{-z\zeta} \hat{\varphi}(\zeta) d\zeta \quad \text{multiplication}$$

The singularities of $\hat{\varphi}(\zeta)$ carry the Stokes constants and are responsible for the divergence of $\tilde{\varphi}(z)$. So they deserve close attention.

The tools for measuring them are the so-called *alien derivations* Δ_ω .

3. Alien derivations.

The one outstanding fact about resurgent functions is the existence on them of a huge array of exotic derivations – the so-called *alien derivations* Δ_ω ($\omega \in \mathbb{C}_\bullet = \widetilde{\mathbb{C} - \{0\}}$). They are bound by no *a priori* constraints.



$$\hat{\Delta}_\omega \hat{\varphi}(\zeta) = \sum_{\epsilon_i = \pm} \delta^{p,q} \left(\hat{\varphi}^{(\epsilon_1; \epsilon_2; \dots; \epsilon_r; +)}(\zeta + \omega) - \hat{\varphi}^{(\epsilon_1; \epsilon_2; \dots; \epsilon_r; -)}(\zeta + \omega) \right)$$

$$\hat{\Delta}_\omega \hat{\varphi}(\zeta) = \frac{1}{2\pi i} \sum_{\epsilon_i \in \{+, -\}} \frac{p! q!}{(p+q+1)!} \begin{cases} +\hat{\varphi}^{(\epsilon_1, \dots, \epsilon_{r-1}, +)}(\zeta + \omega) \\ -\hat{\varphi}^{(\epsilon_1, \dots, \epsilon_{r-1}, -)}(\zeta + \omega) \end{cases}$$

3*. Using alien derivations.

$$\widehat{\Delta}_\omega(\widehat{\varphi}_1 * \widehat{\varphi}_2) \equiv (\widehat{\Delta}_\omega \widehat{\varphi}_1) * \widehat{\varphi}_2 + \widehat{\varphi}_1 * (\widehat{\Delta}_\omega \widehat{\varphi}_2)$$

$$\Delta_\omega(\widetilde{\varphi}_1 \cdot \widetilde{\varphi}_2) \equiv (\Delta_\omega \widetilde{\varphi}_1) \cdot \widetilde{\varphi}_2 + \widetilde{\varphi}_1 \cdot (\Delta_\omega \widetilde{\varphi}_2)$$

$$\mathbb{A}_\omega := e^{-\omega z} \Delta_\omega \implies [\mathbb{A}_\omega, \partial_z] \equiv 0$$

The system $\{\Delta_{\omega_r} \dots \Delta_{\omega_1} \widetilde{\varphi}\}$ encodes all the information about the Borel transform $\widehat{\varphi}(\zeta)$, its behaviour on all its Riemann sheets, and its Stokes constants.

$$E(\widetilde{\varphi}) = 0 \quad \text{gen. diff. or functional equ. or system}$$

↓ *formally*

$$E(\widetilde{\varphi}, \mathbb{A}_\omega \widetilde{\varphi}) = 0 \quad \text{linear homogeneous in } \mathbb{A}_\omega \widetilde{\varphi}$$

↓ *formally*

$$\mathbb{A}_\omega \widetilde{\varphi} = A_\omega \widetilde{\varphi}_\omega \quad \begin{cases} A_\omega = \text{Stokes constant} \\ \widehat{\varphi}_\omega(\zeta) = \text{singular germ at, or "over", } \omega \end{cases}$$

4. The Bridge equation.

- (1) $E(Y) = 0$ *gen. diff. or functional equ. or system*
 $\downarrow$ *formally*
- (2) $Y(z; \tau)$ *complete (parameter-saturated) formal solution*
 $\downarrow$ *formally* $Y(z; \tau)$ *typ.^{lly} in $\mathbb{C}[[z^{-1}; \bigcup_i \tau_i z^{\alpha_i} e^{\omega_i z}]]$*
- (3) Ω $\Omega = \{\omega \in \mathbb{C}_\bullet; \Delta_\omega Y \neq 0\}$
 $\downarrow$ *formally*
- (4) $\Delta_\omega Y(z; \tau) = \mathbb{A}_\omega Y(z; \tau)$ *Bridge Equation*
 $\downarrow$ *formally* $\begin{cases} \mathbb{A}_\omega \text{ ord. diff. operator. (exp.-compatible)} \\ \mathbb{A}_\omega \stackrel{\text{typ.}^{lly}}{=} e^{-\omega z} \tau^n (A_\omega^0 \partial_z + \sum A_\omega^i \tau_i \partial_{t_i}) \end{cases}$
- (5) $\Delta_{\omega_r} \dots \Delta_{\omega_1} Y(z; \tau) = \mathbb{A}_{\omega_1} \dots \mathbb{A}_{\omega_r} Y(z; \tau)$

- Covers a huge range of applications: *singular ODEs; difference equations; resonant vector fields; resonant or identity tangent diffeos of $\mathbb{C}^\nu$.*
- Often deals with situations that are beyond the reach of geometric methods.
- Keeps the Analysis part down to a minimum.

5. Singular & and singularly perturbed system.

Consider this model instance of a *doubly singular* differential system:

$$0 = \epsilon t^2 \partial_t y^i + \lambda_i y^i + b^i(t, \epsilon, y^1, \dots, y^\nu) \quad (1 \leq i \leq \nu) \quad \begin{cases} t \sim 0 \text{ (variable)} \\ \epsilon \sim 0 \text{ (parameter)} \end{cases}$$

It is advisable, both technically and theoretically, to change to the problem's '*critical variables*' z and '*critical parameter*' x , i.e. to set

$$z := 1/t \sim \infty \quad , \quad x := 1/\epsilon \sim \infty$$

so as to prepare for working in the conjugate Borel planes ζ and ξ . This leads to the system:

$$\partial_z Y^i = Y^i \left(\lambda_i x + \sum_{\substack{1+n_i \geq 0 \\ n_j \geq 0 \text{ if } j \neq i}} B_n^i(z) Y^n \right) \quad (1 \leq i \leq \nu)$$

with coefficients $B_n^i(z) \in \mathbb{C}\{z^{-1}\}$ analytic at infinity and x -free.

5*. Loose duality equational/coequational.

We assume that the multipliers λ_i are neither resonant and nor quasi-resonant (meaning that the combinations $-\lambda_i + \sum_{n_j \geq 0} n_j \lambda_j$) are all $\neq 0$ and do not approximate 0 abnormally fast). The general solution, with its full set $\{\tau_1, \dots, \tau_\nu\}$ of integration parameters, may be formally expanded in powers of either z^{-1} or x^{-1} :

$$\tilde{Y} = \tilde{Y}(z, x, \tau) \in \mathbb{C}[[z^{-1} \text{ or } x^{-1}]] \otimes \mathbb{C}\{z^{\rho_1} \tau_1 e^{\lambda_1 z x}, \dots, z^{\rho_\nu} \tau_\nu e^{\lambda_\nu z x}\}$$

The "residues" $\rho_i \in \mathbb{C}$ are the coefficient of z^{-1} in $B_0^i(z) = B_{0, \dots, 0}^i(z)$. To get rid of the ramifications z^{ρ_i} (which complicate the formal expansions without adding anything of substance to the Analysis) we shall set not only $\rho_i \equiv 0$ but also $B_0^i(z) \equiv 0$.

There is bound to be a certain kinship between the z - and x -resurgence, since in the special case when

$B_n^i(z) = \beta_n^i/z$ with β_n^i scalar, the variable z and the perturbation parameter x coalesce:

$$\tilde{Y}^i(z, x, \tau) = \tilde{Y}^i(\textcolor{red}{z} \textcolor{red}{x}) + \sum_{n_j \geq 0} \sum_{j \neq i} \tilde{Y}_n^i(\textcolor{red}{z} \textcolor{red}{x}) \tau_i \tau^n e^{(\lambda_i + \langle n, \lambda \rangle) \textcolor{red}{z} \textcolor{red}{x}} \quad (1)$$

with $\tilde{Y}^i(zx)$ and $\tilde{Y}_n^i(zx) \in \mathbb{C}[[zx)^{-1}]]$. A loose kinship, or lax 'duality', survives even in the general case, and justifies the label *equational* for the *z-resurgence* (z being the variable with respect to which we differentiate in our model system) and *co-equational* for the *x-resurgence*.

6. Symmetrizer/alternator moulds.

$$\{S^\bullet \text{ symmetrizer}\} \iff \left\{ \sum_{\omega \in \text{shuffle}(\omega', \omega'')} S^\omega \equiv S^{\omega'} S^{\omega''} \quad \forall \omega', \omega'' \right\}$$

$$\{A^\bullet \text{ alternator}\} \iff \left\{ \sum_{\omega \in \text{shuffle}(\omega', \omega'')} A^\omega \equiv 0 \quad \forall \omega', \omega'' \right\}$$

Let the D_{ω_i} 's be (ordinary) formal derivations. Then:

$$\{S^\bullet \text{ symmetrizer}\} \iff \left\{ \begin{array}{l} 1 + \sum_{1 \leq r} \sum_{\omega_1, \dots, \omega_r} S^{\omega_1, \dots, \omega_r} D_{\omega_r} \dots D_{\omega_1} \\ \text{is a formal automorphism} \end{array} \right.$$

$$\{A^\bullet \text{ alternator}\} \iff \left\{ \begin{array}{l} \sum_{1 \leq r} \sum_{\omega_1, \dots, \omega_r} A^{\omega_1, \dots, \omega_r} D_{\omega_r} \dots D_{\omega_1} \\ \text{is a formal derivation} \end{array} \right.$$

7. Normalisers and resurgence monomials.

Replace the general solution $\widetilde{Y}$ by the information-equivalent but more flexible *normalising* operators $\Theta^{\pm 1}$:

$$\begin{aligned}\Theta &= 1 + \sum_{i_k, n_k}^{1 \leq r} e^{|u|xz} \widetilde{\mathcal{W}}^{(u_1, \dots, u_r)}_{(B_{n_1}^{i_1}, \dots, B_{n_r}^{i_r})}(z, x) \mathbb{D}_{n_r}^{i_r} \dots \mathbb{D}_{n_1}^{i_1} \\ \Theta^{-1} &= 1 + \sum_{i_k, n_k}^{1 \leq r} (-1)^r e^{|u|xz} \widetilde{\mathcal{W}}^{(u_1, \dots, u_r)}_{(B_{n_1}^{i_1}, \dots, B_{n_r}^{i_r})}(z, x) \mathbb{D}_{n_1}^{i_1} \dots \mathbb{D}_{n_r}^{i_r} \\ \text{with} \quad &\begin{cases} u_k := \langle n_k, \lambda \rangle, & \mathbb{D}_{n_k}^{i_k} := \tau^{n_k} \tau^{i_k} \partial_{\tau_{i_k}} \\ 1 \leq i_k \leq \nu, & \tau_k^n \tau_{i_k} \in \tau^{\mathbb{N}} \end{cases}\end{aligned}$$

and with 'monomials' $\widehat{\mathcal{W}}^\bullet$ inductively defined by

$$(\partial_z + |u|x) \widetilde{\mathcal{W}}^{(u_1, \dots, u_r)}_{(B_{n_1}^{i_1}, \dots, B_{n_r}^{i_r})}(z, x) = -\widetilde{\mathcal{W}}^{(u_1, \dots, u_{r-1})}_{(B_{n_1}^{i_1}, \dots, B_{n_{r-1}}^{i_{r-1}})}(z, x) B_{n_r}^{i_r}(z)$$

Or to lighten notations:

$$(\partial_z + |u|x) \widetilde{\mathcal{W}}^{(u_1, \dots, u_r)}_{(b_1, \dots, b_r)}(z, x) = -\widetilde{\mathcal{W}}^{(u_1, \dots, u_{r-1})}_{(b_1, \dots, b_{r-1})}(z, x) b_r(z)$$

7*. Normalisers and resurgence monomials.

Since $\widetilde{\mathcal{W}}^\bullet$ is *symmetr*al, the operators Θ and Θ^{-1} are (mutually inverse) formal automorphisms of $\mathbb{C}[[\boldsymbol{\tau}]] := \mathbb{C}[[\tau_1, \dots, \tau_\nu]]$:

$$\Theta^{\pm 1}(\tilde{\varphi}_1(\boldsymbol{\tau}), \tilde{\varphi}_2(\boldsymbol{\tau})) \equiv (\Theta^{\pm 1}\tilde{\varphi}_1(\boldsymbol{\tau}))(\Theta^{\pm 1}\tilde{\varphi}_2(\boldsymbol{\tau})) \quad (\tilde{\varphi}_i \in \mathbb{C}[[\boldsymbol{\tau}]])$$

Moreover, they exchange the general solution $\textcolor{red}{Y}$ of our model system and the elementary general solution $\textcolor{blue}{Y}_{\text{nor}}$ of the corresponding (linear) normal system:

$$\begin{aligned} \partial_z Y^i &= Y^i (\lambda_i x + \sum B_n^i(z) Y^n) ; \quad Y^i(z, x, \boldsymbol{\tau}) \in \mathbb{C}[[z^{-1}]] \otimes \mathbb{C}\{\cup_i \tau_i e^{\lambda_i x z}\} \\ \partial_z Y_{\text{nor}}^i &= \lambda_i x Y_{\text{nor}}^i ; \quad Y_{\text{nor}}^i(z, x, \boldsymbol{\tau}) = \tau_i e^{\lambda_i x z} \end{aligned}$$

$$\begin{cases} \Theta \textcolor{red}{Y}^i(z, x, \boldsymbol{\tau}) &\equiv Y_{\text{nor}}^i(z, x, \boldsymbol{\tau}) \\ \Theta^{-1} \textcolor{blue}{Y}_{\text{nor}}^i(z, x, \boldsymbol{\tau}) &\equiv \textcolor{red}{Y}^i(z, x, \boldsymbol{\tau}) \end{cases}$$

8. Equational resurgence.

$$(\partial_z + |\mathbf{u}|x) \mathcal{W}^{(u_1, \dots, u_r)}_{(b_1, \dots, b_r)}(z, x) = -\mathcal{W}^{(u_1, \dots, u_{r-1})}_{(b_1, \dots, b_{r-1})}(z, x) b_r(z) \quad (2)$$

Under the z -Borel transform $\mathcal{B}_z : z^{-n} \mapsto \frac{\zeta^{n-1}}{(n-1)!}$, $b(z) \mapsto \widehat{b}(\zeta)$, $\mathcal{W}^\bullet(z, x) \mapsto \widehat{\mathcal{W}}^\bullet(\zeta, x)$

the induction rule (2) becomes

$$\widehat{\mathcal{W}}^{(u_1, \dots, u_r)}_{(b_1, \dots, b_r)}(\zeta, x) = \frac{1}{\zeta - |\mathbf{u}|x} \int_0^\zeta \widehat{\mathcal{W}}^{(u_1, \dots, u_{r-1})}_{(b_1, \dots, b_{r-1})}(\zeta_1, x) \widehat{b}_r(\zeta - \zeta_1) d\zeta_1 \quad (3)$$

and readily yields all the information we need: location of singularities, Stokes constants, pattern of z -resurgence:

$$\Delta_{ux} \mathcal{W}^{(u_1, \dots, u_r)}_{(b_1, \dots, b_r)}(z, x) = \sum_{u_1 + \dots + u_i = u} \mathcal{W}^{(u_1, \dots, u_i)}_{(b_1, \dots, b_i)}(x) \mathcal{W}^{(u_{i+1}, \dots, u_r)}_{(b_{i+1}, \dots, b_r)}(z, x) \quad (4)$$

with $\begin{cases} \text{monomials } \mathcal{W}^\bullet(z, x) & \text{symmetrizable \& resurgent in } z \\ \text{monics } \mathcal{W}^\bullet(x) & \text{alternant \& entire function of } x \end{cases}$

9. Co-equational resurgence: four requirements.

Our approach is unabashedly *analytical*, in that it strives to identify and resolve the difficulties **first** at the **most basic level**, i.e. at the level of the monomials $\mathcal{W}^{(u_1, \dots, u_r)}_{(b_1, \dots, b_r)}(z, x)$. But **even at that level**, co-equational resurgence is a hard nut to crack. To completely master it, we shall require four things:

- (i) a symmetral *weighted convolution* product $weco^\bullet$.
- (ii) an alternal *weighted convolution* product $welo^\bullet$.
- (iii) the (closed) rules for *alien-differentiating* $weco^\bullet$ and $welo^\bullet$.
- (iv) the discrete-valued *tessellation coefficients*, which in this new context shall take the place of the continuous-valued Stokes constants.

10. Co-equational resurgence at the monomial level.

Under the x -Borel transform $\mathcal{B}_x : \begin{cases} x^{-n} \mapsto \frac{\xi^{n-1}}{(n-1)!} \\ \mathcal{W}^\bullet(z, x) \mapsto \mathcal{B}_x \mathcal{W}^\bullet(z, \xi) \end{cases}$

things are incomparably more complex than under $\mathcal{B}_z$. The induction rule now assumes the form of a partial differential equation in z and ξ :

$$(\partial_z + |\mathbf{u}| \partial_\xi) \mathcal{B}_x \mathcal{W}^{(u_1, \dots, u_r)}_{(b_1, \dots, b_r)}(z, \xi) = - \mathcal{B}_x \mathcal{W}^{(u_1, \dots, u_{r-1})}_{(b_1, \dots, b_{r-1})}(z, \xi) b_r(z) \quad (5)$$

with for $r \geq 2$ the limit condition : $\mathcal{B}_x \mathcal{W}^{(u_1, \dots, u_r)}_{(b_1, \dots, b_r)}(z, 0) = 0$

For $r = 1$, solving (5) in decreasing powers of x and then applying the Borel transform $x \rightarrow \xi$, we find:

$$\mathcal{B}_x \mathcal{W}^{(u_1)}_{(b_1)}(z, \xi) = - \sum_{n \geq 0} \frac{1}{u_1} \frac{(-\xi/u_1)^n}{n!} \partial_z^n b_1(z) = -\frac{1}{u_1} b_1\left(z - \frac{\xi}{u_1}\right)$$

But for $r \geq 2$ we shall need a suitably defined *weighted convolution*.

11. Symmetral weighted convolution.

For $u_i \in \mathbb{C}$ and $\widehat{c}_i(\xi) \in \mathbb{C}\{x\}$, the following integrals

$$\begin{aligned} \text{weco}^{(u_1)}_{\widehat{c}_1}(\xi) &= \frac{1}{u_1} \widehat{c}_1\left(\frac{\xi}{u_1}\right) \\ \dots\dots\dots \\ \text{weco}^{(u_1, \dots, u_r)}_{\widehat{c}_1, \dots, \widehat{c}_r}(\xi) &= \begin{cases} \int_0^{\theta_*} \widehat{c}_r(\xi_r) d\xi_r \int_{\xi_r}^{\theta_r} \widehat{c}_{r-1}(\xi_{r-1}) d\xi_{r-1} \dots \\ \dots \int_{\xi_4}^{\theta_4} \widehat{c}_3(\xi_3) d\xi_3 \int_{\xi_3}^{\theta_3} \widehat{c}_2(\xi_2) d\xi_2 \widehat{c}_1(\xi_1) \frac{1}{u_1} \end{cases} \\ \text{with} \quad &\begin{cases} u_1 \xi_1 + \dots + u_r \xi_r = \xi \\ \theta_i := (\xi - (u_i \xi_i + \dots + u_r \xi_r))(u_1 + \dots + u_{i-1})^{-1} \\ \theta_* := \xi (u_1 + \dots + u_r)^{-1} \end{cases} \end{aligned}$$

unambiguously define germs $\text{weco}^{(u_1, \dots, u_r)}_{\widehat{c}_1, \dots, \widehat{c}_r}(\xi) \in \mathbb{C}\{\xi\}$ provided that $u_1 + \dots + u_i \neq 0$. The mould $\text{weco}^\bullet$ is **symmetral** relative to the (ordinary) convolution product.

A more symmetric definition reads

$$\text{weco}^{(u_1, \dots, u_r)}_{\widehat{c}_1, \dots, \widehat{c}_r}(\xi) := \int_{W^{u_1, \dots, u_r}} \widehat{c}_1(\xi_1) \dots \widehat{c}_r(\xi_r) d\xi_1 \dots d\xi_r$$

with integration on a contorted multi-path:

$$\mathcal{P}^{u_1, \dots, u_r} = \begin{cases} 0 < \xi_r < \xi_{r-1} < \dots < \xi_2 < \xi_1 \\ (u_1 + \dots + u_i) \xi_i + (u_{i+1} \xi_{i+1} + \dots + u_r \xi_r) < \xi \quad (2 \leq i \leq r) \\ u_1 \xi_1 + \dots + u_r \xi_r = \xi \end{cases}$$

11*. Relevance of the weighted convolution product.

The Borel transforms $x \rightarrow \xi$ of the biresurgent monomials $\mathcal{W}^\bullet$ can be expressed in terms of *weighted convolution* products

$$\mathcal{B}_x \mathcal{W}_{b_1, \dots, b_r}^{(u_1, \dots, u_r)}(z, \xi) = \text{weco}_{\widehat{c}_1, \dots, \widehat{c}_r}^{(u_1, \dots, u_r)}(\xi) \quad \text{with} \quad \widehat{c}_i(\xi) := -b_i(z - \xi)$$

with z chosen close enough to ∞ for $\widehat{c}_i(\xi)$ to be regular at $\xi = 0$.

- Since $\widehat{c}_i(\xi) := -b_i(z - \xi)$, the singularities of the $b_i(z)$ are going to dominate co-equational resurgence.
- We note here the characteristic interference of the multiplicative z -plane and the convolutive ξ -plane.

12. The weighted multiplication behind weighted convolution.

Just as ordinary convolution is the Borel image of ordinary multiplication, weighted convolution **weco** is the Borel image of a weighted multiplication **wemu**:

$$\begin{aligned} c_1(x), \dots, c_r(x) &\xrightarrow{\text{Borel}} \widehat{c}_1(\xi), \dots, \widehat{c}_r(\xi) \\ \text{wemu}^{(u_1, \dots, u_r)}_{c_1, \dots, c_r}(x) &\xrightarrow{\text{Borel}} \text{weco}^{(u_1, \dots, u_r)}_{\widehat{c}_1, \dots, \widehat{c}_r}(\xi) \end{aligned}$$

For $u_j > 0$ and $\Re x$ positive and large, weighted multiplication is defined by the integrals:

$$\text{wemu}^{(u_1, \dots, u_r)}_{c_1, \dots, c_r}(x) := \frac{1}{(2\pi i)^r} \int_{-i\infty}^{+i\infty} \frac{c_1(x_1) \dots c_r(x_r) dx_1 \dots dx_r}{\prod_{i=1}^{i=r} ((u_1 + \dots + u_i)x - (x_1 + \dots + x_i))}$$

Integration is along vertical axes $\Im x_j = \alpha_j < u_j \Re x$ but with α_j large enough for $c_j(x_j)$ to be holomorphic on $\alpha_j \leq \Re x_j$. The definition is then extended for general weights u_i by continuous contour deformation, which is always feasible provided the partial sums $u_1 + \dots + u_j$ remain $\neq 0$.

13. Alternal weighted convolution.

The 'alternat marking' *altmark* is a mould operation:

$$\text{altmark}(M)^{\omega', \omega_i^\dagger, \omega''} := (-1)^{r''} \sum_{\omega''' \in \text{sha}(\omega', \tilde{\omega}'')} M^{\omega''', \omega_i^\dagger}$$

that turns any mould $M^\bullet$ into a *marked* mould $\underline{M}^\bullet$ of alternal type.

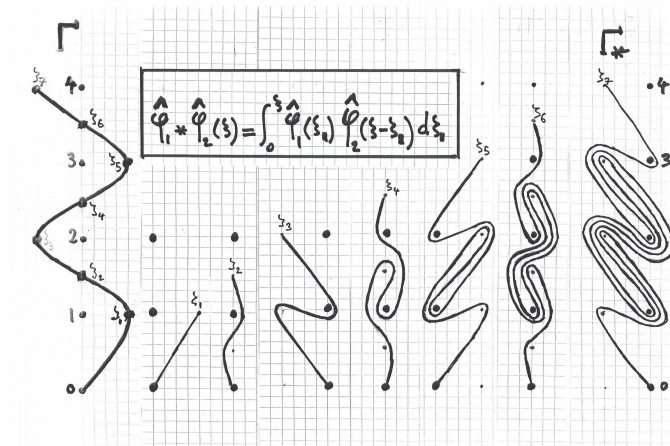
To get closure under alien differentiation, we must supplement the symmetral convolution *weco*[•] by an alternate convolution

welo[•] = *altmark*(*weco*[•]). The corresponding multiplications *wemu*[•] and *welu*[•] have rather similar kernels

$$\begin{cases} \text{wemu}^{\binom{u_1, \dots, u_j, \dots, u_r}{c_1, \dots, c_j, \dots, c_r}}(x) = \frac{1}{(2\pi i)^r} \int S^{\binom{u_1, \dots, u_j, \dots, u_r}{x_1, \dots, x_j, \dots, x_r}}(x) \prod c_i(x_i) dx_i \\ \text{welu}^{\binom{u_1, \dots, u_j^\dagger, \dots, u_r}{c_1, \dots, c_j^\dagger, \dots, c_r}}(x) = \frac{1}{(2\pi i)^r} \int \underline{S}^{\binom{u_1, \dots, u_j^\dagger, \dots, u_r}{x_1, \dots, x_j^\dagger, \dots, x_r}}(x) \prod c_i(x_i) dx_i \end{cases}$$

$$\begin{cases} S^{\binom{u_1, \dots, u_j, \dots, u_r}{x_1, \dots, x_j, \dots, x_r}}(x) = \prod_{i=1}^r ((u_1 + \dots + u_i)x - (x_1 + \dots + x_i))^{-1} \\ \underline{S}^{\binom{u_1, \dots, u_j^\dagger, \dots, u_r}{x_1, \dots, x_j^\dagger, \dots, x_r}}(x) = \begin{cases} (-1)^{r-j} S^{\binom{u_1, \dots, u_{j-1}}{x_1, \dots, x_{j-1}}}(x) S^{\binom{u_r, \dots, u_{j+1}}{x_r, \dots, x_{j+1}}}(x) \times \\ ((u_1 + \dots + u_r)x - (x_1 + \dots + x_r))^{-1} \end{cases} \end{cases}$$

14 Impracticability of the integration multipaths.



Even for ordinary convolution we get impossibly contorted paths. The position is still worse with the *weighted multipaths*. Hence the need for a combinatorial approach.

15. Hyperlogarithmic monomials: stability and density.

We are facing here a highly unusual but inescapable interference of two structures:

- (i) the *multiplicative* structure, which leaves the singularities in place,
- (ii) the *convolutive* structure, which *adds* singularities, in the sense that:
(singularity over ω_1)*(singularity over ω_2) $\Rightarrow$ (singularities over $\omega_1 + \omega_2$).

Then, messing up things still further, we must contend with the *weighted* convolution *weco*, which also *adds* singularities, but via weighted rather than straightforward sums. This forces us to juggle two systems of notation:

- *incremental*, with sequences $(\omega_1, \dots, \omega_r)$ $(\omega_i = \alpha_i - \alpha_{i-1})$
- *positional*, with sequences $[\alpha_1, \dots, \alpha_r]$ $(\alpha_i = \omega_1 + \dots + \omega_i)$

The ideal tool for understanding this hybrid structure is the *hyperlogarithms*, with their *two encodings* (*positional* and *incremental*) their stability under *two products* (ordinary *pointwise multiplication* and *convolution*) and *two sets of exotic derivations* and, not least, their *density* property: any given resurgent function in the Borel plane is the limit, uniformly on any compact set of its Riemann surface, of a suitable series of hyperlogarithms. Here are the main definitions and properties:

15*. Hyperlogarithmic monomials: dimorphy.

$$\widehat{\mathcal{V}}^{[\alpha_1, \dots, \alpha_r]}(\tau) := \int_0^\tau \frac{d\tau_r}{\tau_r - \alpha_r} \cdots \int_0^{\tau_3} \frac{d\tau_2}{\tau_2 - \alpha_2} \int_0^{\tau_2} \frac{d\tau_1}{\tau_1 - \alpha_1}$$

$$\widehat{\mathcal{V}}^{\omega_1, \dots, \omega_r}(\tau) \equiv \widehat{\mathcal{V}}^{[\alpha_1, \dots, \alpha_r]}(\tau) \quad \text{with} \quad \alpha_i \equiv \omega_1 + \dots + \omega_i \quad (\forall i)$$

To express the multiplication-convolution dimorphy we require the *upper convolution* $\widehat{*}$, which has the same unit 1 as pointwise multiplication. Its definition is: $(\widehat{\varphi}_1 \widehat{*} \widehat{\varphi}_2)(\tau) := \int_0^\tau \widehat{\varphi}_1(\tau_1) \widehat{\varphi}_2(\tau - \tau_1) d\tau_1$

$$\times \text{-symmetry} : \quad (\widehat{\mathcal{V}}^{[\alpha']} \cdot \widehat{\mathcal{V}}^{[\alpha'']})(\tau) \equiv \sum_{\alpha \in \text{sha}(\alpha', \alpha'')} \widehat{\mathcal{V}}^{[\alpha]}(\tau) \quad (6)$$

$$\widehat{*} \text{-symmetry} : \quad (\widehat{\mathcal{V}}^{\omega'} \widehat{*} \widehat{\mathcal{V}}^{\omega''})(\tau) \equiv \sum_{\omega \in \text{sha}(\omega', \omega'')} \widehat{\mathcal{V}}^{\omega}(\tau) \quad (7)$$

(6) says that $\widehat{\mathcal{V}}^{[\bullet]}$ is symmetral relative to pointwise multiplication.

(7) says that $\widehat{\mathcal{V}}^{\bullet}$ is symmetral relative to the convolution $\widehat{*}$.

15**. Hyperlogarithmic monomials and monics.

The **hyperlogarithmic monomials** $\tilde{v}^\bullet$ most useful in the present context are defined by:

$$\tilde{v}^{\omega_1, \dots, \omega_r}(\zeta) := \frac{1}{\zeta - (\omega_1 + \dots + \omega_r)} \int_0^\zeta \frac{d\zeta_{r-1}}{\zeta_{r-1} - (\omega_1 + \dots + \omega_{r-1})} \dots \int_0^{\zeta_2} \frac{d\zeta_1}{\zeta_1 - \omega_1}$$

and verify

$$\begin{cases} \tilde{v}^{\omega'}(z) \cdot \tilde{v}^{\omega''}(z) \equiv \sum_{\omega \in \text{sha}(\omega', \omega'')} \tilde{v}^\omega(z) \\ (\tilde{v}^{\omega'} * \tilde{v}^{\omega''})(\tau) \equiv \sum_{\omega \in \text{sha}(\omega', \omega'')} \tilde{v}^\omega(\zeta) \end{cases}$$

The corresponding **hyperlogarithmic monics** $v^\bullet$ are defined inductively by:

$$\Delta_{\omega_1 + \dots + \omega_r} v^{\omega_1, \dots, \omega_r}(z) = v^{\omega_1, \dots, \omega_r} + \sum_{\omega_{i+1} + \dots + \omega_r = 0} v^{\omega_1, \dots, \omega_i} v^{\omega_{i+1}, \dots, \omega_r}(z) \quad (8)$$

and verify the alternility relation $\sum_{\omega \in \text{sha}(\omega', \omega'')} v^\omega \equiv 0$. They are univalued, piecewise analytic functions of their indices ω_j .

15***. Hyperlogarithmic monomials and monics.

Index differentiation for the hyperlogarithmic monomials:

$$\begin{aligned}\omega_1(\partial_{\omega_1} + z) \mathcal{V}^{\omega_1, \dots, \omega_r}(z) &= -\mathcal{V}^{\omega_1 + \omega_2, \dots, \omega_r}(z) \\ \omega_j(\partial_{\omega_j} + z) \mathcal{V}^{\omega_1, \dots, \omega_r}(z) &= +\mathcal{V}^{\omega_1, \dots, \omega_{j-1} + \omega_j, \dots, \omega_r}(z) - \mathcal{V}^{\omega_1, \dots, \omega_j + \omega_{j+1}, \dots, \omega_r}(z) \\ \omega_r(\partial_{\omega_r} + z) \mathcal{V}^{\omega_1, \dots, \omega_r}(z) &= +\mathcal{V}^{\omega_1, \dots, \omega_{r-1} + \omega_r}(z) - \mathcal{V}^{\omega_1, \dots, \omega_{r-1}}(z) \\ z(\partial_z + |\omega|) \mathcal{V}^{\omega_1, \dots, \omega_r}(z) &= -\mathcal{V}^{\omega_1, \dots, \omega_{r-1}}(z)\end{aligned}$$

Index differentiation for the hyperlogarithmic monics:

$$\begin{aligned}\omega_1 \partial_{\omega_1} V^{\omega_1, \dots, \omega_r} &= -V^{\omega_1 + \omega_2, \dots, \omega_r} \\ \omega_j \partial_{\omega_j} V^{\omega_1, \dots, \omega_r} &= +V^{\omega_1, \dots, \omega_{j-1} + \omega_j, \dots, \omega_r} - V^{\omega_1, \dots, \omega_j + \omega_{j+1}, \dots, \omega_r} \\ \omega_r \partial_{\omega_r} V^{\omega_1, \dots, \omega_r} &= +V^{\omega_1, \dots, \omega_{r-1} + \omega_r}\end{aligned}$$

Jump rules for the hyperlogarithmic monics:

The monics $V^\bullet$ are univalued, piecewise analytic functions with cuts along the hypersurfaces $\frac{\omega_1 + \dots + \omega_j}{\omega_{j+1} + \dots + \omega_r} V^{\omega_1, \dots, \omega_r} \in \mathbb{R}^+$ and determination discontinuities given by the *jump formula*:

$$\begin{cases} D \frac{\omega_1 + \dots + \omega_j}{\omega_{j+1} + \dots + \omega_r} V^{\omega_1, \dots, \omega_r} \equiv 2\pi i V^{\omega_1, \dots, \omega_j} V^{\omega_{j+1}, \dots, \omega_r} \\ D_x F(x) := \lim_{\epsilon \rightarrow 0} (F(x + i\epsilon) - F(x - i\epsilon)) \end{cases} \quad (t, \epsilon \in \mathbb{R}^+)$$

16 Weighted convolution with polar inputs.

Setting $\widehat{\mathcal{S}}^{(u_1, \dots, u_r)}_{(v_1, \dots, v_r)}(\xi) := \text{weco}^{(u_1, \dots, u_r)}_{(\widehat{c}_1, \dots, \widehat{c}_r)}(\xi)$ with $\widehat{c}_i(\xi) := \frac{1}{\xi - v_i}$, we get

$$\begin{aligned} \mathcal{S}^{(u_1)}_{(v_1)}(x) &:= \mathcal{V}^{u_1 v_1}(x) \\ \mathcal{S}^{(u_1, u_2)}_{(v_1, v_2)}(x) &:= \begin{cases} +\mathcal{V}^{u_1 v_1, u_2 v_2}(x) \\ -\mathcal{V}^{(u_1+u_2) v_1, u_2 (v_2-v_1)}(x) \\ +\mathcal{V}^{(u_1+u_2) v_2, u_1 (v_1-v_2)}(x) \end{cases} \\ \mathcal{S}^{(u_1, u_2, u_3)}_{(v_1, v_2, v_3)}(x) &:= \begin{cases} +\mathcal{V}^{u_1 v_1, u_2 v_2, u_3 v_3}(x) \\ +\mathcal{V}^{u_1 v_1, (u_2+u_3) v_3, u_2 (v_2-v_3)}(x) \\ -\mathcal{V}^{u_1 v_1, (u_2+u_3) v_2, u_3 (v_3-v_2)}(x) \\ +\mathcal{V}^{(u_1+u_2) v_2, u_1 (v_1-v_2), u_3 v_3}(x) \\ -\mathcal{V}^{(u_1+u_2) v_1, u_2 (v_2-v_1), u_3 v_3}(x) \\ +\mathcal{V}^{(u_1+u_2) v_2, u_3 v_3, u_1 (v_1-v_2)}(x) \\ -\mathcal{V}^{(u_1+u_2) v_1, u_3 v_3, u_2 (v_2-v_1)}(x) \\ +\mathcal{V}^{(u_1+u_2+u_3) v_1, (u_2+u_3) (v_2-v_1), u_3 (v_3-v_2)}(x) \\ -\mathcal{V}^{(u_1+u_2+u_3) v_1, (u_2+u_3) (v_3-v_1), u_2 (v_2-v_3)}(x) \\ +\mathcal{V}^{(u_1+u_2+u_3) v_1, u_3 (v_3-v_1), u_2 (v_2-v_1)}(x) \\ -\mathcal{V}^{(u_1+u_2+u_3) v_2, u_1 (v_1-v_2), u_3 (v_3-v_2)}(x) \\ -\mathcal{V}^{(u_1+u_2+u_3) v_2, u_3 (v_3-v_2), u_1 (v_1-v_2)}(x) \\ +\mathcal{V}^{(u_1+u_2+u_3) v_3, u_1 (v_1-v_3), u_2 (v_2-v_3)}(x) \\ -\mathcal{V}^{(u_1+u_2+u_3) v_3, (u_1+u_2) (v_1-v_3), u_2 (v_2-v_1)}(x) \\ +\mathcal{V}^{(u_1+u_2+u_3) v_3, (u_1+u_2) (v_2-v_3), u_1 (v_1-v_2)}(x) \end{cases} \end{aligned}$$

$\widehat{\mathcal{S}}^{(u_1, \dots, u_r)}_{(v_1, \dots, v_r)}(\xi)$ has $r!! := 1.3.5 \dots (2r-1)$ hyperlogarithmic summands.

17. Weighted convolution with hyperlogarithmic inputs.

The weighted convolution of r hyperlogs of depths $d_1, \dots, d_r$ is a sum of $\mu(d_1, \dots, d_r)$ hyperlogs each of depth $\sum d_i$. The number $\mu(\bullet)$ tends to be huge. Thus:

$\mu(\overbrace{1, \dots, 1}^{r \text{ times}})$	=	$1.3.5 \dots (2r-1)$	=	$r!!$	<i>polar inputs</i>
$\mu(5, 5, 5)$	=	29 135 106	$\sim$	29 10^6	<i>hyperlog. inputs</i>
$\mu(4, 5, 6)$	=	22 855 560	$\sim$	23 10^6	
$\mu(6, 5, 4)$	=	23 963 940	$\sim$	24 10^6	
$\mu(4, 4, 4, 4)$	=	10 050 665 625	$\sim$	10 10^9	
$\mu(1, 3, 5, 7)$	=	349 098 750	$\sim$	0.4 10^9	
$\mu(7, 5, 3, 1)$	=	539 188 650	$\sim$	0.5 10^9	
$\mu(3, 3, 3, 3, 3)$	=	60 575 515 000	$\sim$	60 10^9	
$\mu(1, 2, 3, 4, 5)$	=	6 067 061 000	$\sim$	6 10^9	
$\mu(5, 4, 3, 2, 1)$	=	9 641 071 440	$\sim$	10 10^9	

Thus, for a linear system as simple as (*):

$$(*) \quad (\partial_z + \omega_i x) Y_i(z, x) = Y_{i-1}(z, x) b_i(z) \quad \begin{cases} (1 \leq i \leq 4, Y_0 \equiv 1) \\ b_i \text{ hyperlog. of depth } 4 \end{cases}$$

we have only 4 singularities in the ζ -plane, but close to 10^{10} in the ξ -plane.

18. Disappearance of the Stokes constants.

Applying the rules $\begin{cases} \Delta_{\omega_0} \mathcal{V}^{\omega_1, \dots, \omega_r}(x) = \sum_{\omega_1 + \dots + \omega_i = \omega_0} \mathcal{V}^{\omega_1, \dots, \omega_i} \mathcal{V}^{\omega_{i+1}, \dots, \omega_r}(x) \\ \mathcal{V}^{\omega_1} \equiv 1, \quad \mathcal{V}^{\omega_1, \omega_2} = \text{suitable determination of } \log \frac{\omega_2}{\omega_1} \end{cases}$

to the weighted convolution product: $S^{(\frac{u_1}{v_1}, \frac{u_2}{v_2})}(x) := \begin{cases} +\mathcal{V}^{u_1 v_1, u_2 v_2}(x) \\ -\mathcal{V}^{(u_1+u_2)v_1, u_2(v_2-v_1)}(x) \\ +\mathcal{V}^{(u_1+u_2)v_2, u_1(v_1-v_2)}(x) \end{cases}$

we find that the continuous-valued Stokes constants disappear. Indeed:

$$\begin{aligned} \Delta_{u_1 v_1} S^{(\frac{u_1}{v_1}, \frac{u_2}{v_2})}(x) &= \mathcal{V}^{u_2 v_2}(x) = S^{(\frac{u_2}{v_2})}(x) \\ \Delta_{(u_1+u_2) v_1} S^{(\frac{u_1}{v_1}, \frac{u_2}{v_2})}(x) &= -\mathcal{V}^{u_2(v_2-v_1)}(x) = -S^{(\frac{u_2}{v_2-v_1})}(x) \\ \Delta_{(u_1+u_2) v_2} S^{(\frac{u_1}{v_1}, \frac{u_2}{v_2})}(x) &= \mathcal{V}^{u_1(v_1-v_2)}(x) = S^{(\frac{u_1}{v_1-v_2})}(x) \\ \Delta_{u_1 v_1 + u_2 v_2} S^{(\frac{u_1}{v_1}, \frac{u_2}{v_2})}(x) &= \text{tes}(\frac{u_1}{v_1}, \frac{u_2}{v_2}) = \log \frac{u_2 v_2}{u_1 v_1} - \log \frac{u_2(v_2-v_1)}{(u_1+u_2)v_1} + \log \frac{u_1(v_1-v_2)}{(u_1+u_2)v_2} \end{aligned}$$

with a locally constant tessellation coefficient $\text{tes}(\frac{u_1}{v_1}, \frac{u_2}{v_2}) \in \{0, \pm 2\pi i\}$.

The phenomenon is general and holds for all values of r .

Caveat: The disappearance of Stokes constants is incomplete in the case of v_i -repetitions.

19. The tessellation coefficients: hyperlog. expansions.

At depths $r \geq 3$, local constancy still holds: differentiate the following $\text{tes}^\bullet$ in any u_i or any v_i , and you get ... 0.

$$\text{tes}^{\binom{u_1, u_2, u_3}{v_1, v_2, v_3}} := \left\{ \begin{array}{l} +V \textcolor{blue}{u}_1 \textcolor{red}{v}_1, \textcolor{blue}{u}_2 \textcolor{red}{v}_2, \textcolor{blue}{u}_3 \textcolor{red}{v}_3 \\ +V \textcolor{blue}{u}_1 \textcolor{red}{v}_1, (\textcolor{blue}{u}_2 + \textcolor{blue}{u}_3) \textcolor{red}{v}_3, \textcolor{blue}{u}_2 (\textcolor{red}{v}_2 - \textcolor{red}{v}_3) \\ -V \textcolor{blue}{u}_1 \textcolor{red}{v}_1, (\textcolor{blue}{u}_2 + \textcolor{blue}{u}_3) \textcolor{red}{v}_2, \textcolor{blue}{u}_3 (\textcolor{red}{v}_3 - \textcolor{red}{v}_2) \\ +V (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2) \textcolor{red}{v}_2, \textcolor{blue}{u}_1 (\textcolor{red}{v}_1 - \textcolor{red}{v}_2), \textcolor{blue}{u}_3 \textcolor{red}{v}_3 \\ -V (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2) \textcolor{red}{v}_1, \textcolor{blue}{u}_2 (\textcolor{red}{v}_2 - \textcolor{red}{v}_1), \textcolor{blue}{u}_3 \textcolor{red}{v}_3 \\ +V (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2) \textcolor{red}{v}_2, \textcolor{blue}{u}_3 \textcolor{red}{v}_3, \textcolor{blue}{u}_1 (\textcolor{red}{v}_1 - \textcolor{red}{v}_2) \\ -V (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2) \textcolor{red}{v}_1, \textcolor{blue}{u}_3 \textcolor{red}{v}_3, \textcolor{blue}{u}_2 (\textcolor{red}{v}_2 - \textcolor{red}{v}_1) \\ +V (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2 + \textcolor{blue}{u}_3) \textcolor{red}{v}_1, (\textcolor{blue}{u}_2 + \textcolor{blue}{u}_3) (\textcolor{red}{v}_2 - \textcolor{red}{v}_1), \textcolor{blue}{u}_3 (\textcolor{red}{v}_3 - \textcolor{red}{v}_2) \\ -V (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2 + \textcolor{blue}{u}_3) \textcolor{red}{v}_1, (\textcolor{blue}{u}_2 + \textcolor{blue}{u}_3) (\textcolor{red}{v}_3 - \textcolor{red}{v}_1), \textcolor{blue}{u}_2 (\textcolor{red}{v}_2 - \textcolor{red}{v}_3) \\ +V (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2 + \textcolor{blue}{u}_3) \textcolor{red}{v}_1, \textcolor{blue}{u}_3 (\textcolor{red}{v}_3 - \textcolor{red}{v}_1), \textcolor{blue}{u}_2 (\textcolor{red}{v}_2 - \textcolor{red}{v}_1) \\ -V (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2 + \textcolor{blue}{u}_3) \textcolor{red}{v}_2, \textcolor{blue}{u}_1 (\textcolor{red}{v}_1 - \textcolor{red}{v}_2), \textcolor{blue}{u}_3 (\textcolor{red}{v}_3 - \textcolor{red}{v}_2) \\ -V (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2 + \textcolor{blue}{u}_3) \textcolor{red}{v}_2, \textcolor{blue}{u}_3 (\textcolor{red}{v}_3 - \textcolor{red}{v}_2), \textcolor{blue}{u}_1 (\textcolor{red}{v}_1 - \textcolor{red}{v}_2) \\ +V (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2 + \textcolor{blue}{u}_3) \textcolor{red}{v}_3, \textcolor{blue}{u}_1 (\textcolor{red}{v}_1 - \textcolor{red}{v}_3), \textcolor{blue}{u}_2 (\textcolor{red}{v}_2 - \textcolor{red}{v}_3) \\ -V (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2 + \textcolor{blue}{u}_3) \textcolor{red}{v}_3, (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2) (\textcolor{red}{v}_1 - \textcolor{red}{v}_3), \textcolor{blue}{u}_2 (\textcolor{red}{v}_2 - \textcolor{red}{v}_1) \\ +V (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2 + \textcolor{blue}{u}_3) \textcolor{red}{v}_3, (\textcolor{blue}{u}_1 + \textcolor{blue}{u}_2) (\textcolor{red}{v}_2 - \textcolor{red}{v}_3), \textcolor{blue}{u}_1 (\textcolor{red}{v}_1 - \textcolor{red}{v}_2) \end{array} \right.$$

20. The tessellation coefficients: elementary induction.

Local constancy is an invitation to search for a more elementary expression of $\text{tes}^\bullet$.

Limiting hypersurfaces $\mathcal{H}_{i,j}^+ = \{\mathbf{w} \in \mathbb{C}^{2r} ; H_{i,j}(\mathbf{w}) \in \mathbb{R}^+\}$ (there are $r^2 - 1$ of them):

$$H_{i,j}(\mathbf{w}) := Q_{i,j}^*(\mathbf{w}) / Q_{i,j}^{**}(\mathbf{w}) \quad (i - j \neq 0; i, j \in \mathbb{Z}_{r+1})$$

$$Q_{i,j}^*(\mathbf{w}) := \sum_{\text{circ}(i < q \leq j)} u_q^\# (v_q^\# - v_j^\#)$$

$$Q_{i,j}^{**}(\mathbf{w}) := \sum_{\text{circ}(j < q \leq i)} u_q^\# (v_q^\# - v_j^\#) = \langle \mathbf{u}, \mathbf{v} \rangle - Q_{i,j}^*(\mathbf{w})$$

The jump rule for $\text{tes}^\mathbf{w}$: It is only when $\mathbf{w}$ crosses a hypersurface $\mathcal{H}_{i,j}^+$, that $\text{tes}^\mathbf{w}$ can change its value.

Let $\mathbf{w}$ be any point on $\mathcal{H}_{i,j}^+$ and let $\mathbf{w}^+$, $\mathbf{w}^-$ be two points close by, with $\pm \Im H_{i,j}(\mathbf{w}^\pm) > 0$. Then

$$\text{tes}^{\mathbf{w}^+} - \text{tes}^{\mathbf{w}^-} = \text{tes}^{\mathbf{w}^*} \text{tes}^{\mathbf{w}^{**}}$$

$$\text{with } \begin{cases} \mathbf{w}^* := (u_{i+1}^\#, \dots, u_p^\#, \dots, u_j^\#) \\ \quad \quad \quad (v_{i+1}^\# - v_i^\#, \dots, v_p^\# - v_i^\#, \dots, v_j^\# - v_i^\#) & (\text{circ}(i < p \leq j) \in \mathbb{Z}_{r+1}) \\ \mathbf{w}^{**} := (u_{j+1}^\#, \dots, u_q^\#, \dots, u_{i-1}^\#) \\ \quad \quad \quad (v_{j+1}^\# - v_i^\#, \dots, v_q^\# - v_i^\#, \dots, v_{i-1}^\# - v_i^\#) & (\text{circ}(j < q < i) \in \mathbb{Z}_{r+1}) \end{cases}$$

20*. The tessellation coefficients: elementary expression.

We fix some $c \in \mathbb{C}^*$ and set $\Re_c : z \in \mathbb{C} \mapsto \Re(cz) \in \mathbb{R}$. Then we define:

$$f_w^{w'} := \langle u', v' \rangle \langle u, v \rangle^{-1}, \quad g_w^{w'} := \langle u', \mathbb{R}_\theta v' \rangle \langle u, \mathbb{R}_\theta v \rangle^{-1} \quad (9)$$

From these scalars we construct the crucial sign factor sig which takes its values in $\{-1, 0, 1\}$. Here, the abbreviation $si(\cdot)$ stands for $sign(\Im(\cdot))$.

$$\text{sig}^{\mathbf{w}', \mathbf{w}''} = \text{sig}_c^{\mathbf{w}', \mathbf{w}''} := \frac{1}{8} \begin{cases} (\text{si}(f_{\mathbf{w}'}^{\mathbf{w}'} - f_{\mathbf{w}''}^{\mathbf{w}''}) - \text{si}(g_{\mathbf{w}'}^{\mathbf{w}'} - g_{\mathbf{w}''}^{\mathbf{w}''})) \times \\ (1 + \text{si}(f_{\mathbf{w}'}^{\mathbf{w}'} / g_{\mathbf{w}'}^{\mathbf{w}'})) \text{si}(f_{\mathbf{w}'}^{\mathbf{w}'} - g_{\mathbf{w}'}^{\mathbf{w}'})) \times \\ (1 + \text{si}(f_{\mathbf{w}''}^{\mathbf{w}''} / g_{\mathbf{w}''}^{\mathbf{w}''})) \text{si}(f_{\mathbf{w}''}^{\mathbf{w}''} - g_{\mathbf{w}''}^{\mathbf{w}''})) \end{cases} \quad (10)$$

Next, from the pair $(\mathbf{w}', \mathbf{w}'')$ we derive a pair $(\mathbf{w}^*, \mathbf{w}^{**})$ by setting:

$$u^* := u' \quad , \quad v^* := v' \langle u, v \rangle^{-1} \Im g_w^{w'} - \Re_c v' \langle u, \Re_c v \rangle^{-1} \Im f_w^{w'} \quad (11)$$

$$u^{**} := u'', \quad v^{**} := v'' \langle u, v \rangle^{-1} \Im g_w^{w''} - \Re v'' \langle u, \Re v \rangle^{-1} \Im f_w^{w''} \quad (12)$$

or more symmetrically:

$$\mathbf{v}^* := \det \left(\begin{array}{c} \frac{\mathbf{v}'}{\langle \mathbf{u}, \mathbf{v}' \rangle} \\ \Im \frac{\langle \mathbf{u}', \mathbf{v}' \rangle}{\langle \mathbf{u}, \mathbf{v}' \rangle} \end{array} \quad \begin{array}{c} \frac{\Re \mathbf{v}'}{\langle \mathbf{u}, \Re \mathbf{v}' \rangle} \\ \Im \frac{\langle \mathbf{u}', \Re \mathbf{v}' \rangle}{\langle \mathbf{u}, \Re \mathbf{v}' \rangle} \end{array} \right), \quad \mathbf{v}^{**} := \det \left(\begin{array}{c} \frac{\mathbf{v}''}{\langle \mathbf{u}, \mathbf{v}'' \rangle} \\ \Im \frac{\langle \mathbf{u}', \mathbf{v}'' \rangle}{\langle \mathbf{u}, \mathbf{v}'' \rangle} \end{array} \quad \begin{array}{c} \frac{\Re \mathbf{v}''}{\langle \mathbf{u}, \Re \mathbf{v}'' \rangle} \\ \Im \frac{\langle \mathbf{u}', \Re \mathbf{v}'' \rangle}{\langle \mathbf{u}, \Re \mathbf{v}'' \rangle} \end{array} \right)$$

Lastly, from all these ingredients, we construct an auxilliary bimould $\text{urtes}_{\text{nor}}^\bullet$ by setting:

$$\text{urtes}_{\text{nor}}^w = \sum_{w', w''=w} \text{sig}^{w'w''} \text{tes}_{\text{nor}}^{w*} \text{tes}_{\text{nor}}^{w**} \quad ((w', w'') \neq (w^*, w^{**})) \quad (13)$$

Then the tessellation bimould can be inductively calculated from:

$$\text{tes}_{\text{nor}}^{\bullet} = \sum_{0 \leq n \leq r(\bullet)} \text{push}^n \text{urtes}_{\text{nor}}^{\bullet} \quad (\forall c \in \mathbb{C}^*) \quad (14)$$

21. The tessellation coefficients. Main properties.

P_1 : $\text{tes}^\bullet$ is invariant under the involution *swap* and the iden-potent *push*:

$$\text{swap}.A \begin{pmatrix} u_1, \dots, u_r \\ v_1, \dots, v_r \end{pmatrix} = A \begin{pmatrix} v_r, \dots, v_3 - v_4, v_2 - v_3, v_1 - v_2 \\ u_1 + \dots + u_r, \dots, u_1 + u_2 + u_3, u_1 + u_2, u_1 \end{pmatrix} \quad (\text{swap}^2 = \text{id})$$

$$\text{push}.A \begin{pmatrix} u_1, \dots, u_r \\ v_1, \dots, v_r \end{pmatrix} = A \begin{pmatrix} -u_1 \dots - u_r, u_1, u_2, \dots, u_{r-1} \\ -v_r, v_1 - v_r, v_2 - v_r, \dots, v_{r-1} - v_r \end{pmatrix} \quad (\text{push}^{r+1} = \text{id})$$

P_2 : the bimould $\text{tes}^\bullet$ is *bialternal*, i.e. alternal and of alternal *swappee*.

P_3 : $\text{tes}_{nor}^\bullet$ assumes all its sole values in $\mathbb{Z}$ and $|\text{tes}^{w_1, \dots, w_r}| < (r-1)!(r+1)!$ (far from sharp)

P_4 : As r increases, the set where $\text{tes}^\bullet \neq 0$ has surprisingly small Lebesgue measure.

$$\begin{array}{ll} \text{tes}^{w_1} \equiv 1 & \\ \text{tes}^{w_1, w_2} \in \{0, \pm 1\} & \mathcal{P}(\text{tes}^{w_1, w_2} = \pm 1) \sim 0.21 \\ \text{tes}^{w_1, w_2, w_3} \in \{0, \pm 1\} & \mathcal{P}(\text{tes}^{w_1, w_2, w_3} = \pm 1) \sim 0.026 \\ \text{tes}^{w_1, \dots, w_4} \in \{0, \pm 1, \pm 2\} & \mathcal{P}(\text{tes}^{w_1, \dots, w_4} = \pm 1) \sim 0.0037 \quad \mathcal{P}(\text{tes}^{w_1, \dots, w_4} = \pm 2) \sim 0.0000037 \end{array}$$

P_5 : in presence of vanishing u_i -sums, we no longer have local constancy in the v_j 's.

P_6 : conversely, in presence of v_i -repetitions, we no longer have local constancy in the u_j 's.

P_7 : in the *semi-real* case, i.e. when *either* all u_i 's or all v_i 's are aligned with the origin, the tessellation coefficients altogether exit the picture, since in that case $\text{tes}^{w_1, \dots, w_r} \equiv 0$ as soon as $2 \leq r$.

22. Weighted convolution under alien derivations.

The only alien derivatives Δ_{ω_0} acting effectively on $\text{wemu} \begin{pmatrix} u_1 & \dots & u_r \\ c_1 & \dots & c_r \end{pmatrix} (x)$ correspond either to simple ($s = 1$) or composite ($s > 1$) indices ω_0 of the form

$$\omega_0 = |u^1| v_{i_1}^1 + \dots + |u^s| v_{i_s}^s \quad \text{with} \quad \begin{cases} u^1 u^2 \dots u^{s-1} u^s u^* = u \\ \Delta_{v_{i_k}^k c_{i_k}^k} \neq 0 \text{ and } \begin{pmatrix} u_{i_k}^k \\ c_{i_k}^k \end{pmatrix} \in \begin{pmatrix} u^k \\ c^k \end{pmatrix} \end{cases}$$

with each factor sequence $\begin{pmatrix} u^k \\ c^k \end{pmatrix}$ re-indexed for convenience as $\begin{pmatrix} u_1^k, \dots, u_{r_k}^k \\ c_1^k, \dots, c_{r_k}^k \end{pmatrix}$. The corresponding alien derivative is given by:

$$\Delta_{\omega_0} \text{wemu} \begin{pmatrix} u_1 & \dots & u_r \\ c_1 & \dots & c_r \end{pmatrix} (x) = \begin{cases} \sum_{\check{v}_j^k \text{ over } v_{i_k}^k} \text{Tes} \begin{pmatrix} |u^1| & \dots & |u^s| \\ \check{v}_1^1, \dots, \check{v}_{r_1}^1 & \dots & \check{v}_1^s, \dots, \check{v}_{r_s}^s \end{pmatrix} \times \\ \begin{pmatrix} u_1^k & \dots & u_{r_k}^k \\ \check{v}_1^k c_1^k & \dots & \Delta_{\check{v}_{i_k}^k c_{i_k}^k}^\dagger, \dots, \check{v}_{r_k}^k c_{r_k}^k \end{pmatrix} \\ \prod_{1 \leq k \leq s} \text{welu} \\ \begin{pmatrix} u_1^* & \dots & u_{r_*}^* \\ c_1^* & \dots & c_{r_*}^* \end{pmatrix} \\ \text{wemu} \begin{pmatrix} u_1^* & \dots & u_{r_*}^* \\ c_1^* & \dots & c_{r_*}^* \end{pmatrix} (x) \times \end{cases}$$

22*. Weighted convolution under alien derivations.

The only alien derivatives Δ_{ω_0} acting effectively on $\text{welu}_{c_1^1, \dots, c_j^j, \dots, c_r^r}(x)$ correspond either to simple ($s = 1$) or composite ($s > 1$) indices ω_0 of three possible types – initial, final, global. Respectively:

$$\omega_0^{ini} = |u^1| v_{i_1}^1 + \dots + |u^s| v_{i_s}^s \text{ with } \begin{cases} u^1 \dots u^s u^* = u ; & (u_j^j)^\dagger \in (u_{c^*}^*) \\ \Delta_{v_{i_k}^k c_{i_k}^k} \neq 0 \text{ and } (u_{i_k}^k) \in (u_{c^k}^k) \end{cases} \quad (15)$$

$$\omega_0^{fin} = |u^1| v_{i_1}^1 + \dots + |u^s| v_{i_s}^s \text{ with } \begin{cases} {}^*u u^1 \dots u^s = u ; & (u_j^j)^\dagger \in ({}^*u_{c^*}) \\ \Delta_{v_{i_k}^k c_{i_k}^k} \neq 0 \text{ and } (u_{i_k}^k) \in (u_{c^k}^k) \end{cases} \quad (16)$$

$$\omega_0^{glo} = |u^1| v_{i_1}^1 + \dots + |u^s| v_{i_s}^s \text{ with } \begin{cases} u^1 \dots u^s = u \\ \Delta_{v_{i_k}^k c_{i_k}^k} \neq 0 \text{ and } (u_{i_k}^k) \in (u_{c^k}^k) \end{cases} \quad (17)$$

with each factor sequence $(u_{c^k}^k)$ re-indexed for convenience as $(u_{c_1^k}^k, \dots, u_{r_k^k}^k)$. The corresponding alien derivatives are given by:

22**. Weighted convolution under alien derivations.

$$\Delta_{\omega_0^{ini} \text{ welu}} \left(\begin{smallmatrix} u_1 & \dots & (u_j)^\dagger & \dots & u_r \\ c_1 & \dots & c_j & \dots & c_r \end{smallmatrix} \right) (x) = \left\{ \begin{array}{l} + \sum_{\check{v}_j^k \text{ over } v_{i_k}^k} \text{Tes} \left(\begin{smallmatrix} |u^1| & \dots & |u^s| \\ \check{v}_1^1, \dots, \check{v}_{r_1}^1 & \dots & \check{v}_1^s, \dots, \check{v}_{r_s}^s \end{smallmatrix} \right) \times \\ \quad \left(\begin{smallmatrix} u_1^k & \dots & (u_{i_k}^k)^\dagger & \dots & u_{r_k}^k \\ \check{v}_1^k c_1^k & \dots & \Delta_{\check{v}_k^k c_{i_k}^k} & \dots & \check{v}_{r_k}^k c_{r_k}^k \end{smallmatrix} \right) \\ \Pi_{1 \leq k \leq s} \text{ welu} \quad (x) \times \\ \text{welu} \left(\begin{smallmatrix} u_1^* & \dots & (u_j)^\dagger & \dots & u_{r_*}^* \\ c_1^* & \dots & c_j & \dots & c_{r_*}^* \end{smallmatrix} \right) (x) \end{array} \right.$$

$$\Delta_{\omega_0^{fin} \text{ welu}} \left(\begin{smallmatrix} u_1 & \dots & (u_j)^\dagger & \dots & u_r \\ c_1 & \dots & c_j & \dots & c_r \end{smallmatrix} \right) (x) = \left\{ \begin{array}{l} - \sum_{\check{v}_j^k \text{ over } v_{i_k}^k} \text{Tes} \left(\begin{smallmatrix} |u^1| & \dots & |u^s| \\ \check{v}_1^1, \dots, \check{v}_{r_1}^1 & \dots & \check{v}_1^s, \dots, \check{v}_{r_s}^s \end{smallmatrix} \right) \times \\ \quad \left(\begin{smallmatrix} u_1^k & \dots & (u_{i_k}^k)^\dagger & \dots & u_{r_k}^k \\ \check{v}_1^k c_1^k & \dots & \Delta_{\check{v}_k^k c_{i_k}^k} & \dots & \check{v}_{r_k}^k c_{r_k}^k \end{smallmatrix} \right) \\ \Pi_{1 \leq k \leq s} \text{ welu} \quad (x) \times \\ \text{welu} \left(\begin{smallmatrix} {}^*u_1 & \dots & (u_j)^\dagger & \dots & {}^*u_{r_*} \\ {}^*c_1 & \dots & c_j & \dots & {}^*c_{r_*} \end{smallmatrix} \right) (x) \end{array} \right.$$

$$\Delta_{\omega_0^{glo} \text{ welu}} \left(\begin{smallmatrix} u_1 & \dots & (u_j)^\dagger & \dots & u_r \\ c_1 & \dots & c_j & \dots & c_r \end{smallmatrix} \right) (x) = \left\{ \begin{array}{l} + \sum_{\check{v}_j^k \text{ over } v_{i_k}^k} \text{Tes} \left(\begin{smallmatrix} |u^1| & \dots & |u^s| \\ \check{v}_1^1, \dots, \check{v}_{r_1}^1 & \dots & \check{v}_1^s, \dots, \check{v}_{r_s}^s \end{smallmatrix} \right) \times \\ \quad \left(\begin{smallmatrix} u_1^k & \dots & (u_{i_k}^k)^\dagger & \dots & u_{r_k}^k \\ \check{v}_1^k c_1^k & \dots & \Delta_{\check{v}_k^k c_{i_k}^k} & \dots & \check{v}_{r_k}^k c_{r_k}^k \end{smallmatrix} \right) \\ \Pi_{1 \leq k \leq s} \text{ welu} \quad (x) \end{array} \right.$$

23. First, Second, Third Bridge equations.

First Bridge equation: $[\Delta_\omega, \Theta^{-1}] = \mathbb{A}_\omega \Theta^{-1}$

with $\Delta_\omega := e^{-\omega z} \Delta_\omega$ (z-resurgence) and $\mathbb{A}_\omega = \sum_{(u_1 + \dots + u_r)x = \omega} W^{(u_1, \dots, u_r)}_{(b_1, \dots, b_r)}(x) \mathbb{D}_{\|u_1} \dots \mathbb{D}_{\|u_r}$

Second Bridge equation: $[\Delta_\omega, \Theta^{-1}] = \mathbb{P}_\omega \Theta^{-1}$

with $\Delta_\omega := e^{-\omega x} \Delta_\omega$ (x-resurgence) and:

$$\begin{cases} \mathbb{P}_\omega &:= \sum \sum_{u_i(z - \alpha_i) = \omega} \text{tes}^{(z - \alpha_1, \dots, z - \alpha_r)} \mathbb{Q}_{[\frac{u_1}{\alpha_1}]} \dots \mathbb{Q}_{[\frac{u_r}{\alpha_r}]} \\ \mathbb{Q}_{[\frac{u_0}{\alpha_0}]} &:= e^{u_0 \alpha_0} \sum \sum_{u_i = u_0} \text{welu}^{(\frac{u_1}{\alpha_0 \cdot c_1}, \dots, (\frac{u_i}{\Delta_{\alpha_0} c_i})^\dagger, \dots, \frac{u_r}{\alpha_0 \cdot c_r})} \mathbb{D}_{\|u_1} \dots \mathbb{D}_{\|u_r} \end{cases} \quad (18)$$

Third Bridge equation: $\Delta_\omega \mathbb{Q}_{[\frac{u_0}{\alpha_0}]} = \begin{cases} + \sum_{u_1 + u_2 = u_0} \mathbb{P}_{\omega, [\frac{u_1}{\alpha_0}]} \mathbb{Q}_{[\frac{u_2}{\alpha_0}]} \\ - \sum_{u_1 + u_2 = u_0} \mathbb{Q}_{[\frac{u_1}{\alpha_0}]} \mathbb{P}_{\omega, [\frac{u_2}{\alpha_0}]} \end{cases}$

with $\mathbb{P}_{\omega, [\frac{u_0}{\alpha_0}]} := \sum_{\sum u_i(\alpha_0 - \alpha_i) = \omega} \sum_{u_i = u_0} \text{tes}^{(\alpha_0 - \alpha_1, \dots, \alpha_0 - \alpha_r)} \mathbb{Q}_{[\frac{u_1}{\alpha_1}]} \dots \mathbb{Q}_{[\frac{u_r}{\alpha_r}]} \quad (19)$

24. BE2 and BE3 in the semi-real and other cases.

The semi-real case: In the important instances when the tessellation coefficients $tes^{w_1}, \dots, w_r$ turn trivial (i.e. $\equiv 1$ for $r = 1$ and $\equiv 0$ for $r \neq 1$), the Third Bridge equation simplifies:

$$(BE3) \quad \Delta_{\omega} \mathbb{Q}_{[\frac{u_0}{\alpha_0}]} = \sum_{u_1+u_2=u_0}^{u_1(\alpha_0-\alpha_1)=\omega} [\mathbb{Q}_{[\frac{u_1}{\alpha_1}]}, \mathbb{Q}_{[\frac{u_2}{\alpha_0}]}] \quad (20)$$

and one can check the equality of the exponential factors on both sides:

- (i) Δ_{ω} carries a factor $e^{-\omega x} = e^{-u_1(\alpha_0-\alpha_1)x}$
- (ii) $\mathbb{Q}_{[\frac{u_0}{\alpha_0}]}$ carries a factor $e^{u_0\alpha_0 x} = e^{(u_1+u_2)\alpha_0 x}$
- (iii) $\mathbb{Q}_{[\frac{u_1}{\alpha_1}]}$ carries a factor $e^{u_1\alpha_1 x}$
- (iv) $\mathbb{Q}_{[\frac{u_2}{\alpha_0}]}$ carries a factor $e^{u_2\alpha_0 x}$

The most general case: In the opposite direction, the results extend to the case of hyperlogarithmic (instead of meromorphic) or even **absolutely general inputs** $b_i(z)$ (and thus $\widehat{c}_i(\xi)$), except that we must switch to a multiple indexation $\alpha_j \rightarrow \check{\alpha}_j$ and that the **BE3** inherits a third term, corresponding to the case $\Delta_{\omega}^{glo} welu^{\bullet}$. We get:

$$(BE3) \quad \Delta_{\omega} \mathbb{Q}_{[\frac{u_0}{\alpha_0}]} = \begin{cases} + \sum_{u_1+u_2=u_0} \mathbb{P}_{\omega, [\frac{u_1}{\check{\alpha}_0}]} \mathbb{Q}_{[\frac{u_2}{\check{\alpha}_0}]} \\ - \sum_{u_1+u_2=u_0} \mathbb{Q}_{[\frac{u_1}{\check{\alpha}_0}]} \mathbb{P}_{\omega, [\frac{u_2}{\check{\alpha}_0}]} \\ + \mathbb{P}_{\omega, [\frac{u_0}{\check{\alpha}_0}]} \end{cases} \quad (21)$$

25. Equational vs co-equational resurgence.

- To produce *equational resurgence*, the coefficients $b_i(z)$ need only be analytic germs at ∞ (and verify a uniformity condition).
- To produce *co-equational resurgence*, the $b_i(z)$ must be endlessly continuable over the Riemann sphere (with a uniformity condition).
- **BE1** : The index reservoir Ω_1 is rigidly determined by the *multipliers* λ_i . The Stokes constants are entire functions of x .
- **BE2** : The index reservoir Ω_2 depends linearly on z and the singular points of the coefficients $b_i(z)$. The Stokes constants disappear (*qualification here*) and get replaced by discrete-valued tessellation coefficients. BE2 involves $wemu^\bullet$ and $welu^\bullet$.
- **BE3** : The index reservoir Ω_3 and the tessellation coefficients cease to depend on z . BE3 involves only $welu^\bullet$.

25*. Complexity of co-equational resurgence.

At the end of this tour of coequational resurgence, we find a clear four level stratification:

- *The atomic level*, populated by objects such as simple poles or hyperlogarithms.
- *The molecular level*, consisting of huge clusters of atoms, with unsuspected emergent properties.
- *The microscopic level*, consisting of derivation operators $\mathbb{Q}_\omega$, usually infinite chains of molecules contracted by elementary derivation operators.
- *The macroscopic level*, consisting of new derivation operators $\mathbb{P}_\omega$ assembled from the earlier $\mathbb{Q}_\omega$.
- The passage from the atomic to the molecular level is mediated on the Analysis side by *weighted convolution* and on the combinatorial side by the *scrambling transform*.
- The passage from the molecular to the microscopic level is rather mechanical – mere growth by accumulation.
- The passage from the microscopic to the macroscopic level, arguably the most interesting of the three, is mediated by the *tessellation coefficients*. While much is known about them, it would seem that just as much remains to be discovered.

When we have both z - and x -resurgence, there can be no hesitation.
But in theoretical physics, the x -resurgence is often all we have.

Cf the July 2015 CERN conference on resurgence (Geneva) or the June 2019 IHES conference (Paris).

26. Emergent properties: the flection structure.

When looking at the *weighted convolution* products of poles or hyperlogarithms, we just caught a glimpse of the strange ways in which the u_i - and v_i -indices interact, as well as of the numerous symmetries and invariance properties of the related *tessellation coefficients*.

By following this lead, I stumbled on a whole new algebraic structure – the so-called *flection structure* – with the Lie algebra **ARI** and the group **GARI** as its center piece. This *flection structure* in turn proved quite helpful in the investigation of *arithmetical dimorphy*, i.e. in the study of those $\mathbb{Q}$ -rings of transcendental numbers (such as the *multizetas*) that possess *two* natural (and independent) ‘*multiplication tables*’.

So we have here this minor miracle of a beautiful algebraic structure spontaneously emerging from an *a priori* ‘amorphous’ Analysis problem.

27. Example: the time-independent Schrödinger equation.

$$\partial_q^2 \psi = \frac{x^2}{4} W(q) \quad \text{with} \quad \begin{cases} W(q) = q^\nu + \alpha_1 q^{\nu-1} + \dots + \alpha_\nu \\ \alpha_\nu = -E \text{ (energy)} \end{cases}, \quad x = 2/\hbar$$

$$z = z(q) = \int_0^q \sqrt{W(q')} dq' \sim \frac{2}{2+\nu} q^{\frac{2+\nu}{2}}$$

$$\psi(z, x) = \begin{cases} +C_+(x) e^{xz/2} (q'(z))^{\frac{1}{2}} \varphi_+(z, x) \\ +C_-(x) e^{-xz/2} (q'(z))^{\frac{1}{2}} \varphi_-(z, x) \end{cases}$$

$$\partial_z^2 \varphi_\pm \pm x \partial_z \varphi_\pm = (H^2(z) - H'(z)) \varphi_\pm$$

$$\text{with } H(z) := \frac{1}{2} \frac{q''(z)}{q'(z)} = -\frac{1}{2} \frac{\nu}{2+\nu} z^{-1} + \dots$$

27*. Example: the time-independent Schrödinger equation.

$$\text{BE}_1 \quad \Delta_{x_k} \varphi_{\pm} = S_k(x) \varphi_{\mp} \quad \begin{cases} (\Delta_{x_k} = \Delta_{x_k}^{(z)}) \\ x_k := x \exp\left(\frac{4\pi i k}{2+\nu}\right) \\ S_k(x) \in \mathbb{C}\{x^{\frac{2}{2+\nu}}\} \end{cases}$$

$$\text{BE}_2 \quad \Delta_{\pm z \pm \omega_j} \varphi_{\pm} = P_{j\pm}(x) \varphi_{\mp} \quad (\Delta_{\pm z \pm \omega_j} = \Delta_{\pm z \pm \omega_j}^{(x)})$$

The $P_{j\pm}(x)$ are rational functions (whose form depend on the z -area) of $V_1(x), \dots, V_{\nu}(x)$ with $V_1(x)V_2(x)\dots V_{\nu}(x) \equiv 1$.

$$\text{BE}_3 \quad \begin{cases} \Delta_{n\omega_{i,j}} V_k = 0 & (k \neq i, j) & (\Delta_{n\omega_{ij}} = \Delta_{n\omega_{ij}}^{(x)}) \\ \Delta_{n\omega_{i,j}} V_i = +\frac{1}{n} \left(-\frac{V_{i+1}V_{i+2}\dots V_{j-1}}{V_{j+1}V_{j+2}\dots V_{i-1}} \right)^n & (i \neq j) \\ \Delta_{n\omega_{i,j}} V_j = -\frac{1}{n} \left(-\frac{V_{i+1}V_{i+2}\dots V_{j-1}}{V_{j+1}V_{j+2}\dots V_{i-1}} \right)^n & (i \neq j) \end{cases}$$

$$\omega_{ij} = \omega_j - \omega_i \quad \text{with} \quad \omega_i = \int_{\gamma_i} \sqrt{W(q')} dq'$$

The main results on the time-independent Schrödinger are due to Y. Sibuya (Stokes constants), A. Voros (resurgence in the ξ -plane), and J.E. (convergence in the ξ -plane).

Thank you!

Спасибо за внимание!

И еще огромное спасибо организаторам...

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