

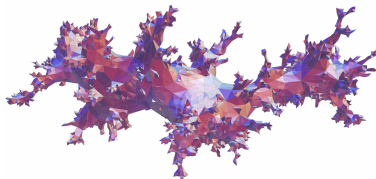
Compact and non-compact models of random geometry

Jean-François Le Gall
(partly joint with Armand Riera)

Probability and the City Seminar, November 2020



European Research Council



Supported by ERC Advanced Grant 740943 GEOBROWN

Outline

Goal of the lecture: Describe how the **basic models of random geometry** (obtained as scaling limits of random graphs embedded in the sphere) can be constructed from random trees equipped with Brownian labels.

Outline

Goal of the lecture: Describe how the **basic models of random geometry** (obtained as scaling limits of random graphs embedded in the sphere) can be constructed from random trees equipped with Brownian labels.

Compact models:

- The **Brownian sphere** (or Brownian map)
- The **Brownian disk**

Non-compact models:

- The **Brownian plane**
- The **Brownian half-plane**
- The **infinite Brownian disk**

Outline

Goal of the lecture: Describe how the **basic models of random geometry** (obtained as scaling limits of random graphs embedded in the sphere) can be constructed from random trees equipped with Brownian labels.

Compact models:

- The **Brownian sphere** (or Brownian map)
- The **Brownian disk**

Non-compact models:

- The **Brownian plane**
- The **Brownian half-plane**
- The **infinite Brownian disk**

Our construction allows us to study relations between different models. These models can also be viewed as quantum surfaces: cf. the work of Sheffield, Miller, Gwynne, Holden, Sun, etc.

1. Brownian spheres and Brownian disks

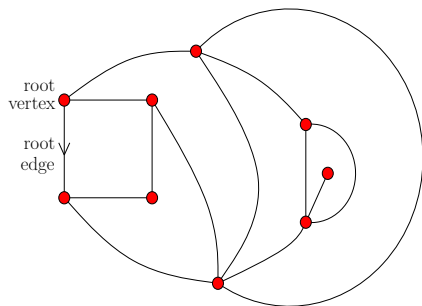
Definition

A **planar map** is a proper embedding of a **finite connected graph** into the two-dimensional sphere (considered up to orientation-preserving homeomorphisms). Self-loops and multiple edges are allowed.

1. Brownian spheres and Brownian disks

Definition

A **planar map** is a proper embedding of a **finite connected graph** into the two-dimensional sphere (considered up to orientation-preserving homeomorphisms). Self-loops and multiple edges are allowed.



A rooted quadrangulation with 7 faces

Faces = connected components of the complement of edges

p -angulation:

- each face is incident to p half-edges

$p = 3$: triangulation

$p = 4$: quadrangulation

Rooted map: distinguished oriented edge

The Brownian sphere (or Brownian map)

Let M_n be uniform over $\mathbb{M}_n^4 = \{\text{rooted quadrangulations with } n \text{ faces}\}$.

$V(M_n)$ vertex set of M_n

d_{gr} graph distance on $V(M_n)$

π_n uniform probability measure on $V(M_n)$

The Brownian sphere (or Brownian map)

Let M_n be uniform over $\mathbb{M}_n^4 = \{\text{rooted quadrangulations with } n \text{ faces}\}$.

$V(M_n)$ vertex set of M_n

d_{gr} graph distance on $V(M_n)$

π_n uniform probability measure on $V(M_n)$

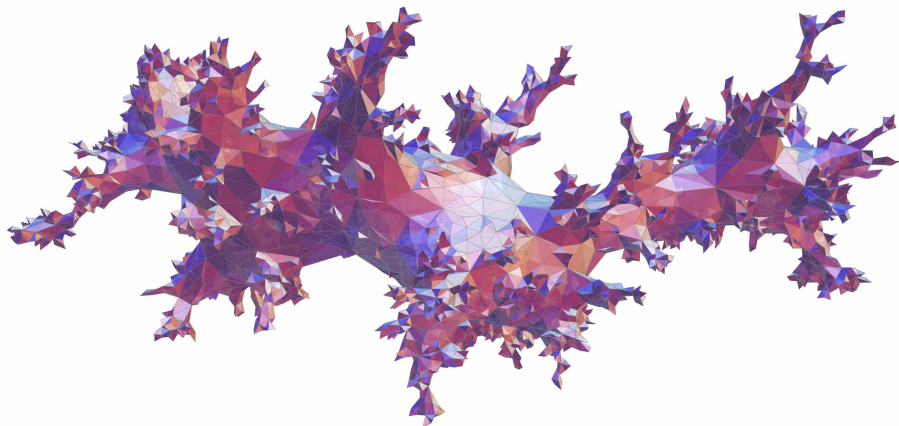
Theorem (LG 2013, Miermont 2013)

$$\left(V(M_n), \left(\frac{9}{8n}\right)^{1/4} d_{\text{gr}}, \pi_n \right) \xrightarrow[n \rightarrow \infty]{(d)} (\mathbf{m}_\infty, D, \text{Vol})$$

in the Gromov-Hausdorff-Prokhorov sense. The limit $(\mathbf{m}_\infty, D, \text{Vol})$ is a random compact metric measure space called the **Brownian sphere** (or **Brownian map**).

Remark A similar result holds for random triangulations and for much more general random planar maps, with the same limit (universality of the Brownian sphere). One can even randomize edge lengths: assigning i.i.d. lengths to edges does not change the scaling limit (Curien-LG, Ann. Sci. ENS 2019).

A large triangulation of the sphere (simulation: N.Curien)
(an approximation of the Brownian sphere)



Two properties of the Brownian sphere

Theorem (Hausdorff dimension)

$$\dim(\mathbf{m}_\infty, D) = 4 \quad \text{a.s.}$$

Uniform control of the volume of balls: for $\delta > 0$,

$$c_\delta(\omega) r^{4+\delta} \leq \text{Vol}(B(x, r)) \leq c'_\delta(\omega) r^{4-\delta},$$

with (random) constants $c_\delta(\omega)$, $c'_\delta(\omega)$ independent of $x \in \mathbf{m}_\infty$ and $r \in (0, 1]$.

Two properties of the Brownian sphere

Theorem (Hausdorff dimension)

$$\dim(\mathbf{m}_\infty, D) = 4 \quad \text{a.s.}$$

Uniform control of the volume of balls: for $\delta > 0$,

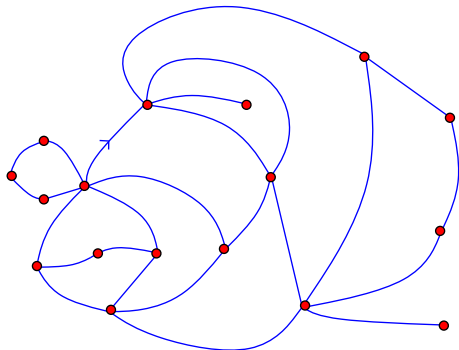
$$c_\delta(\omega) r^{4+\delta} \leq \text{Vol}(B(x, r)) \leq c'_\delta(\omega) r^{4-\delta},$$

with (random) constants $c_\delta(\omega)$, $c'_\delta(\omega)$ independent of $x \in \mathbf{m}_\infty$ and $r \in (0, 1]$.

Theorem (topological type, LG-Paulin 2008)

Almost surely, (\mathbf{m}_∞, D) is homeomorphic to the 2-sphere \mathbb{S}^2 .

Quadrangulations with a boundary



A quadrangulation with a boundary of size 14.

A **quadrangulation with a boundary** is a rooted planar map M such that

- The root face (to the left of the root edge) has an arbitrary even degree. (In the figure, the root face is the “external” face)
- All other faces have degree 4.

The degree of the root face is the **boundary size** of M .

Boltzmann quadrangulations with a boundary

For $p \geq 1$, let $\mathbb{M}^{4,p}$ be the set of all (rooted) quadrangulations with a boundary of size $2p$.

If $Q \in \mathbb{M}^{4,p}$, let $|Q|$ stand for the number of faces of Q

Boltzmann quadrangulations with a boundary

For $p \geq 1$, let $\mathbb{M}^{4,p}$ be the set of all (rooted) quadrangulations with a boundary of size $2p$.

If $Q \in \mathbb{M}^{4,p}$, let $|Q|$ stand for the number of faces of Q

A Boltzmann quadrangulation with boundary size $2p$ is a random quadrangulation with a boundary \mathbf{Q}_p such that :

$$\mathbb{P}(\mathbf{Q}_p = Q) = c_p 12^{-n} \text{ for every } Q \in \mathbb{M}^{4,p} \text{ with } |Q| = n$$

here $c_p > 0$ is the appropriate normalizing constant (depending on p).

Boltzmann quadrangulations with a boundary

For $p \geq 1$, let $\mathbb{M}^{4,p}$ be the set of all (rooted) quadrangulations with a boundary of size $2p$.

If $Q \in \mathbb{M}^{4,p}$, let $|Q|$ stand for the number of faces of Q

A Boltzmann quadrangulation with boundary size $2p$ is a random quadrangulation with a boundary \mathbf{Q}_p such that :

$$\mathbb{P}(\mathbf{Q}_p = Q) = c_p 12^{-n} \text{ for every } Q \in \mathbb{M}^{4,p} \text{ with } |Q| = n$$

here $c_p > 0$ is the appropriate normalizing constant (depending on p).

This makes sense because

$$\#\{Q \in \mathbb{M}^{4,p} : |Q| = n\} \underset{n \rightarrow \infty}{\approx} c'_p n^{-5/2} 12^n$$

Convergence to the Brownian disk

Recall that \mathbf{Q}_p is a Boltzmann quadrangulation with boundary size $2p$. Equip the vertex set $V(\mathbf{Q}_p)$ with the graph distance d_{gr} and the counting measure m_p .

Theorem (Bettinelli and Miermont)

$$\left(V(\mathbf{Q}_p), \left(\frac{3}{2p}\right)^{1/2} d_{\text{gr}}, \frac{2}{p^2} m_p \right) \xrightarrow[p \rightarrow \infty]{(d)} (\mathbb{D}, \Delta, \text{Vol})$$

*in the Gromov-Hausdorff-Prokhorov sense. The limit $(\mathbb{D}, \Delta, \text{Vol})$ is a random compact metric measure space called the **free Brownian disk** with perimeter 1.*

(A similar result for the simple boundary case has been obtained by Gwynne and Miller, see also Albenque-Holden-Sun for triangulations)

Convergence to the Brownian disk

Recall that \mathbf{Q}_p is a Boltzmann quadrangulation with boundary size $2p$. Equip the vertex set $V(\mathbf{Q}_p)$ with the graph distance d_{gr} and the counting measure m_p .

Theorem (Bettinelli and Miermont)

$$\left(V(\mathbf{Q}_p), \left(\frac{3}{2p}\right)^{1/2} d_{\text{gr}}, \frac{2}{p^2} m_p \right) \xrightarrow[p \rightarrow \infty]{(d)} (\mathbb{D}, \Delta, \text{Vol})$$

in the Gromov-Hausdorff-Prokhorov sense. The limit $(\mathbb{D}, \Delta, \text{Vol})$ is a random compact metric measure space called the **free Brownian disk** with perimeter 1.

(A similar result for the simple boundary case has been obtained by Gwynne and Miller, see also Albenque- Holden-Sun for triangulations)

By scaling one can define the free Brownian disk with perimeter r . By conditioning on $\text{Vol}(\mathbb{D}) = v$, one defines the Brownian disk with perimeter r and volume v .

Properties of the Brownian disk

Fact (Bettinelli): The free Brownian disk \mathbb{D} (with perimeter $r > 0$) is **homeomorphic to the closed unit disk**.

Hence one can make sense of the boundary $\partial\mathbb{D}$.

Remark. Similarly as Brownian spheres, Brownian disks can be viewed as Liouville quantum gravity surfaces: recent work of Miller, Sheffield, Gwynne, Holden, ...

Properties of the Brownian disk

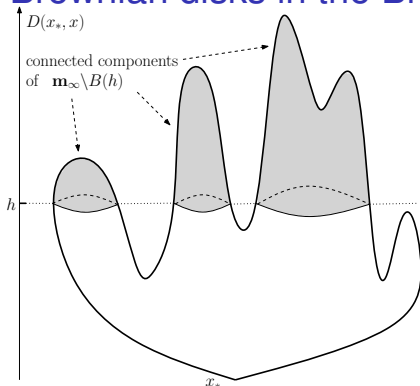
Fact (Bettinelli): The free Brownian disk \mathbb{D} (with perimeter $r > 0$) is homeomorphic to the closed unit disk.

Hence one can make sense of the boundary $\partial\mathbb{D}$.

Remark. Similarly as Brownian spheres, Brownian disks can be viewed as Liouville quantum gravity surfaces: recent work of Miller, Sheffield, Gwynne, Holden, ...

Special subsets of the Brownian sphere (\mathbf{m}_∞, D) can be identified as Brownian disks.

Brownian disks in the Brownian sphere

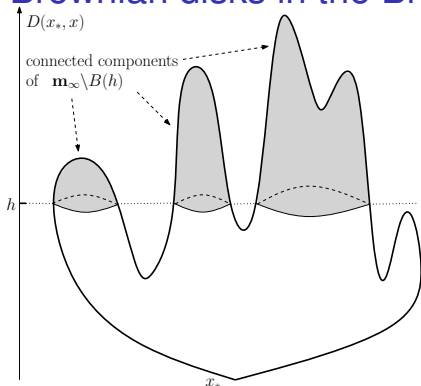


For $h > 0$, let $B(h)$ be the ball of radius h centered at the distinguished point x_* in the Brownian sphere (\mathbf{m}_∞, D)

Let $\mathcal{D}_j, j \in J$ be the connected components of $\mathbf{m}_\infty \setminus B(h)$. We can equip each \mathcal{D}_j with its intrinsic metric $D^{(j)}$

Vol : volume measure on \mathbf{m}_∞

Brownian disks in the Brownian sphere



For $h > 0$, let $B(h)$ be the ball of radius h centered at the distinguished point x_* in the Brownian sphere (\mathbf{m}_∞, D)

Let \mathcal{D}_j , $j \in J$ be the connected components of $\mathbf{m}_\infty \setminus B(h)$. We can equip each \mathcal{D}_j with its intrinsic metric $D^{(j)}$

Vol : volume measure on \mathbf{m}_∞

Theorem

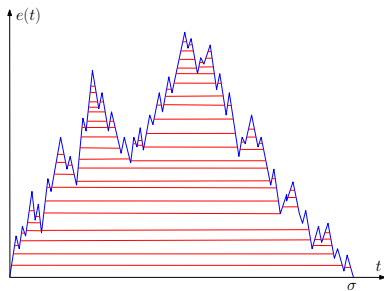
For every j , the limit

$$|\partial \mathcal{D}_j| := \lim_{\varepsilon \rightarrow 0} \varepsilon^{-2} \text{Vol} \{x \in \mathcal{D}_j : D(x, \partial \mathcal{D}_j) < \varepsilon\}$$

exists, and, conditionally on $(|\partial \mathcal{D}_j|, \text{Vol}(\mathcal{D}_j))_{j \in J}$, the metric spaces $(\bar{\mathcal{D}}_j, D^{(j)})$ are independent Brownian disks with the prescribed volumes and perimeters.

2. The construction of the Brownian sphere

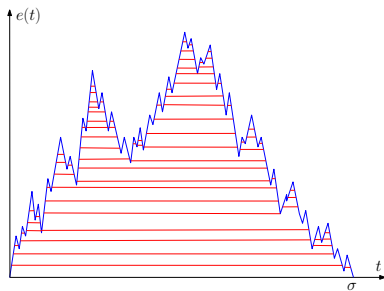
A key ingredient: The **Brownian tree (Aldous' CRT)**, or tree coded by a Brownian excursion under $\mathbf{n}_+(de)$ (the Itô excursion measure).



Informally, glue $s, t \in [0, \sigma]$ if they correspond to the **ends of a horizontal chord** drawn below the graph of e .

2. The construction of the Brownian sphere

A key ingredient: The **Brownian tree (Aldous' CRT)**, or tree coded by a Brownian excursion under $\mathbf{n}_+(de)$ (the Itô excursion measure).



Informally, glue $s, t \in [0, \sigma]$ if they correspond to the **ends of a horizontal chord** drawn below the graph of e .

Formally, say that $s \sim t$ iff $e(s) = e(t) = \min_{u \in [s \wedge t, s \vee t]} e(u)$.

The **Brownian tree** is $\mathcal{T}_e := [0, \sigma] / \sim$, with the metric induced by

$$d_e(s, t) = e(s) + e(t) - 2 \min_{u \in [s \wedge t, s \vee t]} e(u).$$

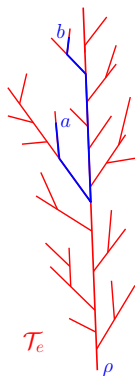
The Brownian tree

$\mathcal{T}_e := [0, \sigma] / \sim$, where

- $s \sim t$ iff $e(s) = e(t) = \min_{u \in [s \wedge t, s \vee t]} e(u)$
- $d_e(s, t) = e(s) + e(t) - 2 \min_{u \in [s \wedge t, s \vee t]} e(u)$.

Then (\mathcal{T}_e, d_e) is a compact \mathbb{R} -tree

(means that two points of \mathcal{T}_e are connected by a unique arc $[[a, b]]$, which is isometric to a line segment — $d(a, b)$ is the length of the blue path connecting a to b)



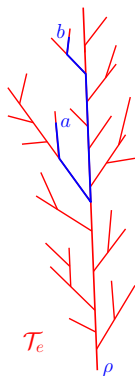
The Brownian tree

$\mathcal{T}_e := [0, \sigma] / \sim$, where

- $s \sim t$ iff $e(s) = e(t) = \min_{u \in [s \wedge t, s \vee t]} e(u)$
- $d_e(s, t) = e(s) + e(t) - 2 \min_{u \in [s \wedge t, s \vee t]} e(u)$.

Then (\mathcal{T}_e, d_e) is a compact \mathbb{R} -tree

(means that two points of \mathcal{T}_e are connected by a unique arc $[[a, b]]$, which is isometric to a line segment — $d(a, b)$ is the length of the blue path connecting a to b)



Let $p_e : [0, \sigma] \rightarrow \mathcal{T}_e = [0, \sigma] / \sim$ be the canonical projection:

- \mathcal{T}_e is rooted at $\rho := p_e(0) = p_e(\sigma)$
- the volume measure is the push forward of Lebesgue measure under p_e .
- the Brownian tree \mathcal{T}_e also inherits a **cyclic ordering** from the projection p_e (it makes sense to explore the tree “clockwise” from one point to another)

Brownian motion indexed by the Brownian tree

Conditionally on \mathcal{T}_e , $Z = (Z_a)_{a \in \mathcal{T}_e}$ is the centered Gaussian process characterized by:

- $Z_\rho = 0$
- $\mathbb{E}[(Z_a - Z_b)^2] = d_e(a, b)$ for every $a, b \in \mathcal{T}_e$

(Technical difficulty: Z is a random process indexed by a random set. Since $\mathcal{T}_e = [0, \sigma] / \sim$, one can as well define Z as indexed by $[0, \sigma]$ — this is the Brownian snake construction)

Fact: Z has continuous sample paths.

Brownian motion indexed by the Brownian tree

Conditionally on \mathcal{T}_e , $Z = (Z_a)_{a \in \mathcal{T}_e}$ is the centered Gaussian process characterized by:

- $Z_\rho = 0$
- $\mathbb{E}[(Z_a - Z_b)^2] = d_e(a, b)$ for every $a, b \in \mathcal{T}_e$

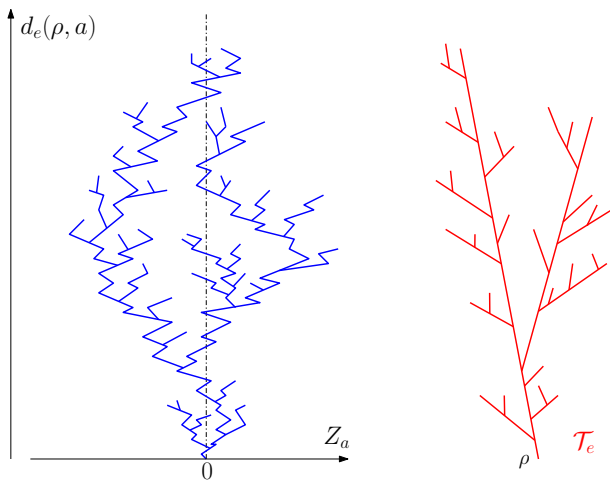
(Technical difficulty: Z is a random process indexed by a random set. Since $\mathcal{T}_e = [0, \sigma] / \sim$, one can as well define Z as indexed by $[0, \sigma]$ — this is the Brownian snake construction)

Fact: Z has continuous sample paths.

One views Z_a as a **Brownian label** assigned to $a \in \mathcal{T}_e$. When moving along a line segment of \mathcal{T}_e , labels evolve like linear Brownian motion.

Motivations for studying \mathcal{T}_e and $(Z_a)_{a \in \mathcal{T}_e}$: These objects arise in a number of **asymptotics for discrete models**, in combinatorics, interacting particle systems, statistical physics, etc.

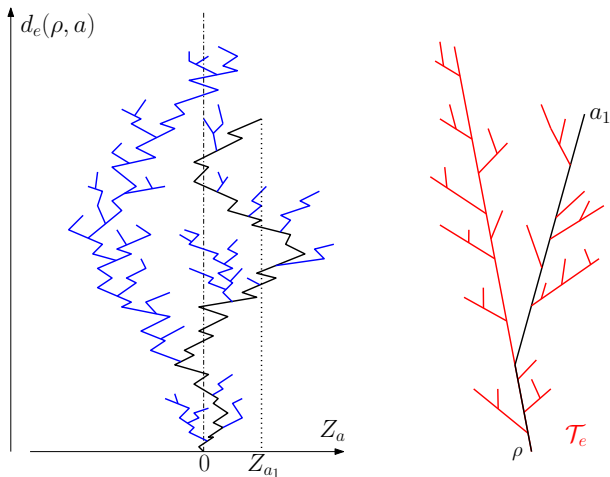
Brownian motion indexed by the Brownian tree 2



The collection $(Z_a)_{a \in \mathcal{T}_e}$ forms a “tree of Brownian paths” whose genealogy is prescribed by \mathcal{T}_e .

Z_a is also interpreted as a “label” assigned to vertex $a \in \mathcal{T}_e$.

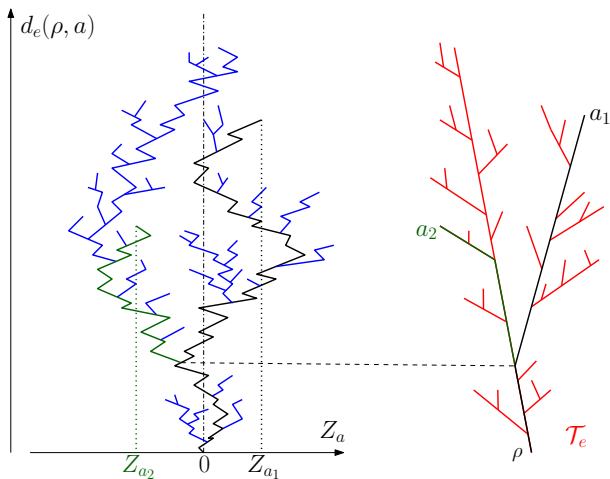
Brownian motion indexed by the Brownian tree 3



The collection $(Z_a)_{a \in \mathcal{T}_e}$ forms a “tree of Brownian paths” whose genealogy is prescribed by \mathcal{T}_e .

Z_a is also interpreted as a “label” assigned to vertex $a \in \mathcal{T}_e$.

Brownian motion indexed by the Brownian tree 4



The collection $(Z_a)_{a \in \mathcal{T}_e}$ forms a “tree of Brownian paths” whose genealogy is prescribed by \mathcal{T}_e .

Z_a is also interpreted as a “label” assigned to vertex $a \in \mathcal{T}_e$.

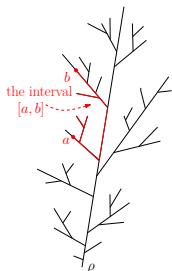
The construction of the Brownian sphere

\mathcal{T}_e is the Brownian tree, $(Z_a)_{a \in \mathcal{T}_e}$ Brownian motion indexed by \mathcal{T}_e (**Two levels of randomness!**).

Set, for every $a, b \in \mathcal{T}_e$,

$$D^0(a, b) = Z_a + Z_b - 2 \max \left(\min_{c \in [a, b]} Z_c, \min_{c \in [b, a]} Z_c \right)$$

where $[a, b]$ is the **“interval”** from a to b corresponding to the **cyclic ordering** on \mathcal{T}_e (vertices visited when going from a to b in clockwise order around the tree).



The construction of the Brownian sphere

\mathcal{T}_e is the Brownian tree, $(Z_a)_{a \in \mathcal{T}_e}$ Brownian motion indexed by \mathcal{T}_e (**Two levels of randomness!**).

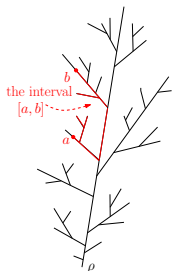
Set, for every $a, b \in \mathcal{T}_e$,

$$D^0(a, b) = Z_a + Z_b - 2 \max \left(\min_{c \in [a, b]} Z_c, \min_{c \in [b, a]} Z_c \right)$$

where $[a, b]$ is the **“interval”** from a to b corresponding to the **cyclic ordering** on \mathcal{T}_e (vertices visited when going from a to b in clockwise order around the tree).

Then let D be the **maximal symmetric function** on $\mathcal{T}_e \times \mathcal{T}_e$ that is bounded above by D^0 and satisfies the **triangle inequality**. Also set

$a \approx b$ if and only if $D(a, b) = 0$ (equivalent to $D^0(a, b) = 0$).



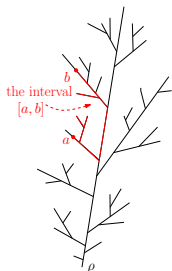
The construction of the Brownian sphere

\mathcal{T}_e is the Brownian tree, $(Z_a)_{a \in \mathcal{T}_e}$ Brownian motion indexed by \mathcal{T}_e (**Two levels of randomness!**).

Set, for every $a, b \in \mathcal{T}_e$,

$$D^0(a, b) = Z_a + Z_b - 2 \max \left(\min_{c \in [a, b]} Z_c, \min_{c \in [b, a]} Z_c \right)$$

where $[a, b]$ is the “**interval**” from a to b corresponding to the **cyclic ordering** on \mathcal{T}_e (vertices visited when going from a to b in clockwise order around the tree).



Then let D be the **maximal symmetric function** on $\mathcal{T}_e \times \mathcal{T}_e$ that is bounded above by D^0 and satisfies the **triangle inequality**. Also set

$a \approx b$ if and only if $D(a, b) = 0$ (equivalent to $D^0(a, b) = 0$).

Definition

The **free Brownian sphere** \mathbf{m}_∞ is the quotient space $\mathbf{m}_\infty := \mathcal{T}_e / \approx$, which is equipped with the distance induced by D .

To get the “standard” Brownian sphere, condition on $\sigma(= \text{Vol}(\mathcal{T}_e)) = 1$.

Summary and interpretation

Starting from the Brownian tree \mathcal{T}_e , with Brownian labels $Z_a, a \in \mathcal{T}_e$,
→ **Identify** two vertices $a, b \in \mathcal{T}_e$ if $D^\circ(a, b) = 0$, meaning that:

- they have the **same label** $Z_a = Z_b$,
- one can go from a to b around the tree (in clockwise or in counterclockwise order) visiting only vertices with **label greater than or equal to** $Z_a = Z_b$.

Summary and interpretation

Starting from the Brownian tree \mathcal{T}_e , with Brownian labels $Z_a, a \in \mathcal{T}_e$,
→ **Identify** two vertices $a, b \in \mathcal{T}_e$ if $D^\circ(a, b) = 0$, meaning that:

- they have the **same label** $Z_a = Z_b$,
- one can go from a to b around the tree (in clockwise or in counterclockwise order) visiting only vertices with **label greater than or equal to** $Z_a = Z_b$.

Key fact: If x_* is the vertex with minimal label ($Z_{x_*} = \min\{Z_a : a \in \mathcal{T}_e\}$) then, for every a

$$D(x_*, a) = Z_a - Z_{x_*}$$

(labels correspond to distances from x_* , up to a shift)

Summary and interpretation

Starting from the Brownian tree \mathcal{T}_e , with Brownian labels $Z_a, a \in \mathcal{T}_e$,
→ **Identify** two vertices $a, b \in \mathcal{T}_e$ if $D^\circ(a, b) = 0$, meaning that:

- they have the **same label** $Z_a = Z_b$,
- one can go from a to b around the tree (in clockwise or in counterclockwise order) visiting only vertices with **label greater than or equal to** $Z_a = Z_b$.

Key fact: If x_* is the vertex with minimal label ($Z_{x_*} = \min\{Z_a : a \in \mathcal{T}_e\}$) then, for every a

$$D(x_*, a) = Z_a - Z_{x_*}$$

(labels correspond to distances from x_* , up to a shift)

- **conn.comp.** of complement of a ball = **excursions** of Z above a level
→ **Brownian disks** correspond to excursions of the process Z !!

A different approach to the Brownian sphere

Miller, Sheffield (2015-2016) have developed a program aiming to relate the Brownian sphere with [Liouville quantum gravity](#):

- new construction of the Brownian sphere using the [Gaussian free field](#) and the random growth process called [Quantum Loewner Evolution](#) (an analog of the celebrated SLE processes studied by Lawler, Schramm and Werner)
- this construction makes it possible to equip the Brownian sphere with a [conformal structure](#), and in fact to show that this conformal structure is determined by the Brownian sphere.

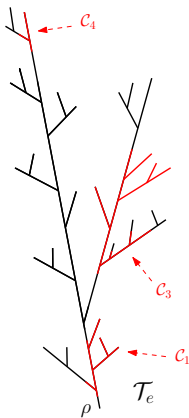
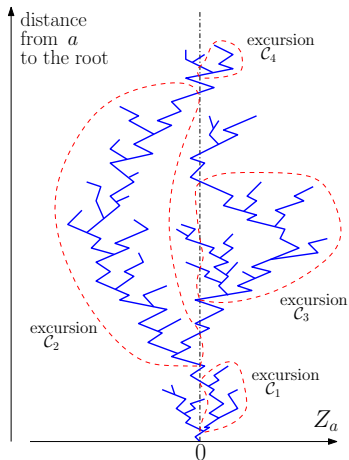
A different approach to the Brownian sphere

Miller, Sheffield (2015-2016) have developed a program aiming to relate the Brownian sphere with [Liouville quantum gravity](#):

- new construction of the Brownian sphere using the [Gaussian free field](#) and the random growth process called [Quantum Loewner Evolution](#) (an analog of the celebrated SLE processes studied by Lawler, Schramm and Werner)
- this construction makes it possible to equip the Brownian sphere with a [conformal structure](#), and in fact to show that this conformal structure is determined by the Brownian sphere.

More recently: the Miller-Sheffield construction has been simplified by a direct construction of the [Liouville quantum gravity metric](#) from the Gaussian free field ([Gwynne-Miller 2019](#) after the work of several other authors).

3. Excursions of Brownian motion indexed by the Brownian tree



Recall:

\mathcal{T}_e Brownian tree
 $(Z_a)_{a \in \mathcal{T}_e}$ Brownian motion indexed by \mathcal{T}_e

Let $(C_i)_{i \in I}$ be the **connected components** of $\{a \in \mathcal{T}_e : Z_a \neq 0\}$.

The **excursions** of Z are $(\bar{C}_i, (Z_a)_{a \in \bar{C}_i})$, $i \in I$, viewed as \mathbb{R} -trees equipped with continuous labels (here \bar{C}_i is the closure of C_i)

The law of excursions

For each “excursion” $(\bar{\mathcal{C}}_i, (Z_a)_{a \in \bar{\mathcal{C}}_i})$, one can define its boundary size

$$|\partial \mathcal{C}_i| = \lim_{\varepsilon \rightarrow 0} \varepsilon^{-2} \text{Vol}(\{a \in \mathcal{C}_i : |Z_a| < \varepsilon\})$$

The law of excursions

For each “excursion” $(\bar{C}_i, (Z_a)_{a \in \bar{C}_i})$, one can define its boundary size

$$|\partial \mathcal{C}_i| = \lim_{\varepsilon \rightarrow 0} \varepsilon^{-2} \text{Vol}(\{a \in \mathcal{C}_i : |Z_a| < \varepsilon\})$$

Theorem (Abraham-LG, JEMS 2018)

There exists a σ -finite measure \mathbb{M} (with appropriate scaling properties) on the space of compact \mathbb{R} -trees \mathcal{T} equipped with a volume measure $\text{Vol}(\cdot)$ and with labels $(z(a))_{a \in \mathcal{T}}$, such that, conditionally on $(|\partial \mathcal{C}_i|)_{i \in I}$,

- the “excursions” $(\bar{C}_i, (Z_a)_{a \in \bar{C}_i})$, $i \in I$ are **independent**
- for every $i \in I$, the **distribution** of $(\bar{C}_i, (Z_a)_{a \in \bar{C}_i})$ knowing $|\partial \mathcal{C}_i| = r$ is

$$\mathbb{M}^{(r)} := \mathbb{M}(\cdot \mid \Sigma = r)$$

where $\Sigma = \lim_{\varepsilon \rightarrow 0} \varepsilon^{-2} \text{Vol}(\{a \in \mathcal{T} : |z(a)| < \varepsilon\})$
(the limit exists \mathbb{M} a.e.)

The law of excursions

For each “excursion” $(\bar{C}_i, (Z_a)_{a \in \bar{C}_i})$, one can define its boundary size

$$|\partial \mathcal{C}_i| = \lim_{\varepsilon \rightarrow 0} \varepsilon^{-2} \text{Vol}(\{a \in \mathcal{C}_i : |Z_a| < \varepsilon\})$$

Theorem (Abraham-LG, JEMS 2018)

There exists a σ -finite measure \mathbb{M} (with appropriate scaling properties) on the space of compact \mathbb{R} -trees \mathcal{T} equipped with a volume measure $\text{Vol}(\cdot)$ and with labels $(z(a))_{a \in \mathcal{T}}$, such that, conditionally on $(|\partial \mathcal{C}_i|)_{i \in I}$,

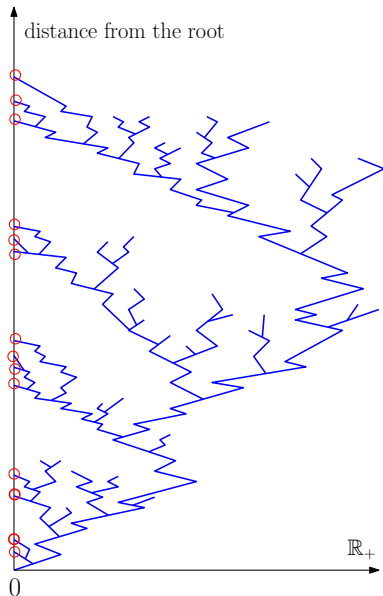
- the “excursions” $(\bar{C}_i, (Z_a)_{a \in \bar{C}_i})$, $i \in I$ are **independent**
- for every $i \in I$, the **distribution** of $(\bar{C}_i, (Z_a)_{a \in \bar{C}_i})$ knowing $|\partial \mathcal{C}_i| = r$ is

$$\mathbb{M}^{(r)} := \mathbb{M}(\cdot \mid \Sigma = r)$$

where $\Sigma = \lim_{\varepsilon \rightarrow 0} \varepsilon^{-2} \text{Vol}(\{a \in \mathcal{T} : |z(a)| < \varepsilon\})$
(the limit exists \mathbb{M} a.e.)

We can write $\mathbb{M} = \mathbb{M}_+ + \mathbb{M}_-$ and interpret \mathbb{M}_+ as a measure on “trees of Brownian paths in $[0, \infty)$ ”. One similarly defines $\mathbb{M}_+^{(r)}$.

The tree of paths under \mathbb{M}_+



Under \mathbb{M}_+ , we now have a tree of nonnegative “Brownian paths” all starting from 0, which stay positive during some interval $(0, \varepsilon]$ and are stopped at the time when they return to 0, if they do return to 0.

Informally, the boundary size Σ counts the number of paths that return to 0 (circled points on the figure).

Explicit formulas under \mathbb{M}_+

Joint distribution of boundary size and volume: The distribution of the pair $(\Sigma, \text{Vol}(\mathcal{T}))$ under \mathbb{M}_+ has density

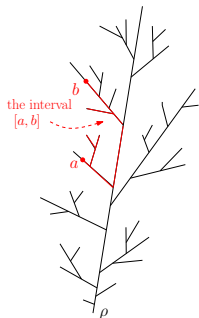
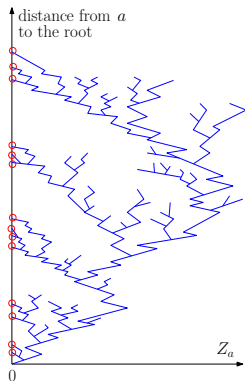
$$f(s, v) = \frac{\sqrt{3}}{2\pi} \sqrt{s} v^{-5/2} \exp\left(-\frac{s^2}{2v}\right)$$

As a consequence, for every $s > 0$, the density of $\text{Vol}(\mathcal{T})$ under $\mathbb{M}_+^{(s)} := \mathbb{M}_+(\cdot \mid \Sigma = s)$ is

$$g_s(v) = \frac{1}{\sqrt{2\pi}} s^3 v^{-5/2} \exp\left(-\frac{s^2}{2v}\right)$$

(this is the asymptotic distribution of the volume of a Boltzmann quadrangulation with a boundary of size n when $n \rightarrow \infty$ and the volume is rescaled by n^{-2})

4. The construction of Brownian disks under \mathbb{M}_+

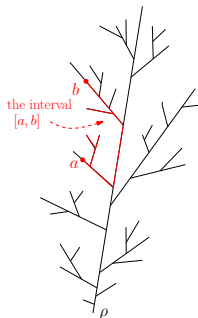
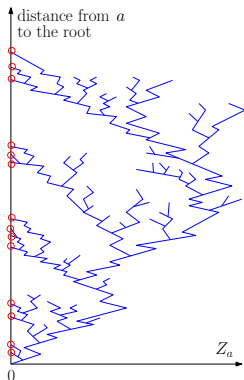


Under $\mathbb{M}_+^{(r)} = \mathbb{M}_+(\cdot \mid \Sigma = r)$,

- we have an \mathbb{R} -tree \mathcal{T}
- and nonnegative labels $z(a)$, $a \in \mathcal{T}$

Also cyclic order structure on \mathcal{T} that allows one to define **intervals** $[a, b]$ (informally, points visited when going from a to b around the tree).

4. The construction of Brownian disks under \mathbb{M}_+



Under $\mathbb{M}_+^{(r)} = \mathbb{M}_+(\cdot \mid \Sigma = r)$,

- we have an \mathbb{R} -tree \mathcal{T}
- and nonnegative labels $z(a)$, $a \in \mathcal{T}$

Also cyclic order structure on \mathcal{T} that allows one to define **intervals** $[a, b]$ (informally, points visited when going from a to b around the tree).

For $a, b \in \mathcal{T}$, set

$$D^\circ(a, b) = z(a) + z(b) - 2 \max \left\{ \min_{c \in [a, b]} z(c), \min_{c \in [b, a]} z(c) \right\}.$$

Imitating the construction of the Brownian sphere would require **identifying** a and b if $D^\circ(a, b) = 0$. But here this would mean identifying all boundary points (**all c such that $z(c) = 0$**)!

Constructing free Brownian disks

Recall $D^\circ(a, b) = z(a) + z(b) - 2 \max \left\{ \min_{c \in [a, b]} z(c), \min_{c \in [b, a]} z(c) \right\}$.

Set $\partial\mathcal{T} = \{c \in \mathcal{T} : z(c) = 0\}$, $\mathcal{T}^\circ = \mathcal{T} \setminus \partial\mathcal{T}$ and, for $a, b \in \mathcal{T}^\circ$,

$$\Delta^\circ(a, b) = \begin{cases} D^\circ(a, b) & \text{if } \max \left\{ \min_{[a, b]} z(c), \min_{[b, a]} z(c) \right\} > 0, \\ \infty & \text{otherwise,} \end{cases}$$

and

$$\Delta(a, b) = \inf_{\substack{a=a_0, a_1, \dots, a_k=b \\ a_i \in \mathcal{T}^\circ}} \sum_{i=1}^k \Delta^\circ(a_{i-1}, a_i).$$

Constructing free Brownian disks

Recall $D^\circ(a, b) = z(a) + z(b) - 2 \max \left\{ \min_{c \in [a, b]} z(c), \min_{c \in [b, a]} z(c) \right\}$.

Set $\partial\mathcal{T} = \{c \in \mathcal{T} : z(c) = 0\}$, $\mathcal{T}^\circ = \mathcal{T} \setminus \partial\mathcal{T}$ and, for $a, b \in \mathcal{T}^\circ$,

$$\Delta^\circ(a, b) = \begin{cases} D^\circ(a, b) & \text{if } \max \left\{ \min_{[a, b]} z(c), \min_{[b, a]} z(c) \right\} > 0, \\ \infty & \text{otherwise,} \end{cases}$$

and

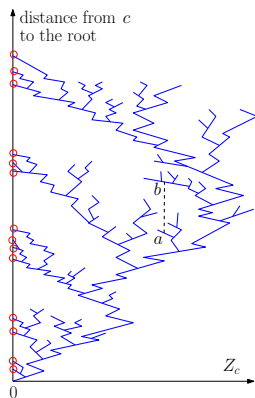
$$\Delta(a, b) = \inf_{\substack{a=a_0, a_1, \dots, a_k=b \\ a_i \in \mathcal{T}^\circ}} \sum_{i=1}^k \Delta^\circ(a_{i-1}, a_i).$$

Theorem (LG, Ann.IHP 2019)

*Under $\mathbb{M}_+^{(r)}$, $(\Delta(a, b), a, b \in \mathcal{T}^\circ)$ has a continuous extension to $\mathcal{T} \times \mathcal{T}$, which is a **pseudo-metric** on \mathcal{T} . The associated quotient space \mathbb{D} equipped with the distance induced by Δ is a **free Brownian disk with perimeter r** .*

Remark: $\partial\mathbb{D}$ corresponds to $\partial\mathcal{T}$ in the quotient space.

Uniform measure on the boundary



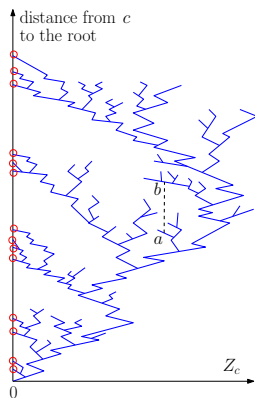
Interpretation: We glue $a, b \in \mathcal{T}^\circ$ if

- they have the **same label** $z(a) = z(b) > 0$
- going from a to b “around” the tree \mathcal{T} one encounters only vertices with **greater label**.

The **Bettinelli-Miermont** construction also relied on using a labeled forest, but here we have the additional remarkable interpretation of labels:

$z(c) = \Delta(c, \partial\mathbb{D})$ coincides with the distance from (the equivalence class of) c to $\partial\mathbb{D}$.

Uniform measure on the boundary



Interpretation: We glue $a, b \in \mathcal{T}^\circ$ if

- they have the **same label** $z(a) = z(b) > 0$
- going from a to b “around” the tree \mathcal{T} one encounters only vertices with **greater label**.

The **Bettinelli-Miermont** construction also relied on using a labeled forest, but here we have the additional remarkable interpretation of labels:

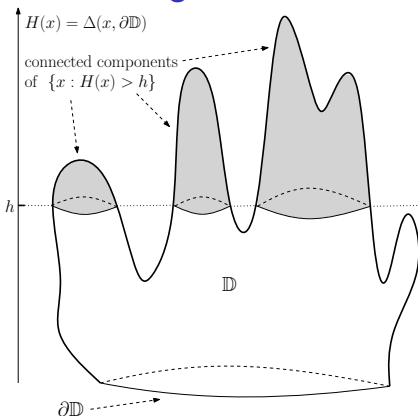
$z(c) = \Delta(c, \partial\mathbb{D})$ coincides with the distance from (the equivalence class of) c to $\partial\mathbb{D}$.

One can use this to construct the **uniform measure** on the boundary.

Proposition

The formula $\langle \mu, \varphi \rangle = \lim_{\varepsilon \rightarrow 0} \varepsilon^{-2} \int_{\mathbb{D}} \text{Vol}(dx) \varphi(x) \mathbf{1}_{\{\Delta(x, \partial\mathbb{D}) < \varepsilon\}}$ defines a finite measure on the boundary with total mass r .

5. Cutting Brownian disks at heights



(\mathbb{D}, Δ) is the free Brownian disk with perimeter r

For $x \in \mathbb{D}$, $H(x) = \Delta(x, \partial\mathbb{D})$ is called the **height** of x .

Fix $h > 0$. For each connected component \mathcal{C} of $\{x : H(x) > h\}$, can define its boundary size (perimeter)

$$|\partial\mathcal{C}| = \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^2} \text{Vol}(\{x \in \mathcal{C} : H(x) < h + \varepsilon\})$$

Theorem (LG-Riera AOP 2020)

*Conditionally on their boundary sizes, the connected components of $\{x \in \mathbb{D} : H(x) > h\}$, equipped with their intrinsic metrics, are **independent free Brownian disks** with the prescribed perimeters.*

Question. How does the collection of perimeters of connected components of $\{x \in \mathbb{D} : H(x) > h\}$ evolve as h varies ?

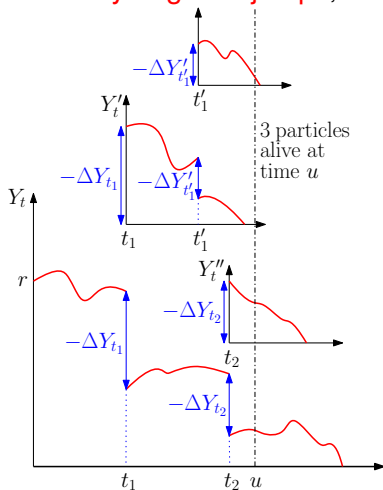
Write $\mathcal{C}^{1,h}, \mathcal{C}^{2,h}, \dots$ for the connected components of $\{x \in \mathbb{D} : H(x) > h\}$ ranked in decreasing order of their boundary sizes, and

$$\mathbf{X}(h) = (|\partial\mathcal{C}^{1,h}|, |\partial\mathcal{C}^{2,h}|, \dots)$$

The preceding theorem suggests that $(\mathbf{X}(h))_{h \geq 0}$ satisfies a kind of **branching property** analogous to that of **growth-fragmentation processes**.

Growth-fragmentation processes

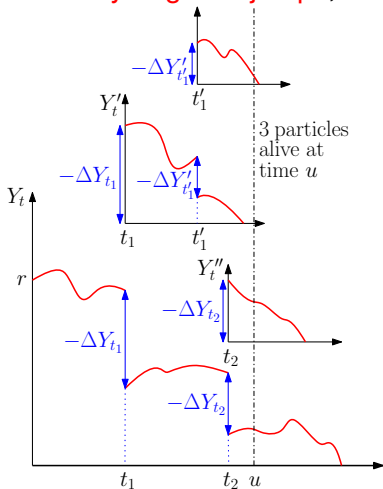
Basic ingredient: Y self-similar Markov process with values in \mathbb{R}_+ and **only negative jumps**, absorbed at 0.



The process starts with an initial particle (**Eve particle**) whose mass evolves in time according to the law of Y started at r .

Growth-fragmentation processes

Basic ingredient: Y self-similar Markov process with values in \mathbb{R}_+ and **only negative jumps**, absorbed at 0.



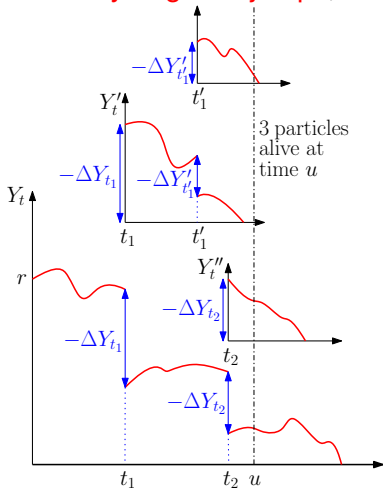
The process starts with an initial particle (**Eve particle**) whose mass evolves in time according to the law of Y started at r .

When the mass of the initial particle has a (negative) jump of size $-\delta$, a **new particle** (child of the Eve particle) is created, whose mass then evolves according to the law of Y started at δ .

In turn, each child of the Eve particle has children at jump times of its mass process, and so on.

Growth-fragmentation processes

Basic ingredient: Y **self-similar Markov process** with values in \mathbb{R}_+ and **only negative jumps**, absorbed at 0.



The process starts with an initial particle (**Eve particle**) whose mass evolves in time according to the law of Y started at r .

When the mass of the initial particle has a (negative) jump of size $-\delta$, a **new particle** (child of the Eve particle) is created, whose mass then evolves according to the law of Y started at δ .

In turn, each child of the Eve particle has children at jump times of its mass process, and so on.

The associated **growth-fragmentation process** is:

$\mathbf{Y}(t) =$ ranked sequence of masses of particles alive at time t .

Growth-fragmentation process in the Brownian disk

Recall that \mathbb{D} is the free Brownian disk with perimeter r , and

$$\mathbf{X}(h) = (|\partial\mathcal{C}^{1,h}|, |\partial\mathcal{C}^{2,h}|, \dots)$$

Here $\mathcal{C}^{1,h}, \mathcal{C}^{2,h}, \dots$ are the connected components of $\{x \in \mathbb{D} : H(x) > h\}$.

Theorem (LG-Riera, AOP 2020)

$(\mathbf{X}(h))_{h \geq 0}$ is a **growth-fragmentation process** whose Eve particle mass process X (starting from 1) can be obtained as follows:

$$X_t = \exp(\xi_{\tau(t)}),$$

where

$$\tau(t) = \inf \left\{ u \geq 0 : \int_0^u e^{\xi_s/2} ds > t \right\}$$

and ξ is the spectrally negative Lévy process with Laplace exponent

$$\psi(q) = \sqrt{\frac{3}{2\pi}} \left(-\frac{8}{3}q + \int_{1/2}^1 (x^q - 1 + q(1-x))(x(1-x))^{-5/2} dx \right).$$

Remarks

- The formula

$$X_t = \exp(\xi_{\tau(t)})$$

is the **Lamperti representation** of a self-similar Markov process in terms of a Lévy process.

- The theorem is closely related to the work of **Bertoin, Curien, Kortchemski** who studied asymptotics for a discrete analog of the process $\mathbf{X}(h)$ (for triangulations with a boundary).
- The measure

$$(x(1-x))^{-5/2} dx$$

that appears in the formula for ψ should be compared with the **dislocation measure** $(x(1-x))^{-3/2} dx$ corresponding to the (pure) **fragmentation process** obtained by cutting the Brownian tree at heights (**Bertoin**).

6. Non-compact models of random geometry

The Brownian plane

Let M_n be uniform over {rooted quadrangulations with n faces}.

$V(M_n)$ vertex set of M_n , $V(M_n)$ is pointed at the root vertex

d_{gr} graph distance on $V(M_n)$

6. Non-compact models of random geometry

The Brownian plane

Let M_n be **uniform** over {rooted quadrangulations with n faces}.

$V(M_n)$ **vertex set** of M_n , $V(M_n)$ is pointed at the root vertex

d_{gr} **graph distance** on $V(M_n)$

Theorem (Curien-LG)

Let a_n be a sequence of positive reals converging to 0 such that $n^{1/4} a_n \rightarrow \infty$. Then

$$\left(V(M_n), a_n d_{\text{gr}} \right) \xrightarrow[n \rightarrow \infty]{(d)} (\mathcal{P}, D)$$

in the **local** Gromov-Hausdorff sense. The limit (\mathcal{P}, D) is a random pointed (non-compact) metric space called the **Brownian plane**.

The Brownian plane is also the scaling limit of the Uniform Infinite Planar Quadrangulation (or of the UIPT, cf. [Budzinski](#)).

(\mathcal{P}, D) is homeomorphic to the usual plane

The infinite Brownian disk

For $p, n \geq 1$, let $\mathbb{M}^{4,p,n}$ be the set of all (rooted) **quadrangulations with a boundary** of size $2p$ and n internal faces.

Let $\mathbf{Q}_{p,n}$ be uniformly distributed over $\mathbb{M}^{4,p,n}$.

The vertex set $V(\mathbf{Q}_{p,n})$ of $\mathbf{Q}_{p,n}$ is a pointed metric space for d_{gr}

Theorem (Baur-Miermont-Ray)

Let $(n_p)_{p \in \mathbb{N}}$ be a sequence of positive integers with $n_p/p^2 \rightarrow \infty$ as $p \rightarrow \infty$. Then

$$\left(V(\mathbf{Q}_{p,n_p}), \left(\frac{3}{2p}\right)^{1/2} d_{\text{gr}} \right) \xrightarrow[p \rightarrow \infty]{(d)} (\mathbb{D}_1^\infty, \Delta^\infty)$$

*in the local Gromov-Hausdorff sense. The limit $(\mathbb{D}_1^\infty, \Delta^\infty)$ is a random pointed non-compact metric space called the **infinite Brownian disk** with perimeter 1.*

The infinite Brownian disk is homeomorphic to the complement of the (open) unit disk of the plane.

The Brownian half-plane

Keep the notation of the preceding slide : $\mathbf{Q}_{p,n}$ is uniformly distributed over the set of all quadrangulations with a boundary of size $2p$ and n internal faces.

Theorem (Baur-Miermont-Ray)

Let $(n_p)_{p \in \mathbb{N}}$ be a sequence of positive integers with $n_p/p^2 \rightarrow \infty$ as $p \rightarrow \infty$, and let $(a_p)_{p \in \mathbb{N}}$ be a sequence of positive reals tending to 0, with $\sqrt{p} a_p \rightarrow \infty$. Then

$$\left(V(\mathbf{Q}_{p,n_p}), a_p d_{\text{gr}} \right) \xrightarrow[p \rightarrow \infty]{(d)} (\mathbb{H}, D^\infty)$$

in the local Gromov-Hausdorff sense. The limit (\mathbb{H}, D^∞) is a random pointed non-compact metric space called the **Brownian half-plane**.

The Brownian half-plane is homeomorphic to the usual half-plane.

Baur-Miermont-Ray (AOP 2019) classify all possible scaling limits of quadrangulations with a boundary: the **Brownian plane**, the **Brownian half-plane** and the **infinite Brownian disk** are the basic non-compact models that can appear in the limit.

Constructing the non-compact models

Basic ingredient: the infinite Brownian tree (Aldous 1990)

This tree consists of

- An infinite spine isometric to $[0, \infty)$
- Brownian subtrees branching off the left side and the right side of the spine

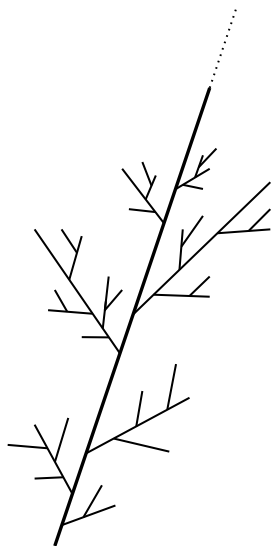
To get the subtrees **branching off the left side**, recall \mathbf{n}_+ is the Brownian excursion measure, consider a Poisson point measure

$$\sum_{i \in I} \delta_{(h_i, e_i)}$$

with intensity $2 dh \mathbf{n}_+(de)$, and for every $i \in I$ **graft the tree** \mathcal{T}_{e_i} coded by e_i at height h_i of the spine.

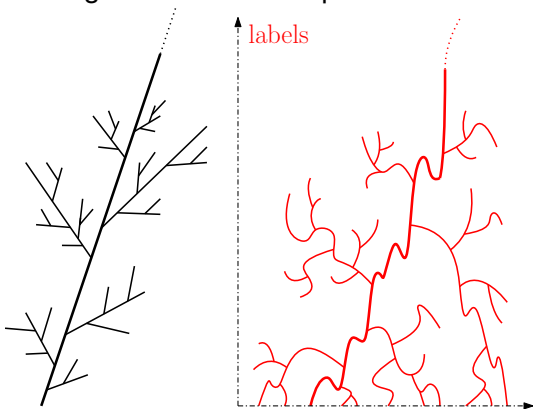
Proceed similarly for the right side.

→ Get a non-compact \mathbb{R} -tree



Labels and truncation of the infinite Brownian tree

Assign a label to each point of the infinite Brownian tree.

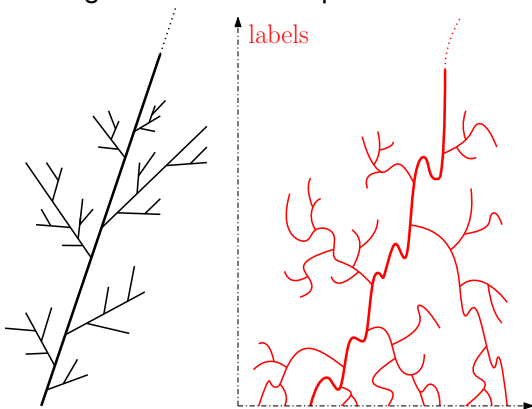


Labels along the spine evolve like a **3-dimensional Bessel process** (started from 0)

For each subtree \mathcal{T}_e , labels on this subtree are given by **Brownian motion indexed by \mathcal{T}_e** (started from the label of the point of the spine where \mathcal{T}_e is grafted)

Labels and truncation of the infinite Brownian tree

Assign a label to each point of the infinite Brownian tree.



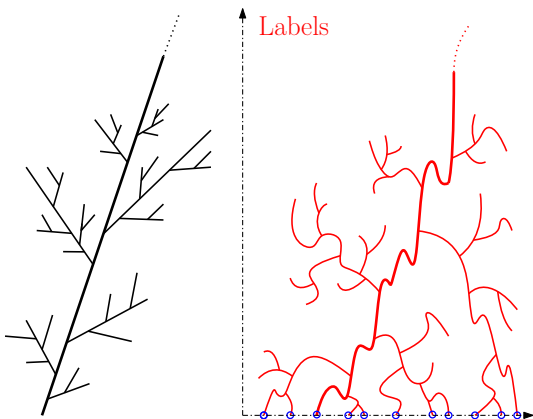
Labels along the spine evolve like a **3-dimensional Bessel process** (started from 0)

For each subtree \mathcal{T}_e , labels on this subtree are given by **Brownian motion indexed by \mathcal{T}_e** (started from the label of the point of the spine where \mathcal{T}_e is grafted)

KEY POINT: Subtrees are **truncated** at points where the label vanishes (so that all labels remain nonnegative) — of course after this truncation, the subtrees are no longer Brownian trees.

The construction of non-compact models (LG-Riera)

The preceding model of a labeled tree allows us to construct the three non-compact models of Brownian geometry.



Can define a quantity Z measuring the number of points with zero label.

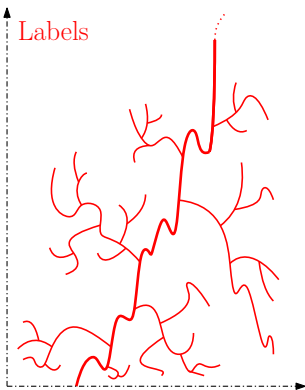
By imitating the construction of the Brownian disk, one gets

- The **Brownian plane** under the conditioning $Z = 0$
- The **infinite Brownian disk** with perimeter a under the conditioning $Z = a$
- The **Brownian half-plane** under $Z = \infty$

In fact in the third case, no conditioning is needed ($Z = \infty$ a.s. in the unconditioned model!)

The case of the Brownian plane

The conditioning $Z = 0$ means that labels do not vanish on any subtree branching off the spine.



Under this conditioning:

- Labels on the spine evolve like a 9-dimensional Bessel process
- The subtrees are Brownian trees equipped with Brownian labels conditioned to have only positive labels

In the Brownian plane, labels correspond to distances from the distinguished point x_* which is the bottom of the spine.

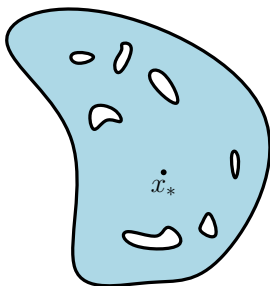
(Similarly, in the construction of the infinite Brownian disk or of the Brownian half-plane, labels correspond to distances from the boundary)

Hulls in the Brownian plane

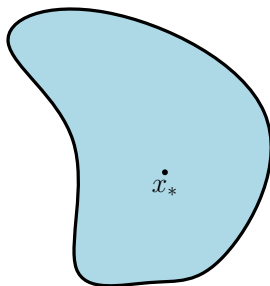
$B(r)$ ball of radius r centered at the distinguished point x_* in the Brownian plane \mathcal{P}

Then $\mathcal{P} \setminus B(r)$ is not connected, but has a **unique unbounded component**: the **hull** $B^\bullet(r)$ is the complement of this unbounded component

(informally, $B^\bullet(r)$ is obtained by filling in the bounded holes in $B(r)$)



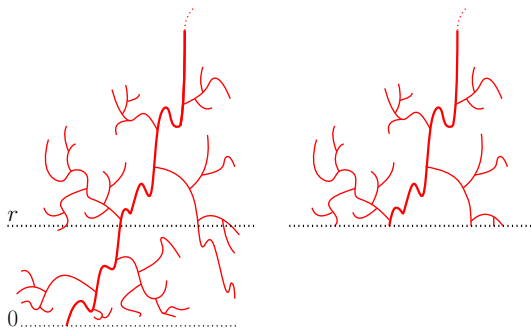
Ball $B(r)$



Hull $B^\bullet(r)$

Complement of hulls in the Brownian plane

Recall: $B^\bullet(r)$ is the hull of radius r in the Brownian plane \mathcal{P}

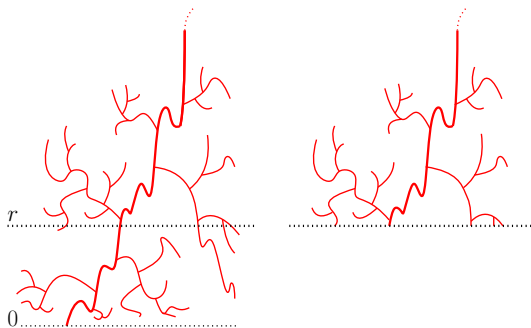


In the infinite tree picture, the complement of $B^\bullet(r)$ corresponds to:

- Keeping the part of the spine **above the last point** with label r on the spine
- Keeping the subtrees branching off this part of the spine, but **truncating** them at level r

Complement of hulls in the Brownian plane

Recall: $B^\bullet(r)$ is the hull of radius r in the Brownian plane \mathcal{P}



In the infinite tree picture, the complement of $B^\bullet(r)$ corresponds to:

- Keeping the part of the spine **above the last point** with label r on the spine
- Keeping the subtrees branching off this part of the spine, but **truncating** them at level r

This resembles the spine representation of the infinite Brownian disk.

Spatial Markov property in the Brownian plane

Recall:

- \mathcal{P} is the Brownian plane
- $B^\bullet(r)$ is the hull of radius r ($\mathcal{P} \setminus B^\bullet(r)$ is the unbounded connected component of $\mathcal{P} \setminus B(r)$)

Equip both $B^\bullet(r)$ and $\mathcal{P} \setminus B^\bullet(r)$ with their intrinsic metrics.

One can define a **boundary size** $|\partial B^\bullet(r)|$ as the limit of ε^{-2} times the volume of the ε -tubular neighborhood of $\partial B^\bullet(r)$.

Theorem (LG-Riera)

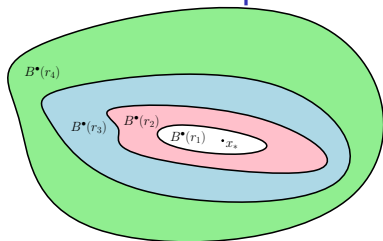
*Conditionally on $|\partial B^\bullet(r)|$, the hull $B^\bullet(r)$ and its complement $\mathcal{P} \setminus B^\bullet(r)$ are independent, and moreover (the closure of) $\mathcal{P} \setminus B^\bullet(r)$ is an **infinite Brownian disk** with perimeter $|\partial B^\bullet(r)|$.*

Isoperimetric inequalities in the Brownian plane

Let $0 < r_1 < r_2 < r_3 < \dots$.

Then the annuli $B^\bullet(r_2) - B^\bullet(r_1)$, $B^\bullet(r_3) - B^\bullet(r_2)$, $B^\bullet(r_3) - B^\bullet(r_2), \dots$ are independent conditionally on their boundary sizes.

—→ Key ingredient for next theorem.

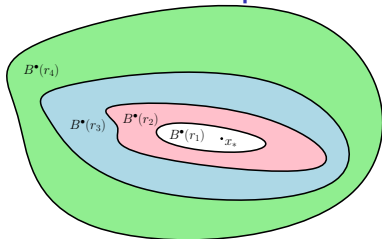


Isoperimetric inequalities in the Brownian plane

Let $0 < r_1 < r_2 < r_3 < \dots$.

Then the annuli $B^\bullet(r_2) - B^\bullet(r_1)$, $B^\bullet(r_3) - B^\bullet(r_2)$, $B^\bullet(r_3) - B^\bullet(r_2), \dots$ are independent conditionally on their boundary sizes.

→ Key ingredient for next theorem.



Let \mathcal{K} be the collection of all (closures of) Jordan domains containing x_* in the Brownian plane. (A Jordan domain D is the interior of a simple loop, $|\partial D|$ is the length of this loop and $|D|$ is the volume of D)

Theorem (Riera)

For any nondecreasing function $f : [0, \infty) \rightarrow (0, \infty)$, we have

$$\inf_{D \in \mathcal{K}} \frac{|\partial D|}{|D|^{1/4}} f(|\log |D||) > 0 \text{ or } = 0 \text{ a.s.}$$

according as $\sum_{n \in \mathbb{N}} \frac{1}{f(n)^2} < \infty$ or $= \infty$.

Thank you for your attention