# Special surfaces in special cubic fourfolds Emanuele Macrì (joint work with Arend Bayer, Aaron Bertram, Alexander Perry)

In this talk, I reported on work in progress on a possible characterization of Hassett

divisors on the moduli space of cubic fourfolds by the property of containing special surfaces. I sketched the construction of such special surfaces for infinitely many divisors and the relation with the work of Russo and Staglianò on rationality of such cubics in low discriminant.

## 1. The Main Theorem

Let  $Y \subset \mathbb{P}^5$  denote a complex smooth cubic fourfold and let  $h := [\mathcal{O}_Y(1)]$  be the class of a hyperplane section. By following [7], we say that Y is special of discriminant d, and use the notation  $Y \in \mathcal{C}_d$ , if there exists a surface  $\Sigma \subset Y$  not homologous to a complete intersection such that the determinant of the intersection matrix

$$\begin{pmatrix} h^2 & h.\Sigma\\ h.\Sigma & \Sigma^2 \end{pmatrix}$$

is equal to d. The locus  $C_d$  is non-empty if and only if  $d \equiv 0, 2 \pmod{6}$  and d > 6; moreover, in such a case,  $C_d$  is an irreducible divisor in the moduli space of cubic fourfolds, which can also be described purely in terms of Hodge theory and periods (by the Global Torelli Theorem [17] and the surjectivity of the period map [10, 13]; we refer to the book in progress [8] for the general theory of cubic fourfolds).

The main result gives an actual surface defining the divisor  $\mathcal{C}_d$ , for special values of d.

**Theorem 1.** Let  $a \ge 1$  be an integer and let  $d := 6a^2 + 6a + 2$ . Let Y be a general cubic fourfold in  $\mathcal{C}_d$ . Then there exists a surface  $\Sigma \subset Y$  such that

- deg( $\Sigma$ ) :=  $h.\Sigma = 1 + \frac{3}{2}a(a+1)$  and  $\Sigma^2 = \frac{d + \text{deg}(\Sigma)^2}{3}$ ;  $H^*(Y, \mathfrak{I}_{\Sigma}(a-j)) = 0$ , for all j = 0, 1, 2.

For discriminant d as in Theorem 1, by [1, 2] there is a polarized K3 surface S of degree d associated to each cubic fourfold in  $\mathcal{C}_d$ . To be precise the surface  $\Sigma$ is not unique but it is a family of surfaces in Y, parameterized by the K3 surface S. Moreover, if the cubic fourfold deforms in the divisor  $\mathcal{C}_d$ , the K3 surface S and the family of surfaces  $\Sigma$  deform along as well.

**Example 2.** Let  $\Sigma$  be the surface in Theorem 1.

(1) Let a = 1, and so d = 14. Then the surface  $\Sigma$  is a smooth quartic scroll, whose existence was observed in [5, 6, 16]; explicitly, in the general case, this is  $\mathbb{P}^1 \times \mathbb{P}^1$  embedded in  $\mathbb{P}^5$  by the linear system  $|\mathcal{O}(1,2)|$ .

(2) Let a = 2, and so d = 38. Then the surface  $\Sigma$  is a smooth "generalized" Coble surface, whose existence was observed in [14]; explicitly, this is the blow-up of  $\mathbb{P}^2$  in 10 general points embedded in  $\mathbb{P}^5$  by the linear system  $|10L - 3(E_1 + \ldots +$  $E_{10})|.$ 

A geometric description for the surfaces  $\Sigma$  is not known when  $a \geq 3$ . In particular, we currently do not know whether the surface is smooth or even integral. If it is smooth, all numerical invariants can be computed; in particular, it will not be rational for any  $a \geq 3$ . On the positive side, the construction does conjecturally generalize to any  $d \equiv 2 \pmod{6}$ . In particular, it works in general for small discriminant (e.g.,  $d \leq 44$ ) and recovers well known surfaces (e.g., the ones in [14]). Moreover, it does provide as well many rational morphisms from the cubic fourfold, which can be described and studied by using the associated K3 surface S and [4]. For example, in the case a = 2, this recovers completely the picture described in [15].

The key insight in our construction comes from derived categories; in particular, the construction of  $\Sigma$  arises from understanding the *Kuznetsov component* Ku(Y) of Y ([9]) and moduli spaces therein ([3, 2]). For d as in Theorem 1, the K3 surface S associated to Y has indeed the property that Ku(Y)  $\cong$  D<sup>b</sup>(S) and the surface  $\Sigma$  arises from a Brill–Noether locus in a special moduli space of stable objects in Ku(Y). The second property in the statement of the theorem can in fact be rephrased by saying that the ideal sheaf  $\mathcal{I}_{\Sigma}(a)$  belongs to Ku(Y).

In what follows, we will give an outline of the construction of  $\Sigma$  in Section 2 and how to induce rational morphisms from Y in Section 3.

### 2. K3 CATEGORIES AND BRILL-NOETHER LOCI

Let Y be a cubic fourfold and let  $D^{b}(Y)$  denote the bounded derived category of coherent sheaves on Y. The Kuznetsov component Ku(Y) of Y is defined as the right orthogonal

$$\operatorname{Ku}(Y) := \langle \mathcal{O}_Y, \mathcal{O}_Y(1), \mathcal{O}_Y(2) \rangle^{\perp} \subset \operatorname{D^b}(Y).$$

We denote by  $i_*$  the inclusion functor  $\operatorname{Ku}(Y) \to \operatorname{D^b}(Y)$  and by  $i^*$  its left adjoint  $\operatorname{D^b}(Y) \to \operatorname{Ku}(Y)$ .

The basic properties of the Kuznetsov component are the following.

- Ku(Y) is a K3 category, i.e., it is smooth, proper triangulated category over  $\mathbb{C}$ , with Serre functor given by [2], the shift by 2 functor ([9]).
- There is a cohomology lattice (H(Ku(Y), ℤ), (−, −)) naturally associated to Ku(Y), given by topological K-theory

$$H(\mathrm{Ku}(Y),\mathbb{Z}) := K_{\mathrm{top}}(\mathrm{Ku}(Y)) := \langle [\mathcal{O}_Y], [\mathcal{O}_Y(1)], [\mathcal{O}_Y(2)] \rangle^{\perp} \subset K_{\mathrm{top}}(Y),$$

where (-, -) denotes the Mukai pairing. It has a Hodge structure of weight 2, given by Hochschild homology, and the Mukai vector gives a morphism  $K(\operatorname{Ku}(Y)) \to H_{\operatorname{alg}}(\operatorname{Ku}(Y), \mathbb{Z})$  ([1]).

• The classes

 $\lambda_1 := i^*[\mathcal{O}_{\text{line}}(1)] \qquad \lambda_2 := i^*[\mathcal{O}_{\text{line}}(2)]$ 

define a sublattice  $A_2 := \langle \lambda_1, \lambda_2 \rangle \subset H_{alg}(Ku(Y), \mathbb{Z})$  ([7, 1]).

- There is a "canonical" (orbit of) stability condition  $\sigma_0$  which deforms over all cubics; we denote by  $\operatorname{Stab}(\operatorname{Ku}(Y))$  the connected component of the space of Bridgeland stability conditions containing  $\sigma_0$  ([3]).
- Given a Mukai vector  $v \in H_{\text{alg}}(\text{Ku}(Y), \mathbb{Z})$  and  $\sigma \in \text{Stab}(\text{Ku}(Y))$ , the moduli space  $M_{\sigma}(v)$  behaves "as nice as" a moduli space of semistable sheaves on a K3 surface. In particular, if v is primitive and  $\sigma$  generic with respect to v, then  $M_{\sigma}(v) \neq \emptyset$  if and only if  $v^2 + 2 \geq 0$ ; in such a case,  $M_{\sigma}(v)$  is a projective irreducible holomorphic symplectic manifold of dimension  $v^2 + 2$ , deformation equivalent to a Hilbert scheme of points on a K3 surface ([2]).
- If Y does not contain a plane, then for all  $y \in Y$ , the projection of the skyscraper sheaf  $i^*k(y)$  is  $\sigma_0$ -stable of Mukai vector  $\lambda_2 \lambda_1$ ; in particular, we obtain an embedding  $Y \hookrightarrow M_{\sigma_0}(\lambda_2 \lambda_1)$  ([12]; the geometric construction is in [11]).

The last property is the starting point for our construction. Indeed, let us fix  $v := \lambda_2 - \lambda_1$ . If we could find another Mukai vector  $u \in H_{\text{alg}}(\text{Ku}(Y), \mathbb{Z})$  such that  $(u, v) = -1, u^2 + 2 \ge 0$ , and the slope of u with respect to  $\sigma_0$  is larger than the slope of v, then for  $F \in M_{\sigma_0}(u)$ , the Brill–Noether locus

 $BN_F := \left\{ E \in M_{\sigma_0}(v) : \min(\hom(E, F), \operatorname{ext}^1(E, F)) \ge 1 \right\} \subset M_{\sigma_0}(v)$ 

has expected codimension 2; in particular, the intersection  $Y \cap BN_F$  has expected codimension 2 as well, and so it could define a surface  $\Sigma_F$  (parameterized by  $M_{\sigma_0}(u)$ ).

To make this argument work, we need to prove the existence of such u and study the non-triviality of BN<sub>F</sub> and its intersection with Y. The existence of u is a straightforward computation: u exists if and only if  $d \equiv 2 \pmod{6}$ .

This Brill–Noether locus can be studied directly in low discriminant; in general, we have to assume that  $d = 6a^2 + 6a + 2$ ,  $a \ge 1$ . In such a case, we can choose usuch that  $u^2 = 0$ . Let  $S := M_{\sigma_0}(u)$ . Then (up to in case slightly deform  $\sigma_0$ ) S is a smooth projective K3 surface and the universal family  $\mathcal{U}$  (which exists) gives a Fourier–Mukai equivalence

$$\Phi_{\mathcal{U}} \colon \mathrm{D}^{\mathrm{b}}(S) \xrightarrow{\cong} \mathrm{Ku}(Y).$$

**Lemma 3.** Let  $a \geq 2$ . Then, for all  $E \in M_{\sigma_0}(v)$ , we have  $\Phi_{\mathcal{U}}^{-1}(E) \cong \mathfrak{I}_{\Gamma}$ , where  $\Gamma \subset S$  is a 0-dimensional closed subscheme of length 4.

In particular, by Lemma 3, we can identify  $M_{\sigma_0}(v)$  with the Hilbert scheme  $S^{[4]}$  (in the case a = 1 this is not true; this case has to be studied separately). We can use this to show the following.

**Lemma 4.** Let  $F \in M_{\sigma_0}(u)$  general. Then (up to shift and taking derived dual) we have

 $i_*F \cong \mathfrak{I}_{\Sigma_F}(a),$ 

where  $\Sigma_F \subset Y$  is a surface.

Theorem 1 follows then directly from Lemma 4.

#### 3. Morphisms

We keep the notation as in the previous section, with  $v = \lambda_2 - \lambda_1$ , u, and  $F \in M_{\sigma_0}(u)$ . Then in "optimal situations" by taking extensions with F gives a well-defined rational map

$$g = g_F \colon M_{\sigma_0}(v) \dashrightarrow M_{\sigma_0}(v-u)$$

which induces a diagram

$$\begin{array}{cccc} \operatorname{Bl}_{\Sigma_F} Y \longrightarrow \operatorname{Bl}_{\operatorname{BN}_F} M_{\sigma_0}(v) \\ & & \downarrow & & \\ & & \downarrow & & \\ & Y \longrightarrow & M_{\sigma_0}(v) - \stackrel{g}{-} \twoheadrightarrow M_{\sigma_0}(v-u) \end{array}$$

and so a closed embedding  $f \colon \operatorname{Bl}_{\Sigma_F} Y \hookrightarrow M_{\sigma_0}(v-u)$ .

If this is the case, and we let  $\Delta$  denote the exceptional divisor of  $\sigma$ , we have the following result.

**Lemma 5.** For a divisor classe  $D \in NS(M_{\sigma_0}(v-u)) \cong (v-u)^{\perp} \subset H_{alg}(Ku(Y), \mathbb{Z})$ , we have

$$f^*D = -\frac{(D + (D, u) u, \lambda_1 + \lambda_2)}{2} \sigma^* h + (D, u) \Delta.$$

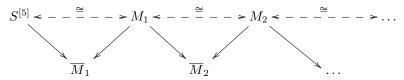
If  $d = 6a^2 + 6a + 2$  as in Theorem 1, then g is indeed well-defined: F corresponds to a skyscraper sheaf at a point  $p \in S$ , and the morphism g is nothing but the map

$$S^{[4]} \dashrightarrow S^{[5]}, \qquad \Gamma \mapsto p + \Gamma.$$

Moreover, by fixing p, the morphism f gives a closed embedding  $\operatorname{Bl}_{\Sigma}Y \hookrightarrow S^{[5]}$ .

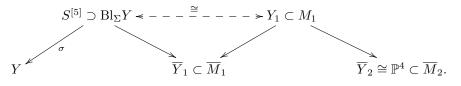
To get rational maps from Y, we can study morphisms from  $S^{[5]}$  and these can be studied by simply looking at the base locus decomposition of the movable cone  $Mov(S^{[5]})$ , which has been completely described in [4].

In the example when a = 2 (and so, d = 38), we have the following diagram:



where the leftmost diagram is a Mukai flop at a  $\mathbb{P}^3$ -bundle over the Fano variety of lines F(Y) of Y, and the next diagram is a Mukai flop at a  $\mathbb{P}^2$ -bundle over the product  $S \times F(Y)$ .

By taking the restriction of the above sequence of morphisms to Y, we find exactly the "trisecant flop" description in [15]



The divisors associated to the two birational maps from Y to  $\overline{Y}_1$ , respectively  $\overline{Y}_2$ , correspond, by using Lemma 5, to the linear systems  $|\mathcal{I}_{\Sigma}(3)|$ , respectively  $|\mathcal{I}_{\Sigma}^2(5)|$  on Y. Concretely, trisecant lines and 5-secant conics to  $\Sigma$  in Y.

In [15] this was used to show the rationality of Y in  $C_{38}$ . Conjecturally ([9]) all cubic fourfolds in  $C_d$ , where  $d = 6a^2 + 6a + 2$ , should be rational. The corresponding picture already in the case a = 3 (d = 74) is not understood:  $S^{[5]}$  has only one interesting morphism, which corresponds to the linear system  $|\mathcal{I}_{\Sigma}^3(10)|$  on Y, and the rationality of Y in  $C_{74}$  is not known.

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